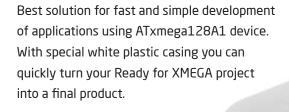
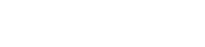
# Ready for XMEGA®











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Nebojsa Matic General Manager

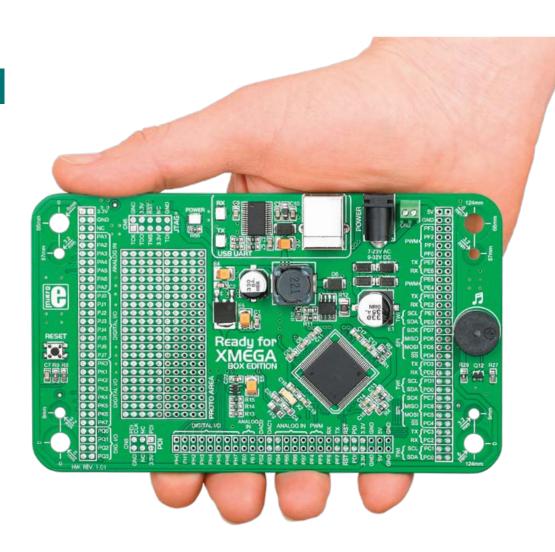
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# Introduction

Ready for XMEGA Board is the best solution for fast and simple development of various microcontroller applications. It comes with **ATxmega128A1**, and contains double-row smart headers for all available microcontroller ports. We have groupped pins according to their functions, so you have everything on the silkscreen. You don't even have to browse through the datasheet. Board also contains USB-UART module, prototyping area and a power supply circuit. Board is specially designed to fit into special white plastic casing so you can turn your XMEGA project into a final product.



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# Package Contains



Damage resistant protective box



Ready for XMEGA board with double row male pin headers



DVD with documentation and examples



04 Ready for XMEGA user's guide



Ready for XMEGA schematic



06 USB cable

# Key Features

## **System Specification**



#### power supply

Via AC/DC connector 7-23V AC or 9-32V DC



#### power consumption

50mA in idle state (when on-board modules are off)



#### **board dimensions**

141 x 84mm (5.55 x 3.3 inch)



#### weight

~67g (0.15 lbs)

JTAG connector

r 🔞

Power LED indicator

UART communication LEDs (RX, TX)

