# PM STEP MOTORS



































# **PM STEP MOTORS**

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# **Product List**

# **Product Line Up**

Series	Outer Diameter (mm)	Length (mm)	Step No.	Step Angle (°)
20PM020S	20	14.3	20	18
20PM020L	20	19.3	20	18
25PM024S	25	12.5	24	15
25PM048S	25	12.5	48	7.5
25PM024L	25	17.0	24	15
25PM048L	25	17.0	48	7.5
35PM024S	35	15.3	24	15
35PM048S	35	15.3	48	7.5
35PM024L	35	21.3	24	15
35PM048L	35	21.3	48	7.5
42PM048S	42	15.3	48	7.5
42PM096S	42	15.3	96	3.75
42PM048L	42	21.3	48	7.5
42PM096L	42	21.3	96	3.75
Series	Outer Diameter (mm)	Shaft Stroke (mm)	Step No.	Step Travel (mm)
20LN024M	20	50	24	0.0508
25LN024L	25	40	24	0.0508
28L024L	28	13	24	0.0420
35LN024L	35	12	24	0.0333

# **Model Numbering System**

42 PM 048 L 1 - 003 02

# Base frame code

Outer diameter size: 42mm diameter = 42

## Motor type code

PM: permanent magnet step motor

LN: permanent magnet linear step motor

## Step code

020: 20 steps per rotation, 18° step angle

024: 24 steps per rotation, 15° step angle

048: 48 steps per rotation, 7.5° step angle

096: 96 steps per rotation, 3.75° step angle

# Length code

S: short version

M: middle version

L: long version

# Magnet grade code

# Resistance code

Winding resistance: 30hm = 003

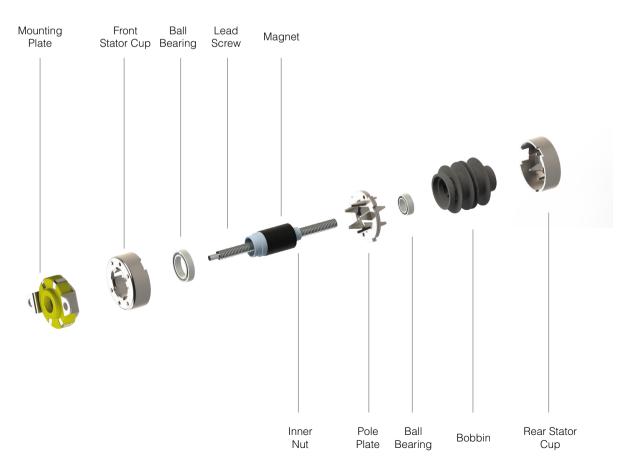
## Mechanical code

# **Structure**

# **Rotary Motors**

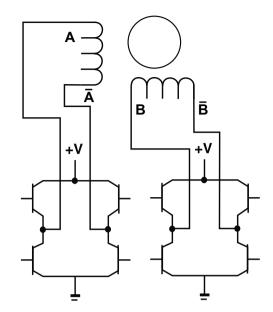


# **Linear Actuators**



# **Operating Principles**

# **Schematic Diagrams**



# Step Sequence

CONNECTOR PIN LOCATION							
PIN NO.	COLOR	CCW - CW (SEEN FROM FLANGE SIDE) PHASE					
1	BLACK	ON	ON			ON	Α
2	YELLOW			ON	ON		Ā
3	ORANGE		ON	ON			В
4	BROWN	ON			ON	ON	B

# **Operating Principles**

In response to each individual control pulse and direction signal, the drive applies power to the motor windings to cause the rotor to take a step forward, a step in reverse, or hold in position.

For example, in a 7.5 degree two phase step motor: When both phases are energized with DC current, the motor will stop rotating and hold in position. The maximum torque the motor can hold in place with rated DC current, is the rated holding torque. If the current in one phase is reversed, the motor will move 1 step (7.5 degrees) in a known direction. If the current in the other phase had been reversed, the motor would move 1 step (7.5 degrees) in the other direction. As current is reversed in each phase in sequence, the motor continues to step in the desired direction. These steps are very accurate. For a 7.5 degree step motor, there are exactly 48 steps in one revolution.

Two phase stepping motors are furnished with two types of windings: bipolar or unipolar. In a bipolar motor there is one winding on each phase. The motor moves in steps as the current in each winding is reversed. This requires a drive with eight electronic switches. In a unipolar motor there are two windings on each phase. The two windings on each phase are connected in opposite directions. Phase current is reversed by turning on alternate windings on the same phase. This requires a drive with only four electronic switches. Bipolar operation typically provides 40% more holding torque than unipolar, because 100% of the winding is energized in the bipolar arrangement.

# Rotary Motors

- · Ø20mm
- · Ø25mm
- · Ø35mm
- · Ø42mm



# 20PM020S - Ø20mm, S, 18°



Phases 2Steps / Revolution 20Shaft Load

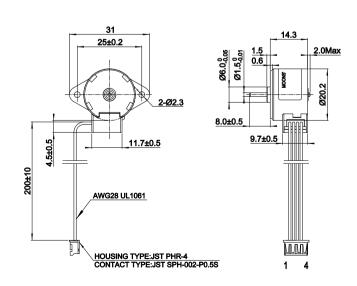
Axial 1N
Radial 5N
IP Rating 40
Approvals RoHS

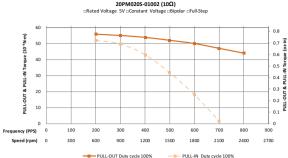
Operating Temp. -20°C to +50°C
 Insulation Class B, 130°C
 Insulation Resistance 100 MegOhms

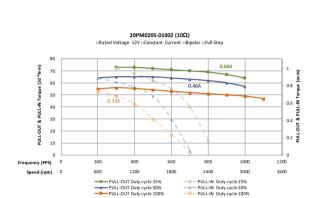
# **Motor Data**

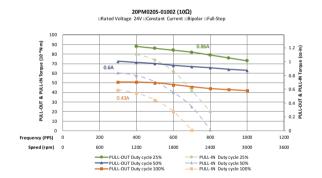
Model	Number	20PM020S0-01002	20PM020S0-02501	
Le	ngth	14.3mm	(0.56in.)	
Step Angle		0	1	8
Rated Current	An	nps	0.33	0.21
Halding Tayon	10 <sup>-4</sup> Nm	Тур.	90	100
Holding Torque	oz-in	Тур.	1.3	1.4
Coil Resistance	Ohms	±10% @ 20°C	10	25
Coil Inductance	mH	Тур.	4.6	10.6
Detent Torque	10 <sup>-4</sup> Nm	Max.	27	27
Detent Torque	oz-in	Max.	0.38	0.38
Datas In autic	gcm <sup>2</sup>		0.24	0.24
Rotor Inertia	10 <sup>-4</sup> oz-in <sup>2</sup>		13.1	13.1
Motor Weight	g		21	
Motor Weight	Lbs		0.05	

