

# High Common-Mode Voltage, Programmable Gain Difference Amplifier

**AD628** 

### **FEATURES**

High common-mode input voltage range  $\pm 120$  V at V<sub>S</sub> =  $\pm 15$  V Gain range 0.1 to 100 Operating temperature range:  $-40^{\circ}$ C to  $\pm 85^{\circ}$ C Supply voltage range

Dual supply: ±2.25 V to ±18 V Single supply: 4.5 V to 36 V Excellent ac and dc performance

Offset temperature stability RTI: 10  $\mu$ V/°C max

Offset: ±1.5 V mV max

CMRR RTI: 75 dB min, dc to 500 Hz, G = +1

#### **APPLICATIONS**

High voltage current shunt sensing
Programmable logic controllers
Analog input front end signal conditioning
+5 V, +10 V, ±5 V, ±10 V, and 4 to 20 mA
Isolation
Sensor signal conditioning
Power supply monitoring
Electrohydraulic control
Motor control

#### **GENERAL DESCRIPTION**

The AD628 is a precision difference amplifier that combines excellent dc performance with high common-mode rejection over a wide range of frequencies. When used to scale high voltages, it allows simple conversion of standard control voltages or currents for use with single-supply ADCs. A wideband feedback loop minimizes distortion effects due to capacitor charging of  $\Sigma\text{-}\Delta$  ADCs.

A reference pin (V<sub>REF</sub>) provides a dc offset for converting bipolar to single-sided signals. The AD628 converts +5 V, +10 V,  $\pm$ 5 V,  $\pm$ 10 V, and 4 to 20 mA input signals to a single-ended output within the input range of single-supply ADCs.

The AD628 has an input common-mode and differential mode operating range of  $\pm 120$  V. The high common-mode input impedance makes the device well-suited for high voltage measurements across a shunt resistor. The buffer amplifier's inverting input is available for making a remote Kelvin connection.

#### **FUNCTIONAL BLOCK DIAGRAM**

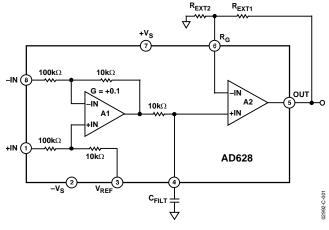


Figure 1.

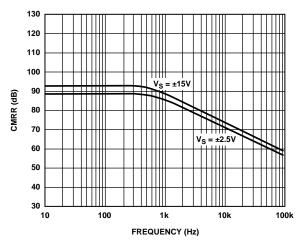


Figure 2. CMRR vs. Frequency of the AD628

A precision  $10~k\Omega$  resistor connected to an external pin is provided for either a low-pass filter or to attenuate large differential input signals. A single capacitor implements a low-pass filter. The AD628 operates from single and dual supplies and is available in an 8-lead SOIC or 8-lead MSOP package. It operates over the standard industrial temperature range of  $-40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$ .

Rev. E

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# **AD628**

# **TABLE OF CONTENTS**

Specifications
Absolute Maximum Ratings
ESD Caution
Pin Configuration and Function Descriptions
Typical Performance Characteristics
Test Circuits
Theory of Operation
Applications
Gain Adjustment
Input Voltage Range
Voltage Level Conversion
Current Loop Receiver
Monitoring Battery Voltages
Filter Capacitor Values
Kelvin Connection
Outline Dimensions
Ordering Guide

### **REVISION HISTORY**

5/05—Rev. D to Rev. E
Changes to Table 1
Changes to Table 25
Changes to Figure 33
3/05—Rev. C to Rev. D
Updated Format
Changes to Table 1
Changes to Table 25
4/04—Rev. B to Rev. C
Updated FormatUniversal
Changes to Specifications
Changes to Absolute Maximum Ratings
Changes to Figure 37
Changes to Figure 2613
Changes to Figure 2713
Changes to Theory of Operation14
Changes to Figure 2914
Changes to Table 5
Changes to Gain Adjustment Section
Added the Input Voltage Range Section15
Added Figure 30
Added Figure 31
Changes to Voltage Level Conversion Section16
Changes to Figure 32
Changes to Table 6
Changes to Figure 33 and Figure 3417
Changes to Figure 35
Changes to Kelvin Connection Section
6/03—Rev. A to Rev. B
Changes to General Description1
Changes to Specifications
Changes to Ordering Guide
Changes to TPCs 4, 5, and 6 5
Changes to TPC 96
Updated Outline Dimensions14
1/02 B 04 B
1/03—Rev. 0 to Rev. A
Change to Ordering Guide4

11/02—Rev. 0: Initial Version

# **SPECIFICATIONS**

 $T_A = 25^{\circ}C$ ,  $V_S = \pm 15$  V,  $R_L = 2$  k $\Omega$ ,  $R_{EXT1} = 10$  k $\Omega$ ,  $R_{EXT2} = \infty$ ,  $V_{REF} = 0$ , unless otherwise noted.

Table 1.