Power regulator 04

FTDI chip 0

USB UART connector 06

Power connector 0

Power screw terminals 08

Reset button (

Double-row pin headers 10

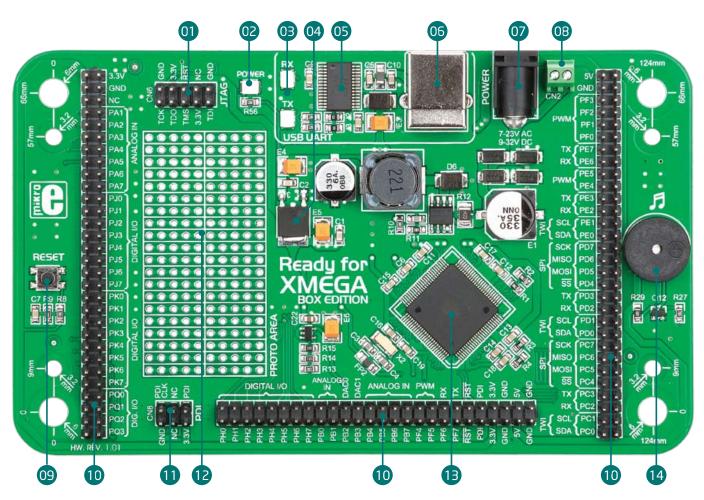
PDI connection 11

Prototyping area 12

ATxmega128A1 microcontroller

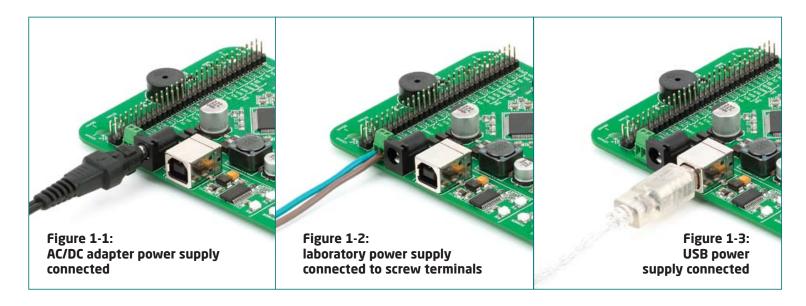
Piezo Buzzer 1

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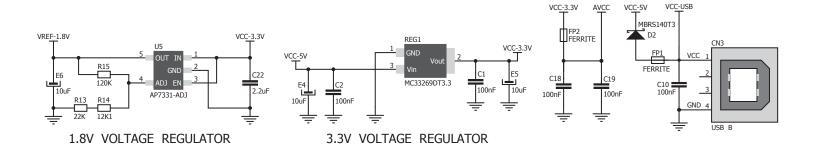


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## 1. Power supply



Ready for XMEGA board can be powered in two ways: via USB connection, or using external power sources such as adapters and laboratory power supplies. USB connection can provide up to 500mA of current which is more than enough for every on-board module and for operation of the microcontroller. If you decide to use external power supply, you can choose between AC/DC adapter connector or power screw terminals. Voltage values must be within **7-23V AC** or **9-32V DC** ranges. **Power LED (GREEN)** will indicate the presence of power supply. Use only one of suggested methods for powering the board.



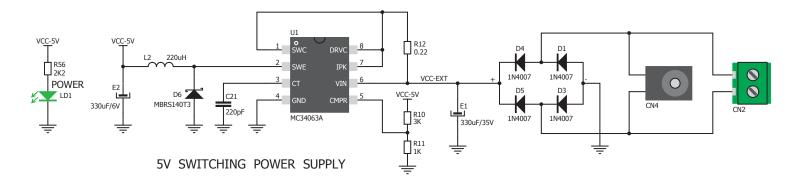


Figure 1-4: Power supply schematics

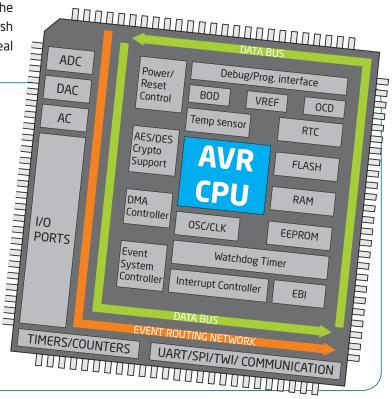
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# 2. ATxmega128A1 microcontroller

Ready for XMEGA development system comes with the **ATxmega128A1** microcontroller. Having lots of MIPS power, flash and RAM, and rich set of inegrated modules, ATxmega128A1 is ideal choice for both beginners and professionals.

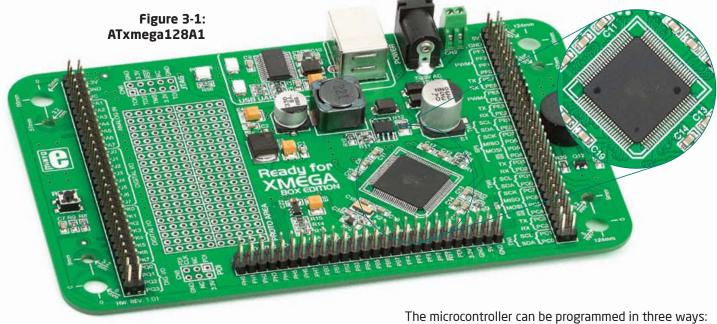
#### **Key microcontroller features**

- Up to 32 MIPS Operation;
- 8/16-bit architecture;
- 128KB of Flash memory;
- 8KB of SRAM memory;
- 2048Bytes of EEPROM;
- 78 I/O pins;
- 32kHz RTC;
- 1.6V to 3.6V Operating Voltage (VCC);
- UART, SPI, TWI;
- ADC, DAC, AC; etc.