<sup>^</sup> Preferred model

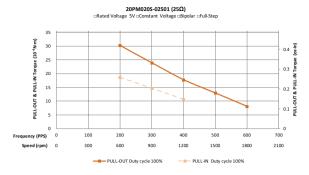


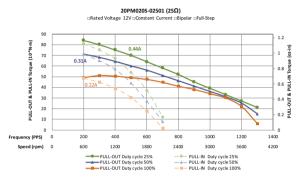


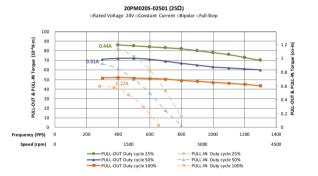




## 20PM020S0-02501







# 20PM020L - Ø20mm, L, 18°



Phases 2
Steps / Revolution 20
Shaft Load

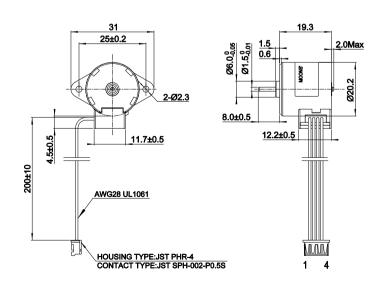
Axial 1N
Radial 5N
IP Rating 40
Approvals RoHS

Operating Temp. -20°C to +50°C
 Insulation Class B, 130°C
 Insulation Resistance 100 MegOhms

# **Motor Data**

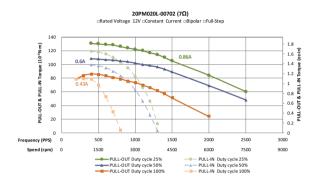
Model	Number	20PM020L8-00702	20PM020L8-02101	
Lei	ngth	19.3mm	(0.76in.)	
Step Angle		0	1	8
Rated Current	An	nps	0.43	0.25
Halding Tayous	10 <sup>-4</sup> Nm	Тур.	155	155
Holding Torque	oz-in	Тур.	2.2	2.2
Coil Resistance	Ohms	±10% @ 20°C	7	21
Coil Inductance	mH	Тур.	4.8	14.3
Detect Towns	10 <sup>-4</sup> Nm	Max.	41	41
Detent Torque	oz-in	Max.	0.57	0.57
Dotor Inortio	gcm <sup>2</sup>		0.37	0.37
Rotor Inertia	10 <sup>-4</sup> oz-in <sup>2</sup>		20.2	20.2
Motor Weight	g		27	
	Lbs		0.06	

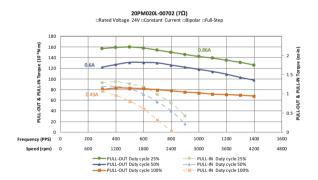
^ Preferred model



# 20PM020L8-00702

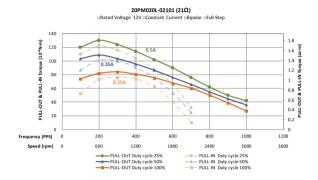






## 20PM020L-02101 (21Ω) □Rated Voltage 5V □Constant Voltage □Bipolar □Full-Step PULL-OUT & PULL-IN Torque (104N·m) 50 0.7 (ujezo) an buol NI-TING & LONG-TING & 0.6 0.5 0.4 0.3 0.2 0.2 40 20 10 0.1 Frequency (PPS) 0 200 400 500 300 1800 Speed (rpm) 0 600 900 1200 1500

20PM020L8-02101





# 25PM024S - Ø25mm, S, 15°



Phases 2Steps / Revolution 24Shaft Load

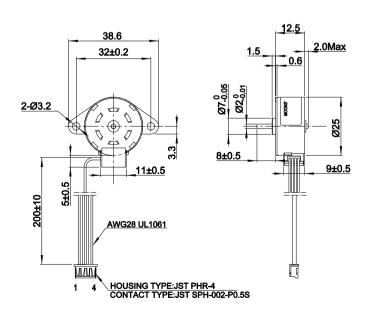
Axial 1N
Radial 5N
IP Rating 40
Approvals RoHS

Operating Temp. -20°C to +50°C
 Insulation Class B, 130°C
 Insulation Resistance 100 MegOhms

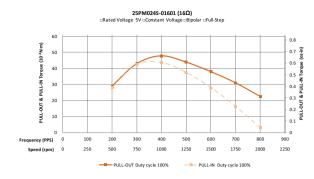
# **Motor Data**

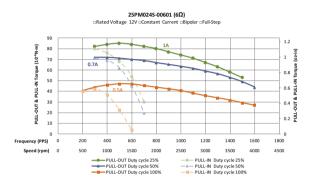
Model	Number	25PM024S8-00601	25PM024S8-01601	
Le	ngth	12.5mm	(0.40in.)	
Step Angle		0	1	5
Rated Current	An	nps	0.5	0.32
Halding Tayous	10 <sup>-4</sup> Nm	Тур.	105	115
Holding Torque	oz-in	Тур.	1.5	1.6
Coil Resistance	Ohms	±10% @ 20°C	6	16
Coil Inductance	mH	Тур.	2.7	7.4
Detect Town	10 <sup>-4</sup> Nm	Max.	29	29
Detent Torque	oz-in	Max.	0.40	0.40
Datas la astic	gc	cm <sup>2</sup>	0.54	0.54
Rotor Inertia	10 <sup>-4</sup> oz-in <sup>2</sup>		29.5	29.5
Matau Maiaht		g	30	
Motor Weight	LI	bs	0.07	

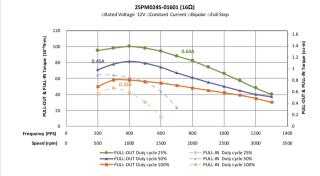
^ Preferred model

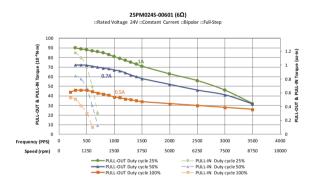














# 25PM048S - Ø25mm, S, 7.5°



Phases 2Steps / Revolution 48

Shaft Load

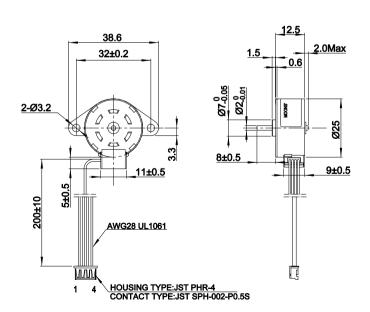
Axial 1N
Radial 5N
IP Rating 40
Approvals RoHS

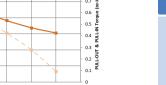
Operating Temp. -20°C to +50°C
 Insulation Class B, 130°C
 Insulation Resistance 100 MegOhms