			AD628AR		AD628ARM				
Parameter	Conditions	Min	Тур	Max	Min	Тур	Max	Unit	
DIFFERENTIAL AMP + OUTPUT AMP									
Gain Equation	$G = +0.1(1 + R_{EXT1}/R_{EXT2})$							V/V	
Gain Range	See Figure 29	0.1 <sup>1</sup>		100	0.11		100	V/V	
Offset Voltage	$V_{CM} = 0 \text{ V}$ ; RTI of input pins <sup>2</sup> ; Output amp $G = +1$	-1.5		+1.5	-1.5		+1.5	mV	
vs. Temperature			4	8		4	8	μV/°C	
CMRR <sup>3</sup>	RTI of input pins; G = +0.1 to $+100$	75			75			dB	
	500 Hz	75			75			dB	
Minimum CMRR Over Temperature	-40°C to +85°C	70			70			dB	
vs. Temperature			1	4		1	4	(μV/V)/°C	
PSRR (RTI)	$V_S = \pm 10 \text{ V to } \pm 18 \text{ V}$	77	94		77	94		dB	
Input Voltage Range									
Common Mode		-120		+120	-120		+120	V	
Differential		-120		+120	-120		+120	V	
Dynamic Response									
Small Signal BW –3 dB	G = +0.1		600			600		kHz	
Full Power Bandwidth			5			5		kHz	
Settling Time	G = +0.1, to 0.01%, 100 V step			40			40	μs	
Slew Rate			0.3			0.3		V/µs	
Noise (RTI)									
Spectral Density	1 kHz		300			300		nV/√Hz	
	0.1 Hz to 10 Hz		15			15		μV p-p	
DIFFERENTIAL AMP									
Gain			0.1			0.1		V/V	
Error		-0.1	+0.01	+0.1	-0.1	+0.01	+0.1	%	
vs. Temperature				5			5	ppm/°C	
Nonlinearity				5			5	ppm	
vs. Temperature			3	10		3	10	ppm	
Offset Voltage	RTI of input pins	-1.5		+1.5	-1.5		+1.5	mV	
vs. Temperature				8			8	μV/°C	
Input Impedance									
Differential			220			220		kΩ	
Common Mode			55			55		kΩ	
CMRR <sup>4</sup>	RTI of input pins; G = +0.1 to +100	75			75			dB	
	500 Hz	75			75			dB	
Minimum CMRR Over Temperature	−40°C to +85°C	70			70			dB	
vs. Temperature			1	4		1	4	(μV/V)/°C	
Output Resistance			10			10		kΩ	
Error		-0.1		+0.1	-0.1		+0.1	%	

# **AD628**

			AD628AR			AD628ARM		
Parameter	Conditions	Min	Тур	Max	Min	Тур	Max	Unit
OUTPUT AMPLIFIER								
Gain Equation	$G = (1 + R_{EXT1}/R_{EXT2})$							V/V
Nonlinearity	$G = +1, V_{OUT} = \pm 10 V$			0.5			0.5	ppm
Offset Voltage	RTI of output amp	-0.15		+0.15	-0.15		+0.15	mV
vs. Temperature				0.6			0.6	μV/°C
Output Voltage Swing	$R_L = 10 \text{ k}\Omega$	-14.2		+14.1	-14.2		+14.1	V
	$R_L = 2 k\Omega$	-13.8		+13.6	-13.8		+13.6	V
Bias Current			1.5	3		1.5	3	nA
Offset Current			0.2	0.5		0.2	0.5	nA
CMRR	$V_{CM} = \pm 13 \text{ V}$	130			130			dB
Open-Loop Gain	$V_{OUT} = \pm 13 \text{ V}$	130			130			dB
POWER SUPPLY								
Operating Range		±2.25		±18	±2.25		±18	V
Quiescent Current				1.6			1.6	mA
TEMPERATURE RANGE		-40		+85	-40		+85	°C

<sup>&</sup>lt;sup>1</sup> To use a lower gain, see the Gain Adjustment section. <sup>2</sup> The addition of the difference amp's and output amp's offset voltage does not exceed this specification. <sup>3</sup> Error due to common mode as seen at the output:  $V_{OUT} = [\frac{(0.1)(V_{CM})}{\frac{75}{10^{20}}}] \times [Output \ Amplifier \ Gain]$ 

 $<sup>^4</sup>$  Error due to common mode as seen at the output of A1:  $V_{OUT}$   $AI = [\frac{(0.1)(V_{CM})}{10^{\frac{75}{20}}}]$ 

 $T_{A}=25^{\circ}C\text{, }V_{S}=5\text{ V, }R_{L}=2\text{ k}\Omega\text{, }R_{EXT1}=10\text{ k}\Omega\text{, }R_{EXT2}=\infty\text{, }V_{REF}=2.5\text{, unless otherwise noted.}$ 

Table 2.