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# 3. Programming the microcontroller



- 01 Via USB-UART mikroBootloader
- O2 Using JTAG external programmer
- 03 Using PDI external programmer

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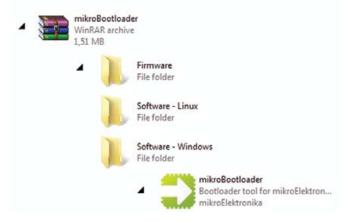
## Programming with mikroBootloader

You can program the microcontroller with bootloader which is preprogrammed into the device by default. To transfer .hex file from a PC to MCU you need bootloader software (**mikroBootloader USB HID**) which can be downloaded from:



http://www.mikroe.com/eng/downloads/get/1271/mikrobootloader\_xmega\_v101.zip

After software is downloaded, unrar it to a desired location, and start mikroBootloader USB HID software.



note

This version of mikroBootloader is specialized for ATxmega128A1 chip.

#### mikroBootloader software

**note** Before starting mikroBootloader software, connect Ready for XMEGA with a PC using USB cable provided with the package



Figure 3-2: mikroBootloader window

01

When you start mikroBootloader software, a window shown on **Figure 3-2** should appear.

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### **Identifying device COM port**



Figure 3-3: Identifying COM port

Open **Device Manager** window and expand **Ports section** to see which COM port is assigned to Ready for XMEGA board (in this case COM34)

## step 1 - Choosing COM port

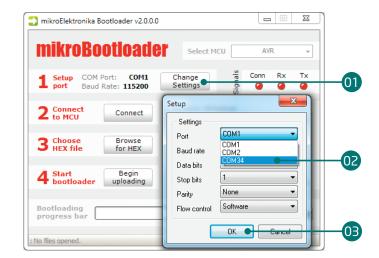


Figure 3-4: Choosing COM port

- Olick the "Change Settings" button.
- O2 From the drop down list, select appropriate COM **port** which is used for communication with a PC
- OB Click OK.

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## step 2 - Establishing Connection

note: Baud rate is set to 115200bps by default.



Figure 3-5: Connecting with mikroBootloader

O1 Press "Reset" button on Ready for XMEGA board and click "Connect" button within 5s, otherwise existing microcontroller program will execute. If connected, caption on a button will be changed to "Disconnect".

## step 3 - Browsing for .HEX file



Figure 3-6: Browse for HEX

O1 Click the "Browse for HEX" button and from a pop-up window (Figure 3.7) choose .HEX file which will be uploaded to MCU memory

## step 4 - Selecting .HEX file

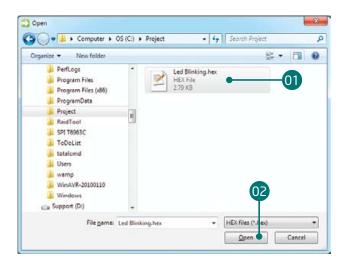


Figure 3-7: Locating and Selecting .hex file

- 01 Select .HEX file using open dialog window.
- OZ Click the "Open" button.