# **Motor Data**

Model	Number	25PM048S9-00601	25PM048S9-01601	
Lei	ngth	12.5mm	(0.40in.)	
Step Angle		0	7	.5
Rated Current	An	nps	0.5	0.32
Halding Tayous	10 <sup>-4</sup> Nm	Тур.	170	230
Holding Torque	oz-in	Тур.	2.4	3.2
Coil Resistance	Ohms	±10% @ 20°C	6	16
Coil Inductance	mH	Тур.	3.4	9.4
Detect Towns	10 <sup>-4</sup> Nm	Max.	44	44
Detent Torque	oz-in	Max.	0.61	0.61
Datas Inastia	go	m²	0.54	0.54
Rotor Inertia	10 <sup>-4</sup> oz-in <sup>2</sup>		29.5	29.5
MotovWoight		9	30	
Motor Weight	Lbs		0.07	

^ Preferred model





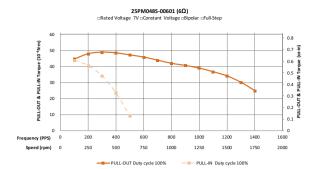


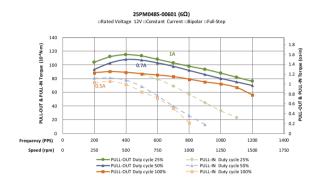


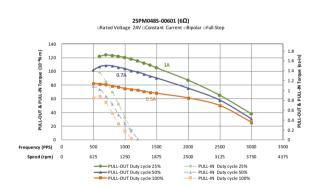




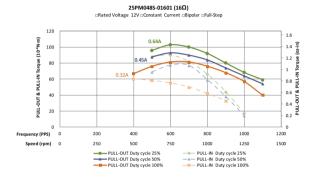


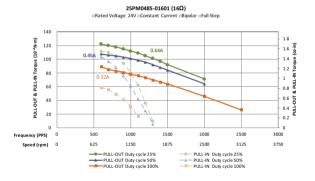












# 25PM024L - Ø25mm, L, 15°



Phases 2Steps / Revolution 24Shaft Load

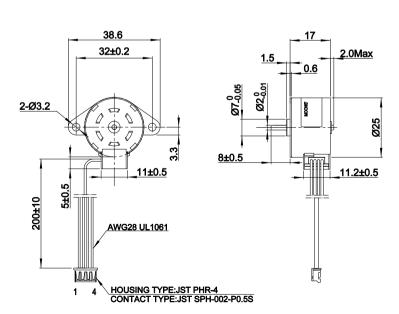
Axial 1N
Radial 5N
IP Rating 40
Approvals RoHS

Operating Temp. -20°C to +50°C
 Insulation Class B, 130°C
 Insulation Resistance 100 MegOhms

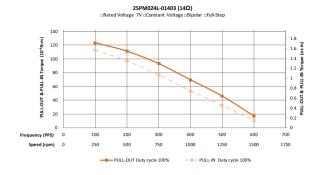
# **Motor Data**

Model	Number	25PM024L8-00801	25PM024L8-01403	
Lei	ngth	17mm (0.67in.)		
Step Angle		0	1	5
Rated Current	An	nps	0.47	0.35
Lialding Tayous	10 <sup>-4</sup> Nm	Тур.	160	170
Holding Torque	oz-in	Тур.	2.2	2.4
Coil Resistance	Ohms	±10% @ 20°C	8	14
Coil Inductance	mH	Тур.	7.9	14.4
Detent Torque	10 <sup>-4</sup> Nm	Max.	36	36
Detent Torque	oz-in	Max.	0.50	0.50
Rotor Inertia	gc	rm²	0.88	0.88
Hotor mertia	10 <sup>-4</sup> oz-in <sup>2</sup>		48.1	48.1
Motor Weight	g		39	
	Lbs		0.09	

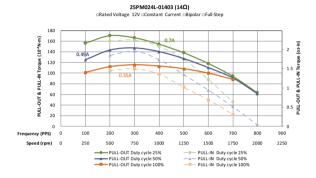
^ Preferred model

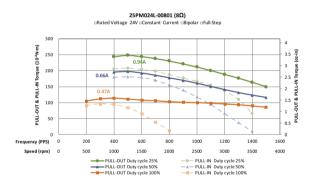














# 25PM048L - Ø25mm, L, 7.5°



Phases 2Steps / Revolution 48

Shaft Load

Axial 1N
Radial 5N
IP Rating 40
Approvals Role

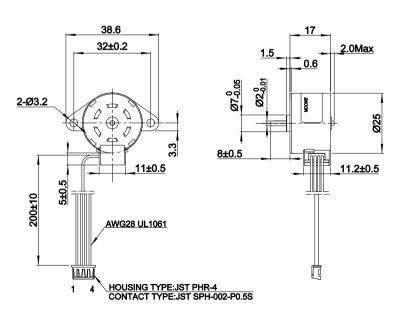
Approvals RoHS
 Operating Temp. -20°C to +50°C

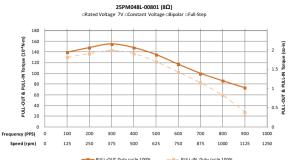
Insulation Class
 Insulation Resistance
 100 MegOhms

# **Motor Data**

Model	Number	25PM048L9-00801	25PM048L9-01401	
Le	ngth	17mm (0.67in.)		
Step Angle		0	7	.5
Rated Current	An	nps	0.47	0.35
Halding Tayon	10 <sup>-4</sup> Nm	Тур.	270	270
Holding Torque	oz-in	Тур.	3.8	3.8
Coil Resistance	Ohms	±10% @ 20°C	8	14
Coil Inductance	mH	Тур.	7.2	14.5
Detect Towns	10 <sup>-4</sup> Nm	Max.	33	33
Detent Torque	oz-in	Max.	0.45	0.45
Determinentia	gc	cm <sup>2</sup>	0.88	0.88
Rotor Inertia	10 <sup>-4</sup> oz-in <sup>2</sup>		48.1	48.1
MotovWoight	g		39	
Motor Weight	Lbs		0.09	

<sup>^</sup> Preferred model



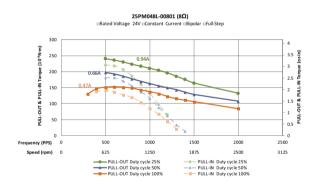


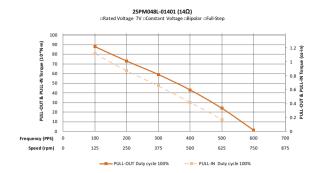


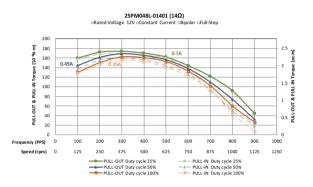
1000

1000

1200









Frequency (PPS)