	AD628AR			AD628ARM			T	
Parameter	Conditions	Min	Тур	Max	Min	Тур	Max	Unit
DIFFERENTIAL AMP + OUTPUT AMP			·					
Gain Equation	$G = +0.1(1 + R_{EXT1}/R_{EXT2})$							V/V
Gain Range	See Figure 29	0.1 <sup>1</sup>		100	0.1 <sup>1</sup>		100	V/V
Offset Voltage	$V_{CM} = 2.25 \text{ V}$ ; RTI of input pins <sup>2</sup> ; Output Amp G = +1	-3.0		+3.0	-3.0		+3.0	mV
vs. Temperature			6	15		6	15	μV/°C
CMRR <sup>3</sup>	RTI of input pins; G = +0.1 to +100	75 75			75 75			dB dB
Minimum CMRR Over Temperature	-40°C to +85°C	70			70			dB
vs. Temperature	10 0 10 10 0	, ,	1	4	, 0	1	4	(μV/V)/°C
PSRR (RTI)	$V_S = 4.5 \text{ V to } 10 \text{ V}$	77	94	•	77	94	•	dB
Input Voltage Range		,,			' '			
Common Mode <sup>4</sup>		-12		+17	-12		+17	V
Differential		-15		+15	-15		+15	v
Dynamic Response		13		113	'3		113	*
Small Signal BW –3 dB	G = +0.1		440			440		kHz
Full Power Bandwidth	G = +0.1		30			30		kHz
Settling Time	G = +0.1, to 0.01%, 30 V step		15			15		μs
Slew Rate	d = +0.1, to 0.0170, 50 v step		0.3			0.3		ν/μs
Noise (RTI)			0.5			0.5		ν/μ3
Spectral Density	1 kHz		350			350		nV/√Hz
Spectral Delisity	0.1 Hz to 10 Hz		15			15		μV p-p
DIFFERENTIAL AMP	0.1112 to 10112		13			13		μνρ-ρ
Gain			0.1			0.1		V/V
Error		-0.1	+0.01	+0.1	-0.1	+0.01	+0.1	%
Nonlinearity		-0.1	±0.01	3	-0.1	+0.01	3	ppm
vs. Temperature			3	10		3	10	1
Offset Voltage	RTI of input pins	-2.5	3	+2.5	-2.5	3	+2.5	ppm mV
vs. Temperature	Kiroi iiiput piiis	-2.5		+2.5 10	-2.5		10	μV/°C
Input Impedance				10			10	μν/ C
Differential			220			220		kΩ
Common Mode			55			55		kΩ
CMRR <sup>5</sup>	DTI of input pipe. C 10.1 to 1100	75	33		75	33		dB
CIVIRN	RTI of input pins; G = +0.1 to +100 500 Hz	75 75			75 75			dВ
Minimum CMRR Over Temperature		70			70			dB
vs. Temperature	-40 C to +83 C	70	1	4	/0	1	4	(μV/V)/°C
Output Resistance			10	4		10	4	(μν/ν)/ C
Error		-0.1	10	+0.1	-0.1	10	+0.1	%
OUTPUT AMPLIFIER		-0.1		+0.1	-0.1		+0.1	70
Gain Equation	$G = (1 + R_{EXT1}/R_{EXT2})$							V/V
Nonlinearity	$G = +1$ , $V_{OUT} = 1 \text{ V to } 4 \text{ V}$			0.5			0.5	
Output Offset Voltage	RTI of output amp	-0.15		0.5	-0.15		0.5	ppm mV
	KIT OF Output amp	-0.13		0.13	-0.13		0.13	
vs. Temperature	D = 10 kO	0.9			0.0			μV/°C
Output Voltage Swing	$R_{L} = 10 \text{ k}\Omega$ $R_{L} = 2 \text{ k}\Omega$			4.1 4	0.9		4.1 4	V
Piac Current	$U\Gamma = 7 \text{ K77}$	1	1 F	4	1	1 F	4	
Bias Current			1.5	3		1.5	3	nA
Offset Current	$V_{CM} = 1 V \text{ to } 4 V$	120	0.2	0.5	120	0.2	0.5	nA de
CMRR		130			130			dB
Open-Loop Gain	$V_{OUT} = 1 V \text{ to } 4 V$	130			130			dB

# **AD628**

		AD628AR		AD628ARM				
Parameter	Conditions	Min	Тур	Max	Min	Тур	Max	Unit
POWER SUPPLY								
Operating Range		±2.25		+36	±2.25		+36	V
Quiescent Current				1.6			1.6	mA
TEMPERATURE RANGE		-40		+85	-40		+85	°C

 $<sup>^{\</sup>rm 1}$  To use a lower gain, see the Gain Adjustment section.  $^{\rm 2}$  The addition of the difference amp's and output amp's offset voltage does not exceed this specification.

 $<sup>^3</sup>$  Error due to common mode as seen at the output:  $V_{OUT} = [\frac{(0.1)(V_{CM})}{75}] \times [Output\ Amplifier\ Gain]$ 

<sup>&</sup>lt;sup>4</sup> Greater values of voltage are possible with greater or lesser values of V<sub>REF</sub>.

 $<sup>^{5}</sup>$  Error due to common mode as seen at the output of A1:  $V_{OUT}$   $AI = [\frac{(0.1)(V_{CM})}{10^{\frac{75}{20}}}]$ 

### **ABSOLUTE MAXIMUM RATINGS**

Table 3.