## step 5 - Uploading .HEX file



Figure 3-8: Begin uploading

01 To start .HEX file bootloding click the "Begin uploading" button.

## step 6 - Progress bar



Figure 3-9: Progress bar

101 You can monitor .HEX file uploading via progress bar.

## step 7 - Finish upload

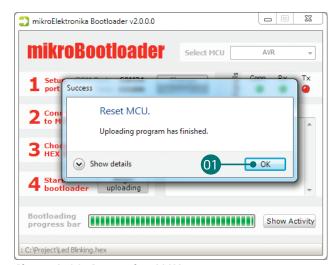
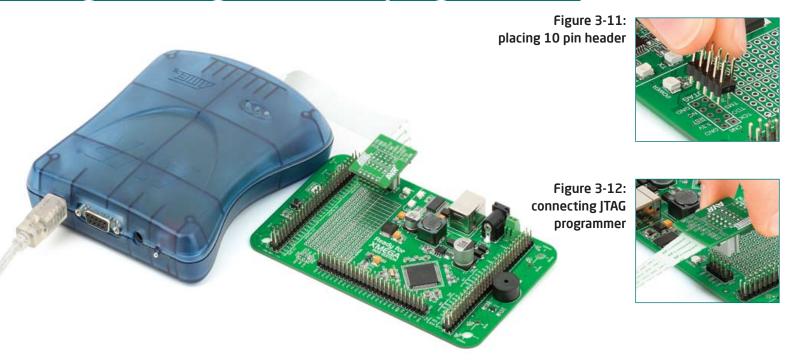


Figure 3-10: Restarting MCU

- 01 Click "OK" button after uploading is finished.
- O2 Press "Reset" button on Ready for XMEGA board and wait for 5 seconds. Your program will execute automatically.

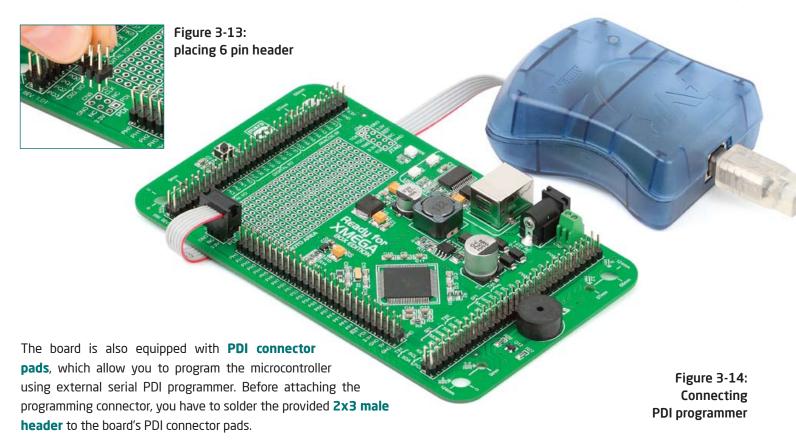
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# Programming with JTAG programmer



Ready for XMEGA board contains **JTAG connector pads** so you can program the board and debug your code using external programer/ debugger. Before connecting the programmer you have to solder the provided **IDC10 2x5 male header** onto the board's JTAG connector pads. If bootloader program is accidentally erased, you can upload it again via AVR JTAG or PDI programmer. Ready for XMEGA Bootloader **Firmware.hex** can be found under Firmware folder (see page 12).

# Programming with PDI programmer



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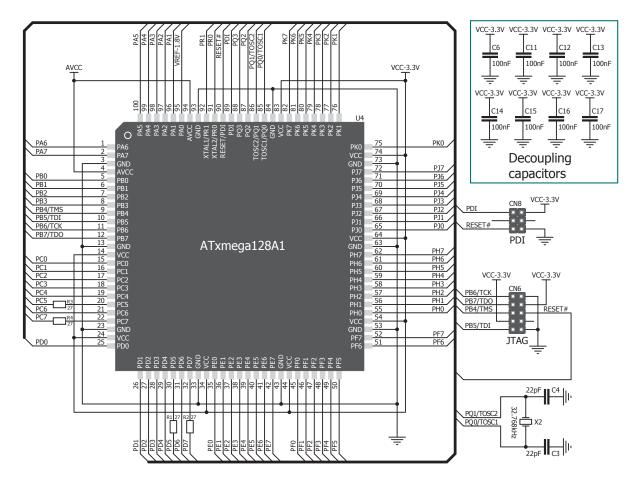