Speed (rpm) 0

# 35PM024S - Ø35mm, S, 15°



Phases 2Steps / Revolution 24

Shaft Load

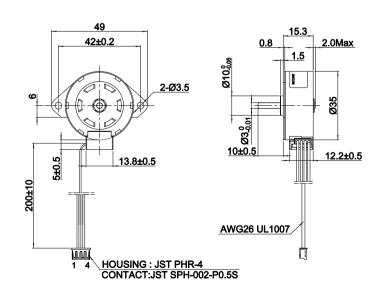
Axial 1 N
Radial 7.5 N
IP Rating 40
Approvals RoHS

Operating Temp. -20°C to +50°C
 Insulation Class B, 130°C
 Insulation Resistance 100 MegOhms

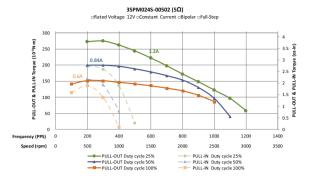
# **Motor Data**

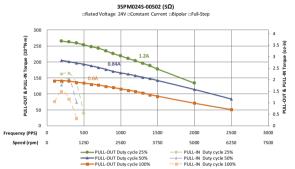
Model	Number		35PM024S9-00502	35PM024S9-01201	35PM024S9-08001		
Length				15.3mm (0.60in.)			
Step Angle		0		15			
Rated Current	Д	mps	0.6	0.38	0.15		
Holding Torque	10 <sup>-4</sup> Nm	Тур.	270	270	310		
Holding Torque	oz-in	Тур.	3.8	3.8	4.3		
Coil Resistance	Ohms	±10% @ 20°C	5	12.5	80		
Coil Inductance	mH	Тур.	4.2	10	62.4		
Datant Targue	10 <sup>-4</sup> Nm	Max.	55	70	70		
Detent Torque	oz-in	Max.	0.77	0.97	0.97		
Datau Inautia	Q	gcm²	2.8	2.8	2.8		
Rotor Inertia	10-	4 oz-in²	153	153	153		
Motor Woight		g	70				
Motor Weight		Lbs	0.15				

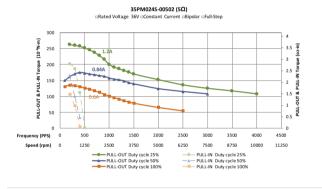
^ Preferred model





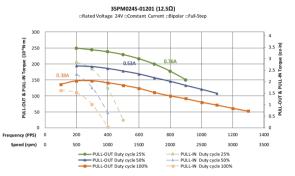






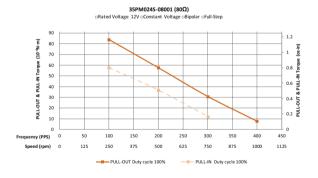


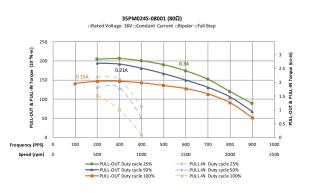
35PM024S9-01201

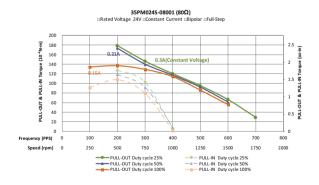




## 35PM024S9-08001







# 35PM048S - Ø35mm, S, 7.5°



Phases 2Steps / Revolution 48

Shaft Load

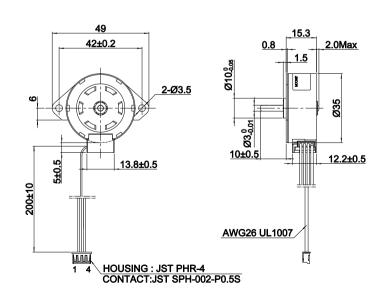
Axial 1 N
Radial 7.5 N
IP Rating 40
Approvals RoHS

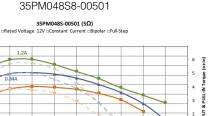
Operating Temp. -20°C to +50°C
 Insulation Class B, 130°C
 Insulation Resistance 100 MegOhms

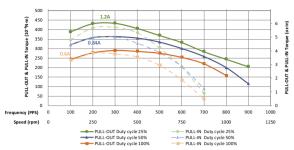
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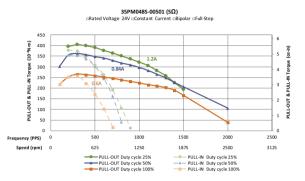
M	odel Number		35PM048S8-00501	35PM048S8-01201	35PM048S8-08001		
Length				15.3mm (0.60in.)			
Step Angle		0		7.5			
Rated Current	,	Amps	0.6	0.38	0.15		
Holding Torque	10 <sup>-4</sup> Nm	Тур.	450	450	540		
Holding Torque	oz-in Typ.		6.3	6.3	7.6		
Coil Resistance	Ohms ±10% @ 20°C		5	12.5	80		
Coil Inductance	mH	Тур.	5.2	12.5	78		
Detent Torque	10 <sup>-4</sup> Nm	Max.	60	75	75		
Detent Torque	oz-in	Max.	0.8	1.04	1.04		
Rotor Inertia	gcm <sup>2</sup>		2.8	2.8	2.8		
Hotor inertia	10	r <sup>4</sup> oz-in <sup>2</sup>	153	153	153		
Motor Woight		g		70			
Motor Weight		Lbs	0.15				

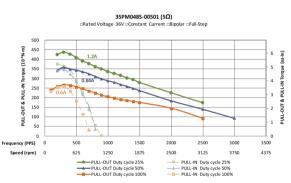
^ Preferred model







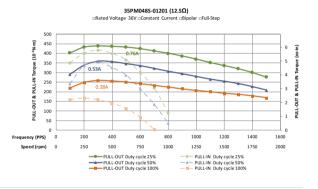




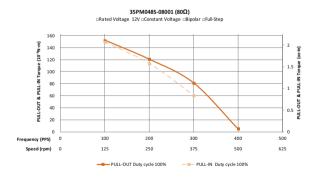


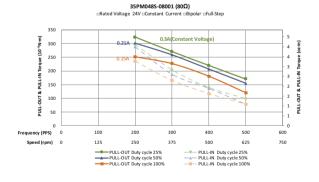
35PM048S8-01201

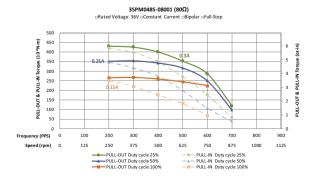












# 35PM024L - Ø35mm, L, 15°



Phases 2Steps / Revolution 24

Shaft Load

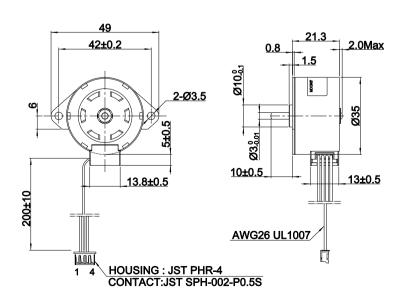
Axial 1 N
Radial 7.5 N
IP Rating 40
Approvals RoHS