Parameter	Rating
Supply Voltage	±18 V
Internal Power Dissipation	See Figure 3
Input Voltage (Common Mode)	±120 V <sup>1</sup>
Differential Input Voltage	±120 V <sup>1</sup>
Output Short-Circuit Duration	Indefinite
Storage Temperature	−65°C to +125°C
Operating Temperature Range	-40°C to +85°C
Lead Temperature Range (10 sec Soldering)	300°C

 $<sup>^{1}</sup>$  When using  $\pm 12$  V supplies or higher (see the Input Voltage Range section).

Stresses greater than those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

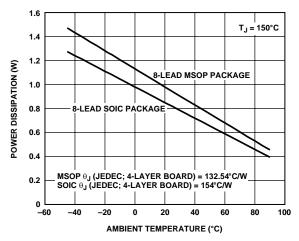


Figure 3. Maximum Power Dissipation vs. Temperature

### **ESD CAUTION**

ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although this product features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.



# PIN CONFIGURATION AND FUNCTION DESCRIPTIONS

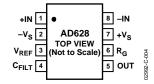


Figure 4. Pin Configuration

**Table 4. Pin Function Descriptions** 

		E
Pin No.	Mnemonic	Descriptions
1	+IN	Noninverting Input
2	-V <sub>S</sub>	Negative Supply Voltage
3	$V_{REF}$	Reference Voltage Input
4	C <sub>FILT</sub>	Filter Capacitor Connection
5	OUT	Amplifier Output
6	R <sub>G</sub>	Output Amplifier Inverting Input
7	+V <sub>S</sub>	Positive Supply Voltage
8	-IN	Inverting Input

### TYPICAL PERFORMANCE CHARACTERISTICS

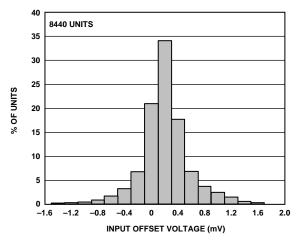


Figure 5. Typical Distribution of Input Offset Voltage,  $V_S = \pm 15$  V, SOIC Package

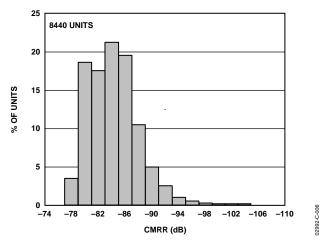


Figure 6. Typical Distribution of Common-Mode Rejection, SOIC Package

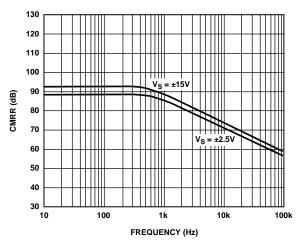


Figure 7. CMRR vs. Frequency

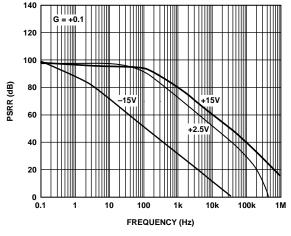


Figure 8. PSRR vs. Frequency, Single and Dual Supplies

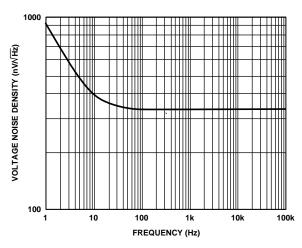


Figure 9. Voltage Noise Spectral Density, RTI,  $V_S = \pm 15 \text{ V}$ 

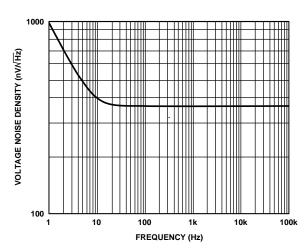


Figure 10. Voltage Noise Spectral Density, RTI,  $V_S = \pm 2.5 \text{ V}$ 

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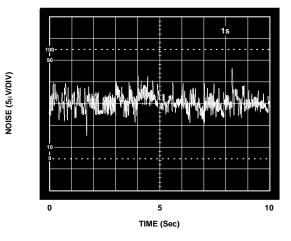


Figure 11. 0.1 Hz to 10 Hz Voltage Noise, RTI

02992-C-011

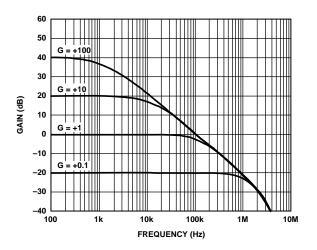


Figure 12. Small Signal Frequency Response,  $V_{OUT} = 200 \text{ mV p-p}, G = +0.1, +1, +10, \text{ and } +100$ 

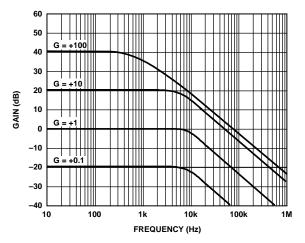


Figure 13. Large Signal Frequency Response,  $V_{OUT} = 20 \text{ V p-p, } G = +0.1, +1, +10, \text{ and } +100$ 

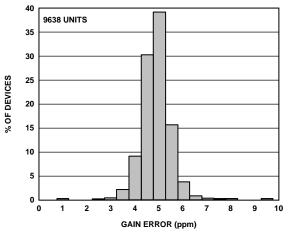


Figure 14. Typical Distribution of +1 Gain Error

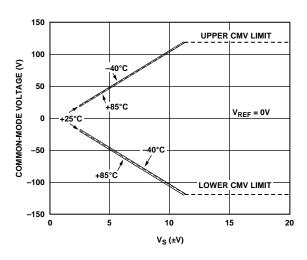


Figure 15. Common-Mode Operating Range vs. Power Supply Voltage for Three Temperatures