Figure 3-15: PDI & JTAG programmer connection schematics

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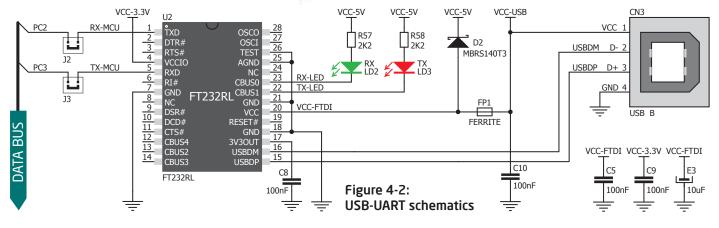
## 4. USB-UART

Fast on-board **FTDI®** chip allows you to communicate with a PC or other UART devices using USB-UART connection. USB-B connector (CN3) is used for connecting the USB cable. RX (receive) and TX (transmit) LEDs will indicate communication status. Before conecting the board with the PC, make sure to have the appropriate FTDI drivers installed on your operating system. Drivers can be found at following URL:

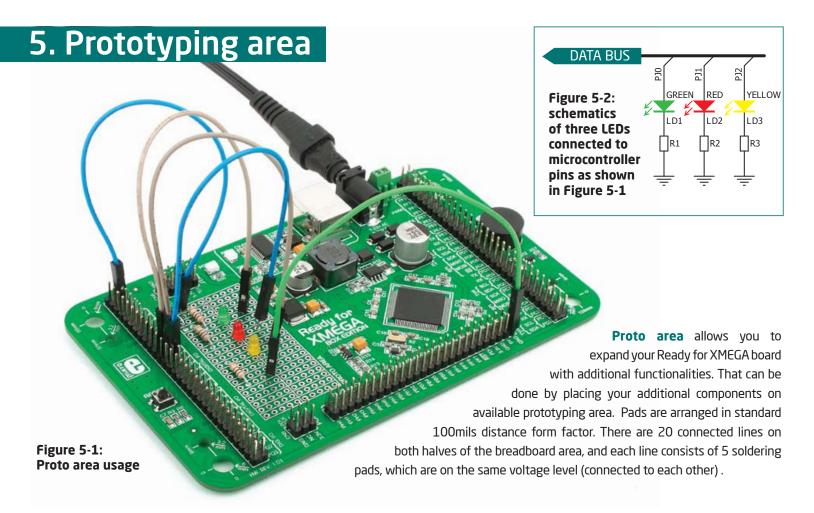
#### http://www.ftdichip.com/Drivers/VCP.htm



**USB-UART** connected



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# 6. Pin headers

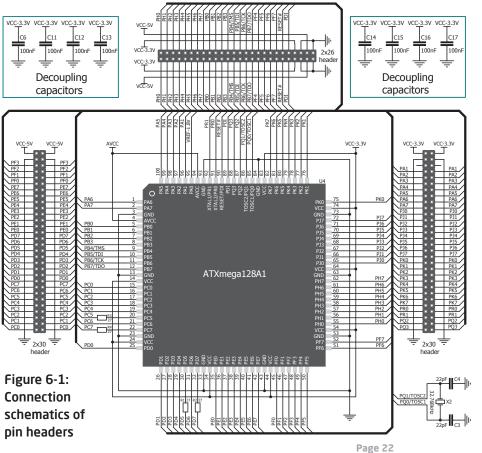


Figure 6-2: Pin headers Each microcontroller pin is available for futher connections through on-board connection headers. Each line is available in two header pins. Pins are groupped according to their functions, which makes development and connections much easier. Everything is printed on the silkscreen, so you won't even have to open the microcontroller datasheet while developing. Before using the pins, you have to solder the provided 2x30 and **2x26 male headers** onto the board's pads.