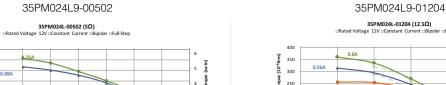
Operating Temp. -20°C to +50°C
 Insulation Class B, 130°C
 Insulation Resistance 100 MegOhms

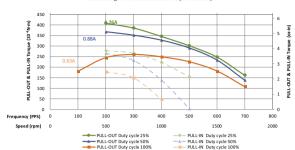
# **Motor Data**

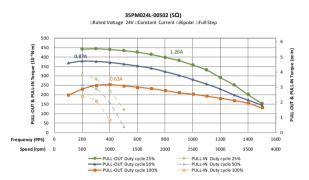
Mode	Model Number			35PM024L9-01204	35PM024L9-07501	
Le	Length			21.3 mm (0.84 in.)		
Step Angle		0		15		
Rated Current	А	mps	0.63	0.4	0.16	
Holding Torque	10 <sup>-4</sup> Nm	Тур.	450	450	490	
Holding Torque	oz-in	Тур.	6.3	6.3	6.9	
Coil Resistance	Ohms	±10% @ 20°C	5	12.5	75	
Coil Inductance	mH	Тур.	6.2	14.7	71	
Detent Torque	10 <sup>-4</sup> Nm	Max.	150	185	185	
Detent Torque	oz-in	Max.	2.1	2.57	2.57	
Datas la autia	gcm <sup>2</sup>		4.7	4.7	4.7	
Rotor Inertia	10-4	oz-in²	257	257	257	
Motor Moight	g		90			
Motor Weight	Lbs		0.2			

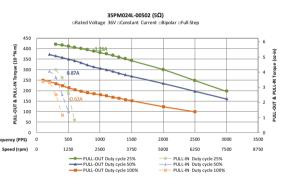
^ Preferred model

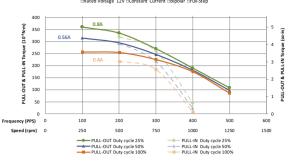


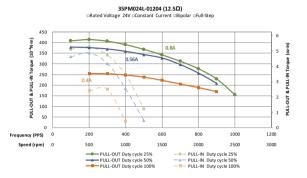


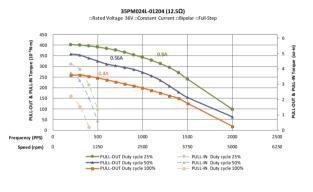




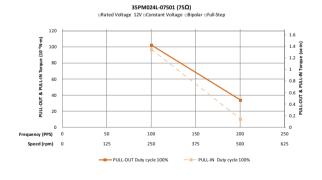


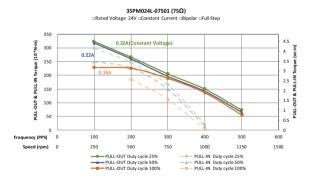


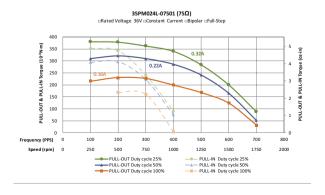












# 35PM048L - Ø35mm, L, 7.5°



Phases 2 Steps / Revolution 48

Shaft Load

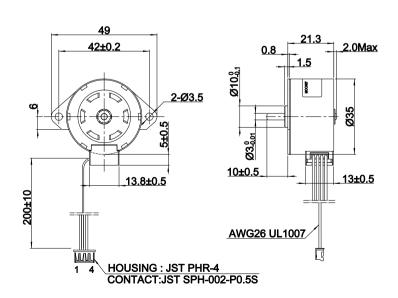
Axial 1 N Radial 7.5 N IP Rating 40 Approvals RoHS

Operating Temp. -20°C to +50°C Insulation Class B, 130°C Insulation Resistance 100 MegOhms

# **Motor Data**

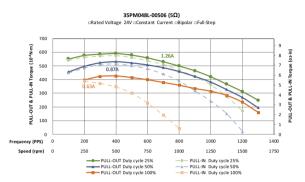
Mo	Model Number			35PM048L8-01201	35PM048L8-07501	
	Length		21.3 mm (0.84 in.)			
Step Angle		0		7.5		
Rated Current	Α	mps	0.63	0.4	0.16	
Halding Tayous	10 <sup>-4</sup> Nm	Тур.	670	670	700	
Holding Torque	oz-in	Тур.	9.4	9.4	9.8	
Coil Resistance	Ohms	±10% @ 20°C	5	12.5	75	
Coil Inductance	mH	Тур.	8.6	20.1	98.5	
Datast Tayoua	10 <sup>-4</sup> Nm	Max.	130	130	130	
Detent Torque	oz-in	Max.	1.81	1.81	1.81	
Datau la autia	gcm <sup>2</sup>		4.7	4.7	4.7	
Rotor Inertia	10 <sup>-4</sup> oz-in <sup>2</sup>		257	257	257	
Matax Maiaht		g	90			
Motor Weight	Lbs		0.2			

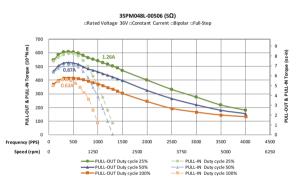
^ Preferred model

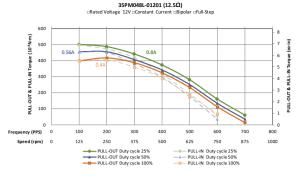


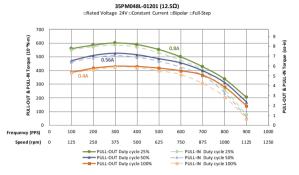


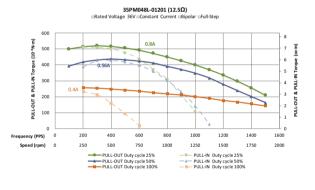




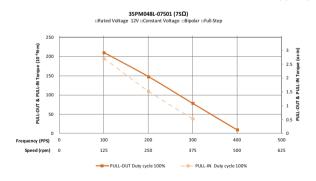


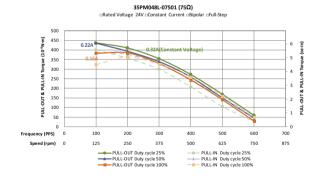


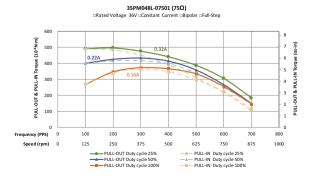




# 35PM048L8-07501







# 42PM048S - Ø42mm, S, 7.5°



Phases 2Steps / Revolution 48

Shaft Load

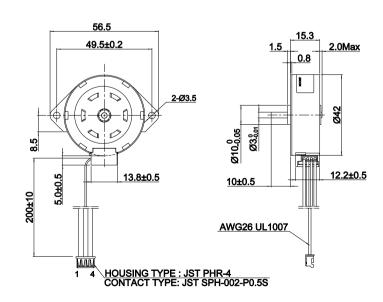
Axial 1 N
Radial 7.5 N
IP Rating 40
Approvals RoHS