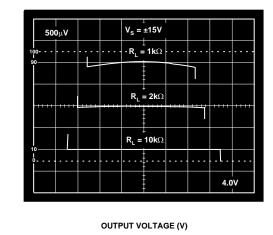


Figure 16. Normalized Gain Error vs.  $V_{OUT}$ ,  $V_S = \pm 15 \text{ V}$ 

2992-C-016

02992-C-014

02992-C-015

OUTPUT ERROR (µV)

OUTPUT VOLTAGE (V) Figure 17. Normalized Gain Error vs.  $V_{OUT}$ ,  $V_S = \pm 2.5 \ V$ 

02992-C-017

02992-C-018

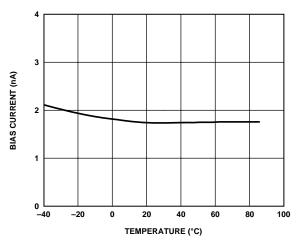


Figure 18. Bias Current vs. Temperature Buffer

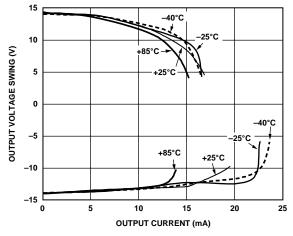


Figure 19. Output Voltage Operating Range vs. Output Current

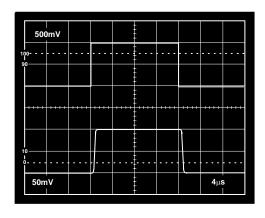


Figure 20. Small Signal Pulse Response,  $R_L = 2 k\Omega$ ,  $C_L = 0 pF$ , Top: Input, Bottom: Output

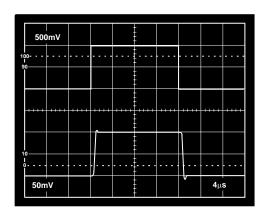


Figure 21. Small Signal Pulse Response,  $R_L = 2 k\Omega$ ,  $C_L = 1000 pF$ , Top: Input, Bottom: Output

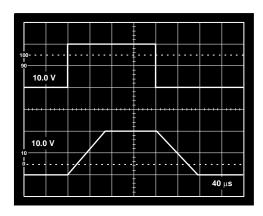
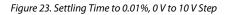


Figure 22. Large Signal Pulse Response,  $R_L = 2 \text{ k}\Omega$ ,  $C_L = 1000 \text{ pF}$ , Top: Input, Bottom: Output

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02992-C-021



02992-C-023

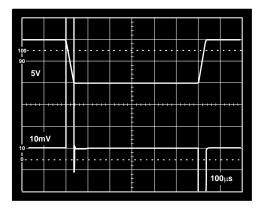


Figure 24. Settling Time to 0.01% 0 V to -10 V Step

# **TEST CIRCUITS**

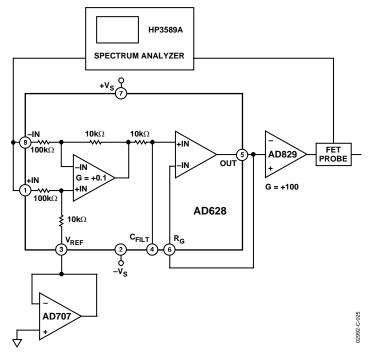
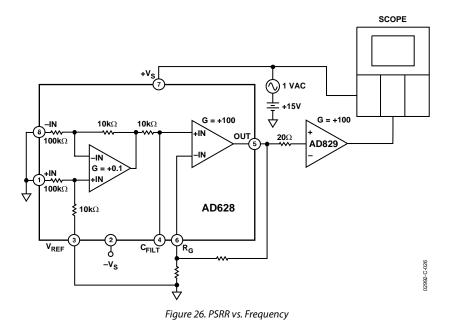


Figure 25. CMRR vs. Frequency



Rev. E | Page 13 of 20

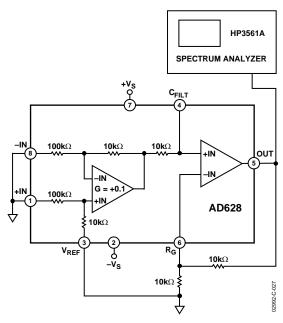


Figure 27. Noise Tests

### THEORY OF OPERATION

The AD628 is a high common-mode voltage difference amplifier, combined with a user-configurable output amplifier (see Figure 28 and Figure 29). Differential mode voltages in excess of 120 V are accurately scaled by a precision 11:1 voltage divider at the input. A reference voltage input is available to the user at Pin 3 (V<sub>REF</sub>). The output common-mode voltage of the difference amplifier is the same as the voltage applied to the reference pin. If the uncommitted amplifier is configured for gain, connecting Pin 3 to one end of the external gain resistor establishes the output common-mode voltage at Pin 5 (OUT).