#### 7. Reset button Figure 7-1: **Reset button** VCC-3.3V connection R8 10K schematics AVCC VCC-3.3V Ready for XMEGA 1 C4 22pF has board 10 11 12 13 14 15 16 17 18 specialized reset circuit ATXmega128A1 with high-quality reset VCC<u>-3</u>.3V VCC<u>-3</u>.3V VCC<u>-3</u>.3V button, which can be used to reset the program execution of the microcontroller. If you want VCC-3.3V VCC-3.3V VCC-3.3V VCC-3.3V to reset the circuit, press on-board C15 RESET button. It will generate low 100nF 100nF 100nF 100nF voltage level on microcontroller reset pin (input). In addition, a reset can be 20 20 20 20 20 20 30 40 </tr Decoupling externally provided through RST pin capacitors on 2x26 header (Figure 6-1).

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# 8. Piezo buzzer

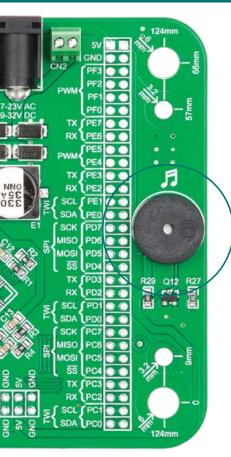
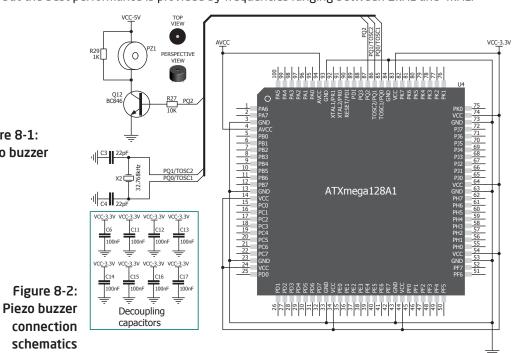


Figure 8-1: Piezo buzzer

On-board piezo buzzer is a very useful module which can be used in debuging your code, or to have audio signalization feature when board is integrated as a final product. Piezo buzzer's resonant frequency is 3.8kHz. In addition, other frequencies in the range between 20Hz and 20.000Hz can be used, but the best performance is provided by frequencies ranging between 2kHz and 4kHz.



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## 9. Integrating with the casing



Figure 9-1:
Place the board into the bottom part
of the casing. Make sure to align the
connectors with the square openenings

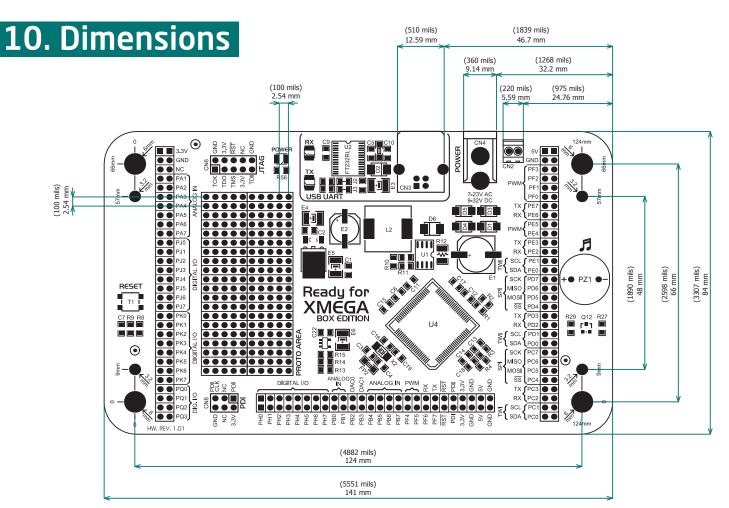


Figure 9-2: Wind screws into inner screw holes to mount the board to the bottom casing plastic



Figure 9-2: Place cover casing plastic and wind screws into outter screw holes for connecting it with bottom plastics

Ready for XMEGA can easily be integrated into the specialized white plastic casing. This feature is very convenient for turning the board into a final product. The white plastic casing contains inner and outter screw holes. Inner are used for attaching the board to the casing and outter are used for connecting the top part of the casing, and enclosing the board. Casing comes with holes for USB and power adapter connector, but you can customize it by driling and cutting holes in specific areas, depending on the target application.



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