Operating Temp. -20°C to +50°C
 Insulation Class B, 130°C
 Insulation Resistance 100 MegOhms

# **Motor Data**

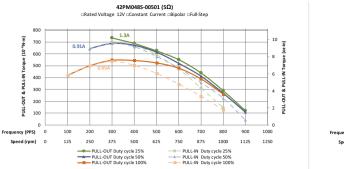
Model Number			42PM048S0-00501	42PM048S0-01201	42PM048S0-08001	
Length		15.3mm (0.60in.)				
Step Angle		0		7.5		
Rated Current	A	Amps	0.65	0.42	0.15	
Halding Tayous	10 <sup>-4</sup> Nm	Тур.	870	830	800	
Holding Torque	oz-in	Тур.	12.2	11.6	11.2	
Coil Resistance	Ohms	±10% @ 20°C	5	12	80	
Coil Inductance	mH	Тур.	5.4	11.6	72.5	
Detent Tourne	10 <sup>-4</sup> Nm	Max.	126	126	126	
Detent Torque	oz-in	Max.	1.75	1.75	1.75	
Detectoration	gcm <sup>2</sup>		7.4	7.4	7.4	
Rotor Inertia	10 <sup>-4</sup> oz-in <sup>2</sup>		404	404	404	
MataulMaiaht		g	90			
Motor Weight	Lbs		0.2			

^ Preferred model



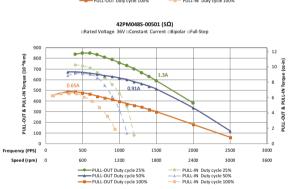
Rotary

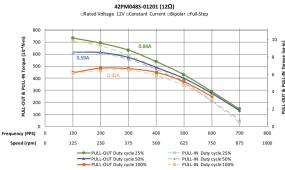


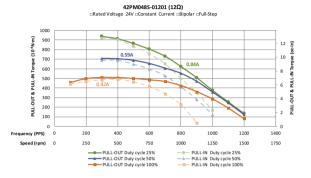


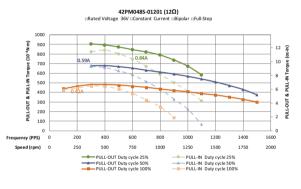
42PM048S0-00501



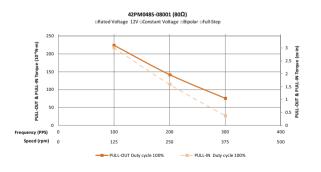


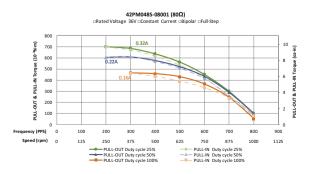


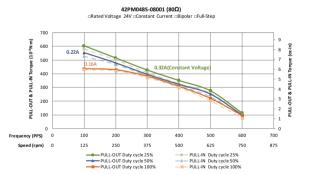




# 42PM048S0-08001







# 42PM096S - Ø42mm, S, 3.75°



Phases 2Steps / Revolution 96

Shaft Load

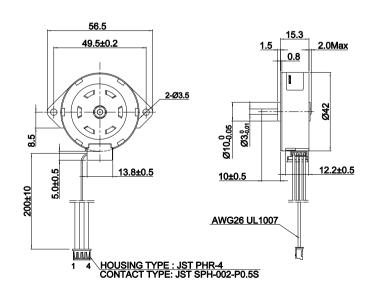
Axial 1 N
Radial 7.5 N
IP Rating 40
Approvals RoHS

Operating Temp. -20°C to +50°C
 Insulation Class B, 130°C
 Insulation Resistance 100 MegOhms

# **Motor Data**

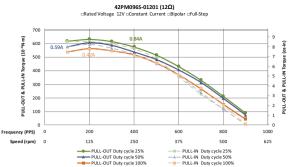
Model Number		42PM096S0-00501	42PM096S0-01201	42PM096S0-08001		
	Length		15.3mm (0.60in.)			
Step Angle		0		3.75		
Rated Current	Д	mps	0.65	0.42	0.15	
Halding Tayous	10 <sup>-4</sup> Nm	Тур.	960	940	780	
Holding Torque	oz-in	Тур.	13.4	13.2	10.9	
Coil Resistance	Ohms	±10% @ 20°C	5	12	80	
Coil Inductance	mH	Тур.	6.2	13.4	82	
Datant Tayawa	10 <sup>-4</sup> Nm	Max.	90	90	90	
Detent Torque	oz-in	Max.	1.25	1.25	1.25	
Datay Inartia	gcm <sup>2</sup>		7.4	7.4	7.4	
Rotor Inertia	10 <sup>-4</sup> oz-in <sup>2</sup>		404	404	404	
Matax Waight		g	90			
Motor Weight		Lbs	0.2			

<sup>^</sup> Preferred model

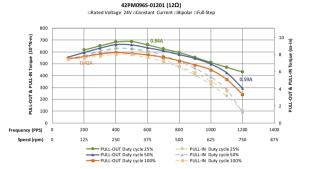


Rotary

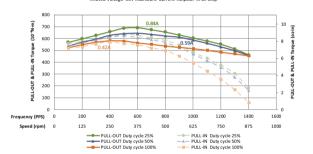








## 42PM096S-01201 (12Ω)



250

PULL-OUT Duty cycle 25%
PULL-OUT Duty cycle 50%
PULL-OUT Duty cycle 100%

125

42PM096S0-00501

42PM096S-00501 (5Ω)
□Rated Voltage 12V □Constant Current □Bipolar □Full-Step

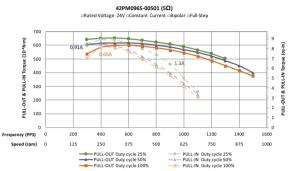
400 300

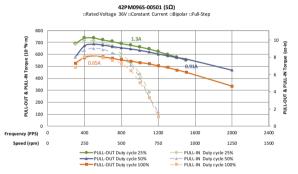
200

100

Frequency (PPS) 0

Speed (rpm) 0





# 42PM096S0-08001

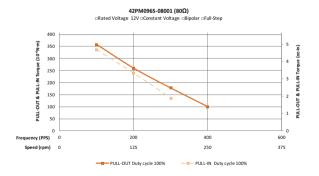
1200

750

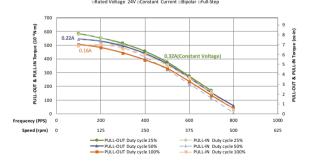
1000

625

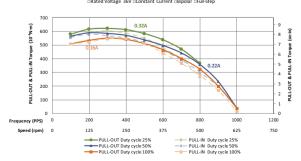
PULL-IN Duty cycle 25%
PULL-IN Duty cycle 50%
PULL-IN Duty cycle 100%