The output of the difference amplifier is internally connected to a 10 k $\Omega$  resistor trimmed to better than  $\pm 0.1\%$  absolute accuracy. The resistor is connected to the noninverting input of the output amplifier and is accessible to the user at Pin 4 ( $C_{\text{FILT}}$ ). A capacitor may be connected to implement a low-pass filter, a resistor may be connected to further reduce the output voltage, or a clamp circuit may be connected to limit the output swing.

The uncommitted amplifier is a high open-loop gain, low offset, low drift op amp, with its noninverting input connected to the internal 10 k $\Omega$  resistor. Both inputs are accessible to the user.

Careful layout design has resulted in exceptional common-mode rejection at higher frequencies. The inputs are connected to Pin 1 (+IN) and Pin 8 (-IN), which are adjacent to the power pins, Pin 2 ( $-V_s$ ) and Pin 7 ( $+V_s$ ). Because the power pins are at ac ground, input impedance balance and, therefore, common-mode rejection, are preserved at higher frequencies.

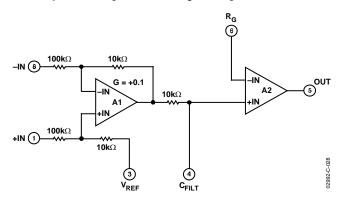


Figure 28. Simplified Schematic

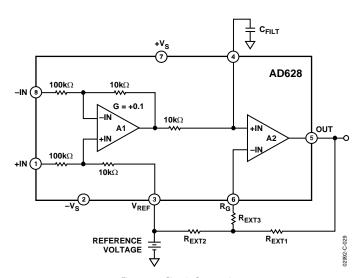


Figure 29. Circuit Connections

### **APPLICATIONS**

#### **GAIN ADJUSTMENT**

The AD628 system gain is provided by an architecture consisting of two amplifiers. The gain of the input stage is fixed at 0.1; the output buffer is user-adjustable as  $G_{A2} = 1 + R_{EXTI}/R_{EXT2}$ . The system gain is then

$$G_{TOTAL} = 0.1 \times \left(1 + \frac{R_{EXTI}}{R_{EXT2}}\right) \tag{1}$$

At a 2 nA maximum, the input bias current of the buffer amplifier is very low and any offset voltage induced at the buffer amplifier by its bias current may be neglected (2 nA  $\times$  10 k $\Omega$  = 20  $\mu V$ ). However, to absolutely minimize bias current effects,  $R_{EXT1}$  and  $R_{EXT2}$  can be selected so that their parallel combination is 10 k $\Omega$ . If practical resistor values force the parallel combination of  $R_{EXT1}$  and  $R_{EXT2}$  below 10 k $\Omega$ , a series resistor ( $R_{EXT3}$ ) can be added to make up for the difference. Table 5 lists several values of gain and corresponding resistor values.

Table 5. Nearest Standard 1% Resistor Values for Various Gains (See Figure 29)

Total Gain (V/V)	A2 Gain (V/V)	R <sub>EXT1</sub> (Ω)	R <sub>EXT2</sub> (Ω)	R <sub>EXT3</sub> (Ω)			
0.1	1	10 k	∞	0			
0.2	2	20 k	20 k	0			
0.25	2.5	25.9 k	18.7 k	0			
0.5	5	49.9 k	12.4 k	0			
1	10	100 k	11 k	0			
2	20	200 k	10.5 k	0			
5	50	499 k	10.2 k	0			
10	100	1 M	10.2 k	0			

To set the system gain to less than 0.1, an attenuator can be created by placing a resistor,  $R_{\text{EXT4}}$ , from Pin 4 ( $C_{\text{FILT}}$ ) to the reference voltage. A divider would be formed by the 10 k $\Omega$  resistor which is in series with the positive input of A2 and  $R_{\text{EXT4}}$ . A2 would be configured for unity gain.

Using a divider and setting A2 to unity gain yields

$$G_{W \, / \, DIVIDER} = 0.1 \times \left(\frac{R_{EXT4}}{10 \; \mathrm{k}\Omega + R_{EXT4}}\right) \times 1$$

#### **INPUT VOLTAGE RANGE**

The common-mode input voltage range is determined by  $V_{\text{REF}}$  and the supply voltage. The relation is expressed by

$$V_{CM_{IJPPER}} \le 11(V_{S+} - 1.2 \text{ V}) - 10 V_{REF}$$
 (2)

$$V_{CM_{LOWER}} \ge 11(V_{S-} + 1.2 \text{ V}) - 10 V_{REF}$$

where  $V_{S+}$  is the positive supply,  $V_{S-}$  is the negative supply, and 1.2 V is the headroom needed for suitable performance. Equation 2 provides a general formula for calculating the common-mode input voltage range. However, the AD628 should be kept within the maximum limits listed in the Specifications (see Table 1) to maintain optimal performance. This is illustrated in Figure 30 where the maximum common-mode input voltage is limited to  $\pm 120$  V. Figure 31 shows the common-mode input voltage bounds for single-supply voltages.

