

## **BMX160**

# 9-axis Absolute Orientation Sensor

#### **GENERAL DESCRIPTION**

The BMX160 is a very small low power, low noise absolute orientation sensor designed for use in wearable devices like smart watches or augmented reality glasses. It comprises a 3-axis accelerometer, gyroscope and geomagnetic sensor in a single package. Its current consumption is typically 1580  $\mu\text{A},$  enabling always-on applications in battery driven devices. The BMX160 is available in a compact 14-pin 2.5 x 3.0 x 0.95 mm³ LGA package.

#### **BMX160 TARGET APPLICATIONS**

- ► Augmented reality and immersive gaming
- ▶ 3D scanning and indoor mapping
- ► Indoor navigation and pedestrian dead-reckoning, step counting
- ► Wearable accessories requiring small footprint and high performance
- ▶ 9-axis sensor fusion, air mouse applications
- ► Optical image stabilization

### **BMX160 TARGET DEVICES**

- ► Smart watches, wearable fitness trackers, augmented reality glasses
- ▶ Mobile phones and tablet PCs
- ► Game controllers and smart remote controls
- ► Toys, e.g. quatrocopters

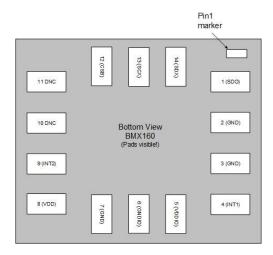
#### SENSOR FEATURES

Due to the built-in hardware synchronization of the inertial sensor data and geomagnetic sensor data, the BMX160 is ideally suited for augmented reality, immersive gaming, and navigation applications that require highly accurate, low power and low latency 9-axis sensor data fusion. The BMX160 provides high precision sensor data together with an accurate time stamp generated by a real-time clock. The BMX160 features an on-chip interrupt engine which provides motion-based context awareness as always-on background functions.

#### **TECHNICAL SPECIFICATIONS**

| BMX160 Technical data   |  |
|---|--|
| Package dimension (mm <sup>3</sup> )  | 2.5 x 3.0 x 0.95   |
| Temperature ranges  | -40 °C +85 °C  |
| Supply voltage (V <sub>DDIO</sub> ) Supply voltage (V <sub>DD</sub> )   | 1.2 V 3.6 V<br>1.71 V 3.6 V  |
| Typ. current consumption Gyro full operation Gyro + Acc. + Geomag. Geomag. @full operation Acc. @full operation Suspend mode Significant motion Step detector | 850 μΑ<br>1585 μΑ<br>660 μΑ<br>180 μΑ<br>5 μΑ<br>30 μΑ<br>30 μΑ  |
| Sensitivity   | (A)<br>±2 g: 16384 LSB/g<br>±4 g: 8192 LSB/g<br>±8 g: 4096 LSB/g<br>±16 g: 2048 LSB/g<br>(B)<br>±125 °/s: 262.4 LSB/°/s<br>±250 °/s: 131 LSB/°/s<br>±500 °/s: 65.6 LSB/°/s<br>±1000 °/s: 32.8 LSB/°/s<br>±2000 °/s: 16.4 LSB/°/s |
| Device resolution   | (M): 0.3 μT  |
| TCS (typ.)  | (A): ±0.03 %/K<br>(M): ±0.01 %/K<br>(G): ±0.02 %/K   |
| Non-linearity (typ.)  | (A): ±0.5 % FS<br>(G): ±0.1 % FS<br>(M): ±1 % FSmax  |
| Offset (typ.)   | (A): ±40 mg<br>(G): ±3 °/s<br>(M): ±40 μT  |
| TCO (typ.)  | (A): ±1.0 mg/K<br>(G): ±0.05 /s/K  |
| Noise density (typ.)  | (A): ±180 μg/ √Hz<br>(M): ±0.3 μT<br>(G): 0.008 °/s/ √Hz   |
| FIFO size   | 1024 byte  |
|   |  |

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Pin out

#### **TECHNICAL SPECIFICATIONS**

| Pin |                  |   |
|-----|------------------|---|
| Pin | Name             | Description   |
| 1   | SDO              | Serial data output in SPI<br>Address select in I <sup>2</sup> C mode  |
| 2   | GND              | Ground for digital and analog   |
| 3   | GND              | Ground for digital and analog   |
| 4   | INT              | Interrupt pin1  |
| 5   | V <sub>OUT</sub> | Digital I/O supply voltage (1.23.6 V)   |
| 6   | GNDIO            | Ground for I/O  |
| 7   | GND              | Ground for digital & analog   |
| 8   | VDD              | Power supply analog & digital domain (1.71 – 3.6 V)   |
| 9   | INT 2            | Interrupt pin 2   |
| 10  | -                | Do not connect  |
| 11  | _                | Do not connect  |
| 12  | CSB              | Chip select for SPI mode/<br>Protocol select pin  |
| 13  | SCx              | SCK: SPI clock<br>SCL: I <sup>2</sup> C clock   |
| 14  | SDX              | SDA serial data I/O in I <sup>2</sup> C<br>MOSI serial data input in SPI<br>4W<br>SISO serial data I/O in SPI<br>3W |

Examples of interrupts that can be issued, in a power efficient manner, without using extensive software algorithms are: any-or no-motion detection, tap or double tap sensing, orientation detection, free-fall or shock events.

The smart built-in power management unit (PMU) can be configured, for example, to further lower the power consumption by automatically sending the gyroscope into fast start-up mode and waking it again based on the any-motion interrupt of the accelerometer. By allowing the host to sleep longer, the PMU significantly contributes to power saving on system level.

#### **SYSTEM COMPATABILITY**

With a footprint of only  $2.5 \times 3.0 \text{ mm}^2$  and a package height of only 0.95 mm, the BMX160 can easily be designed into devices with miniaturized PCBs.

The BMX160 has been designed for always-on, 9-axis applications in wearable devices such as smart watches and head mounted devices, mobile phones, tablets, remote controls, game controllers, and toys such as quatrocopters.

BMX160 is footprint and register compatible to BMI160. This way it allows easy upgrade from the 6-axes intertial measurement unit to the 9-axes absolute orientation sensor.

The integrated 1024 byte FIFO buffer supports low power applications and prevents data loss in non-real-time systems. The intelligent FIFO architecture allows dynamic reallocation of FIFO space for accelerometer, gyroscope and geomagnetic sensor. In a typical 9-DoF application – including the geomagnetic sensor – this is sufficient for approx. 0.5 s. Accel and Gyro 16 bit, Accel 2 g to 16 g range.

The BMX160 is fully Android Marshmallow compliant, and in the implementation of the Significant Motion and Step Detector interrupts, each of which consumes less than 30  $\mu$ A. The BMX160 offers a wide V<sub>DD</sub> voltage range from 1.71 V to 3.6 V and a V<sub>DDIO</sub> range from 1.2 V to 3.6 V, allowing the BMX160 to be powered at 1.8 V for both V<sub>DD</sub> and V<sub>DDIO</sub>.

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