# 42PM096S-08001 (80Ω) □Rated Voltage 24V □Constant Current □Bipolar □Full-Step



# 42PM096S-08001 (80Ω) Rated Voltage 36V □Constant Current □Big



# 42PM048L - Ø42mm, L, 7.5°



Phases 2Steps / Revolution 48

Shaft Load

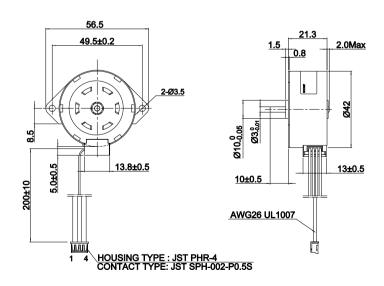
Axial 1 N
Radial 7.5 N
IP Rating 40
Approvals RoHS

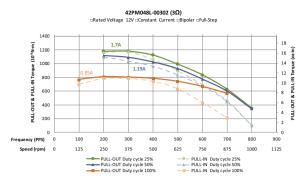
Operating Temp. -20°C to +50°C
 Insulation Class B, 130°C
 Insulation Resistance 100 MegOhms

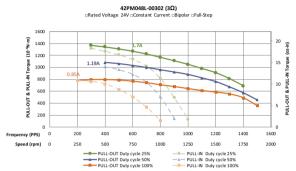
# **Motor Data**

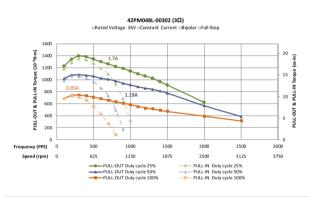
M	Model Number			42PM048L1-00711	42PM048L1-06001	
	Length		21.3 mm (0.84 in.)			
Step Angle		0		7.5		
Rated Current	,	Amps	0.85	0.55	0.2	
Halding Tayous	10 <sup>-4</sup> Nm	Тур.	1200	1200	1250	
Holding Torque	oz-in	Тур.	16.8	16.8	17.5	
Coil Resistance	Ohms	±10% @ 20°C	3	7	60	
Coil Inductance	mH	Тур.	4.4	9.6	82	
Datast Tausus	10 <sup>-4</sup> Nm	Max.	215	215	215	
Detent Torque	oz-in	Max.	2.99	2.99	2.99	
Datas In autic	gcm <sup>2</sup>		11	11	11	
Rotor Inertia	10 <sup>-4</sup> oz-in <sup>2</sup>		601	601	601	
MataxMaiaht		g	120			
Motor Weight	Lbs		0.26			

<sup>^</sup> Preferred model

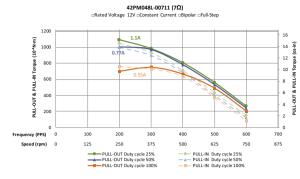


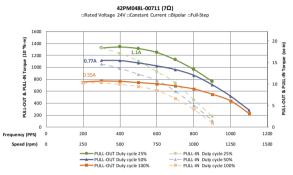


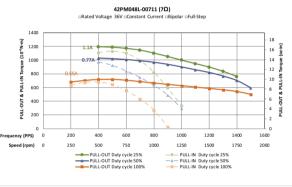




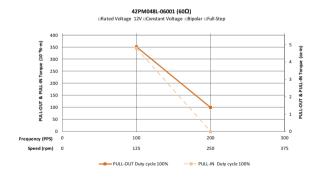
## 42PM048L1-00711

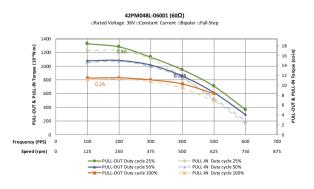


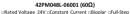


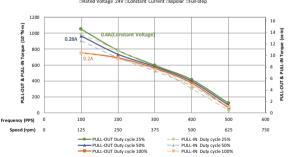


# 42PM048L1-06001









Technic

# 42PM096L - Ø42mm, L, 3.75°



Phases 2Steps / Revolution 96

Shaft Load

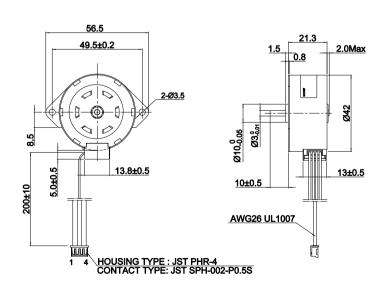
Axial 1 N
Radial 7.5 N
IP Rating 40
Approvals RoHS

Operating Temp. -20°C to +50°C
 Insulation Class B, 130°C
 Insulation Resistance 100 MegOhms

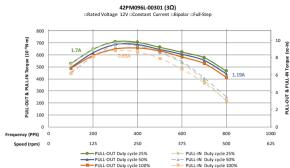
# **Motor Data**

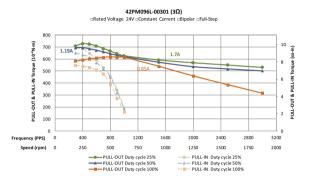
Model Number			42PM096L1-00301	42PM096L1-00701	42PM096L1-06001	
Length		21.3 mm (0.84 in.)				
Step Angle		0		3.75		
Rated Current	А	mps	0.85	0.55	0.2	
Holding Torque	10 <sup>-4</sup> Nm	Тур.	970	920	900	
Holding Torque	oz-in	Тур.	13.6	12.9	12.6	
Coil Resistance	Ohms	±10% @ 20°C	3	7	60	
Coil Inductance	mH	Тур.	5.5	12.1	103	
Detent Torque	10 <sup>-4</sup> Nm	Max.	215	215	215	
Detent Torque	oz-in	Max.	2.99	2.99	2.99	
Datas Inastia	gcm <sup>2</sup>		11	11	11	
Rotor Inertia	10 <sup>-4</sup> oz-in <sup>2</sup>		601	601	601	
Motor Woight		g	120			
Motor Weight	Lbs		0.26			

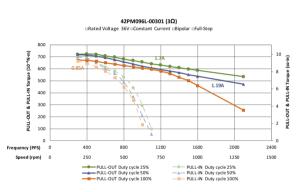
^ Preferred model



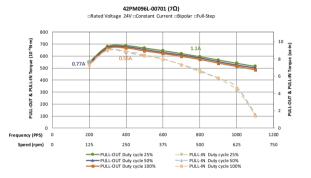


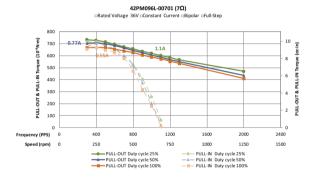




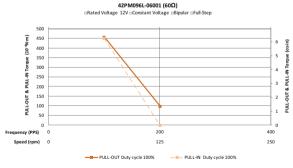








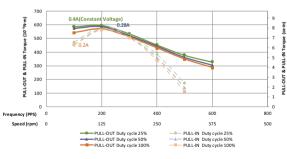




42PM096L-06001 (60Ω) □Rated Voltage 36V □Constant Current □Bipolar □Full-Step

PULL-OUT Duty cycle 25%
PULL-OUT Duty cycle 50%
PULL-OUT Duty cycle 100%





42PM096S-06001 (60Ω)
□Rated Voltage 24V □Constant Current □Bio

600 500

PULL-OUT & PULL-IN Torque 400 300 200

Frequency (PPS) 0

Note	

# Linear Actuators

- · Ø20mm
- · Ø25mm
- · Ø28mm
- · Ø35mm



Actuators



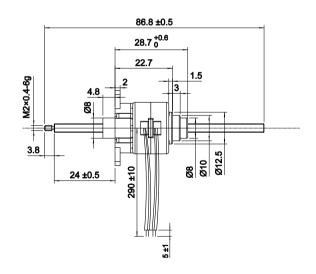
•	Phases	2
•	Steps	24
•	Shaft Stroke	50mm
•	Linear Step Travel	0.0508 mm
•	Bearing System	2 Ball Bearings
•	Ambient Temp.	-10°C to +65°C
•	Insulation Class	B, 130°C
•	Insulation Resistance	20MeaOhms