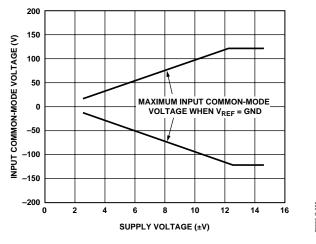


Figure 30. Input Common-Mode Voltage vs. Supply Voltage for Dual Supplies

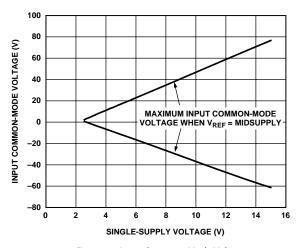


Figure 31. Input Common-Mode Voltage vs. Supply Voltage for Single Supplies

The differential input voltage range is constrained to the linear operation of the internal amplifiers A1 and A2. The voltage applied to the inputs of A1 and A2 should be between  $V_{\text{S}-}+1.2\ V$  and  $V_{\text{S}+}-1.2\ V$ . Similarly, the outputs of A1 and A2 should be kept between  $V_{\text{S}-}+0.9\ V$  and  $V_{\text{S}+}-0.9\ V$ .

#### **VOLTAGE LEVEL CONVERSION**

Industrial signal conditioning and control applications typically require connections between remote sensors or amplifiers and centrally located control modules. Signal conditioners provide output voltages up to  $\pm 10$  V full scale; however, ADCs or microprocessors operating on single 3.3 V to 5 V logic supplies are becoming the norm. Thus, the controller voltages require further reduction in amplitude and reference.

Furthermore, voltage potentials between locations are seldom compatible, and power line peaks and surges can generate destructive energy between utility grids. The AD628 is an ideal solution to both problems. It attenuates otherwise destructive signal voltage peaks and surges by a factor of 10 and shifts the differential input signal to the desired output voltage.

Conversion from voltage-driven or current-loop systems is easily accommodated using the circuit in Figure 32. This shows a circuit for converting inputs of various polarities and amplitudes to the input of a single-supply ADC.

Note that the common-mode output voltage can be adjusted by connecting Pin 3 ( $V_{\text{REF}}$ ) and the lower end of the 10 k $\Omega$  resistor to the desired voltage. The output common-mode voltage will be the same as the reference voltage.

The design of such an application may be done in a few simple steps, which include the following:

- Determine the required gain. For example, if the input voltage must be transformed from  $\pm 10$  V to 0 V to +5 V, the gain is +5/+20 or +0.25.
- Determine if the circuit common-mode voltage must be changed. An AD7715-5 ADC is illustrated for this example. When operating from a 5 V supply, the common-mode voltage of the AD7715 is half the supply or 2.5 V. If the AD628 reference pin and the lower terminal of the 10 k $\Omega$  resistor are connected to a 2.5 V voltage source, the output common-mode voltage will be 2.5 V.

Table 6 shows resistor and reference values for commonly used single-supply converter voltages. R<sub>EXT3</sub> is included as an option. It is used to balance the source impedance into A2, which is described in more detail in the Gain Adjustment section.

Table 6. Nearest 1% Resistor Values for Voltage Level Conversion Applications

Input Voltage (V)	ADC Supply Voltage (V)	Desired Output Voltage (V)	V <sub>REF</sub>	R <sub>EXT1</sub> (kΩ)	R <sub>EXT3</sub> (kΩ)
±10	5	2.5	2.5	15.0	4.02
±5	5	2.5	2.5	39.7	2.00
+10	5	2.5	2.5	39.7	2.00
+5	5	2.5	2.5	89.8	1.00
±10	3	1.25	1.25	2.49	7.96
±5	3	1.25	1.25	15.0	4.02
+10	3	1.25	1.25	15.0	4.02
+5	3	1.25	1.25	39.7	2.00

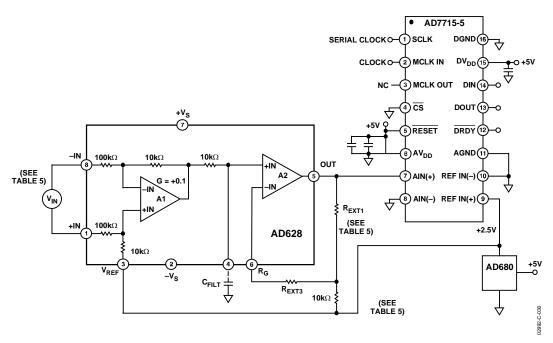


Figure 32. Level Shifter

### **CURRENT LOOP RECEIVER**

Analog data transmitted on a 4 to 20 mA current loop can be detected with the receiver shown in Figure 33. The AD628 is an ideal choice for such a function because the current loop must be driven with a compliance voltage sufficient to stabilize the loop, and the resultant common-mode voltage often exceeds commonly used supply voltages. Note that with large shunt values a resistance of equal value must be inserted in series with the inverting input to compensate for an error at the noninverting input.

### **MONITORING BATTERY VOLTAGES**

Figure 34 illustrates how the AD628 can be used to monitor a battery charger. Voltages approximately eight times the power supply voltage can be applied to the input with no damage. The resistor divider action is well-suited for the measurement of many power supply applications, such as those found in battery chargers or similar equipment.

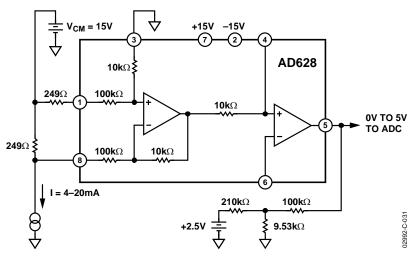


Figure 33. Level Shifter for 4 to 20 mA Current Loop

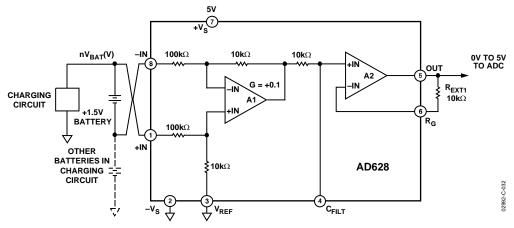


Figure 34. Battery Voltage Monitor

### **FILTER CAPACITOR VALUES**

A capacitor can be connected to Pin 4 ( $C_{\text{FILT}}$ ) to implement a low-pass filter. The capacitor value is

$$C = 15.9/f_t(\mu F)$$

where  $f_t$  is the desired 3 dB filter frequency.

Table 7 shows several frequencies and their closest standard capacitor values.

Table 7. Capacitor Values for Various Filter Frequencies

Frequency (Hz)	Capacitor Value (μF)
10	1.5
50	0.33
60	0.27
100	0.15
400	0.039
1 k	0.015
5 k	0.0033
10 k	0.0015

### **KELVIN CONNECTION**

In certain applications, it may be desirable to connect the inverting input of an amplifier to a remote reference point. This eliminates errors resulting in circuit losses in interconnecting wiring. The AD628 is particularly suited for this type of connection. In Figure 35, a 10 k $\Omega$  resistor is added in the feedback to match the source impedance of A2, which is described in more detail in the Gain Adjustment section.

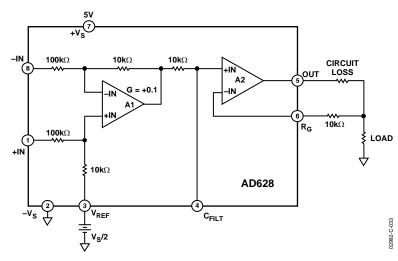
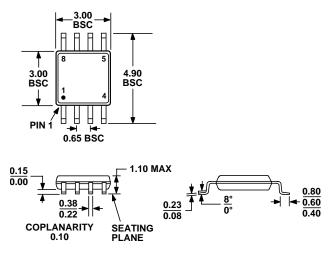


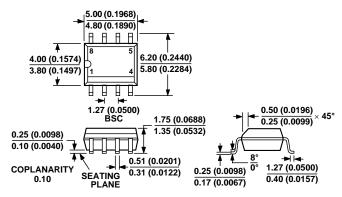
Figure 35. Kelvin Connection

### **OUTLINE DIMENSIONS**



**COMPLIANT TO JEDEC STANDARDS MO-187-AA** 

Figure 36. 8-Lead Mini Small Outline Package [MSOP] (RM-8) Dimensions shown in millimeters



#### **COMPLIANT TO JEDEC STANDARDS MS-012-AA**

CONTROLLING DIMENSIONS ARE IN MILLIMETERS; INCH DIMENSIONS (IN PARENTHESES) ARE ROUNDED-OFF MILLIMETER EQUIVALENTS FOR REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN

Figure 37. 8-Lead Standard Small Outline Package [SOIC] Narrow Body (R-8)

Dimensions shown in millimeters and (inches)

### **ORDERING GUIDE**

Model	Temperature Range	Description	Package Option	Branding
AD628AR	−40°C to +85°C	8-Lead SOIC	R-8	
AD628AR-REEL	-40°C to +85°C	8-Lead SOIC 13" Reel	R-8	
AD628AR-REEL7	-40°C to +85°C	8-Lead SOIC 7" Reel	R-8	
AD628ARZ <sup>1</sup>	-40°C to +85°C	8-Lead SOIC	R-8	
AD628ARZ-RL <sup>1</sup>	-40°C to +85°C	8-Lead SOIC 13" Reel	R-8	
AD628ARZ-R7 <sup>1</sup>	-40°C to +85°C	8-Lead SOIC 7" Reel	R-8	
AD628ARM	-40°C to +85°C	8-Lead MSOP	RM-8	JGA
AD628ARM-REEL	-40°C to +85°C	8-Lead MSOP 13" Reel	RM-8	JGA
AD628ARM-REEL7	-40°C to +85°C	8-Lead MSOP 7" Reel	RM-8	JGA
AD628ARMZ <sup>1</sup>	-40°C to +85°C	8-Lead MSOP	RM-8	JGZ
AD628ARMZ-RL <sup>1</sup>	-40°C to +85°C	8-Lead MSOP 13" Reel	RM-8	JGZ
AD628ARMZ-R7 <sup>1</sup>	-40°C to +85°C	8-Lead MSOP 7" Reel	RM-8	JGZ
AD628-EVAL		Evaluation Board		

<sup>&</sup>lt;sup>1</sup> Z = Pb-free part.