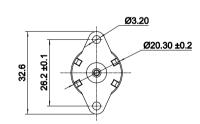
# **Motor Data**

Model	20LN024M8-01401		
Step Angle		0	15
Constant Current		Amps	0.35
Holding Force	N	Тур.	30
	OZ	Тур.	107.9
Coil Resistance	Ohms	±7% @ 25°C	14
Coil Inductance	mH	±15%	6.4
Pull/Push Force	N	@ 400000	30
Full/Fusii Force	oz	@ 400pps	107.9
Date d Nat Weight	g		45
Rated Net Weight	Lbs		0.099

# 20LN024M8-01401 (14Ω) □Rated Voltage 12V □Constant Current □Bipolar □Full-Step 45 40 0.35A **2** 30 Force ( 25 **ysnd/lind** 15 10 0 200 1000 1200 Pulse Rate (pps)

Pull/Push Force





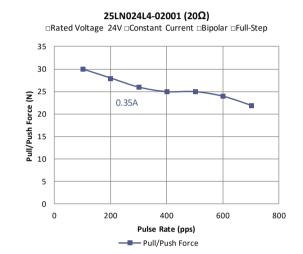


Phases 2
Steps 24
Shaft Stroke 40mm
Linear Step Travel 0.0508 mm
Bearing System 2 Ball Bearings
Ambient Temp. -20°C to +65°C

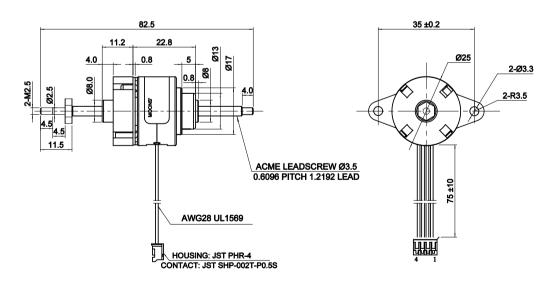
Insulation Class
 Insulation Resistance
 B, 130°C
 100MegOhms

# **Motor Data**

Mode	25LN024L4-02001		
Step Angle		0	15
Constant Current		Amps	0.35
Holding Force	N	Тур.	40
	OZ	Тур.	143.9
Coil Resistance	Ohms	±7% @ 25°C	20
Coil Inductance	mH	±15%	12.9
Pull/Push Force	N	@	24
Pull/Push Force	OZ	600pps	86.3
Data d Nati Walata	g		45
Rated Net Weight	Lbs		0.099



# Dimensions: mm



vei view

Rotary Motors

Linear Actuators

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# 28L024L - Ø28mm, L, 15°

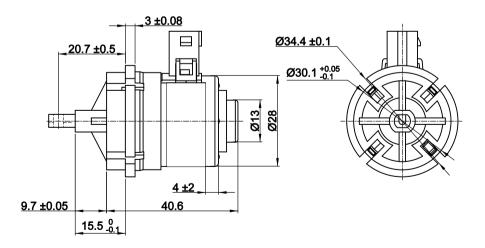


Phases Steps 24 Shaft Stroke 13mm Linear Step Travel 0.042 mm Bearing System 2 Ball Bearings Ambient Temp. -10°C to +80°C Insulation Class B, 130°C Insulation Resistance 100MegOhms

# **Motor Data**

Mode	28L024L8-15001		
Step Angle		0	15
Constant Current		Amps	0.13
Holding Force	N	Тур.	100
Holding Force	OZ	Тур.	359.7
Coil Resistance	Ohms	±7% @ 25°C	150
Coil Inductance	mH	±15%	112
Dull/Duch Force	N	@	60
Pull/Push Force	OZ	200pps	215.8
5	g		75
Rated Net Weight	Lbs		0.165

# 28L024L8-15001 (150Ω) □Rated Voltage 24V □Constant Current □Bipolar □Full-Step 70 Pull/Push Force (N) 0.13A 50 40 30 20 10 200 400 600 800 1000 Pulse Rate (pps) Pull/Push Force



# 35LN024L - Ø35mm, L, 15°

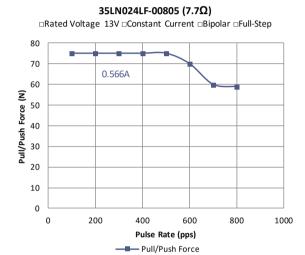


Phases 24 Steps 12mm Shaft Stroke Linear Step Travel 0.0333 mm Bearing System 2 Ball Bearings Ambient Temp. -40°C to +120°C

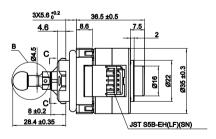
Insulation Class B, 130°C Insulation Resistance 100MegOhms

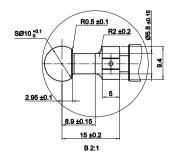
# **Motor Data**

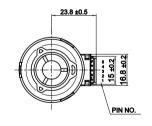
Mod	35LN024LF-00805		
Step Angle		0	15
Constant Current		Amps	0.566
Holding Force	N	Тур.	110
	OZ	Тур.	395.7
Coil Resistance	Ohms	±7% @ 25°C	7.7
Coil Inductance	mH	±15%	9.75
Dull/Duch Force	N	@	50
Pull/Push Force	OZ	364pps	179.9
Dated Nat Waight	g		115
Rated Net Weight	Lbs		0.254

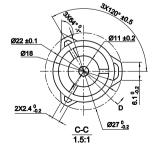


Dimensions: mm









Actuators

Note	

- · Speed-Torque Characteristics
  - · About Rated Current
    - · Conversion Factors



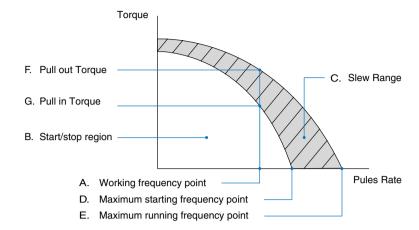
Rotary Motors

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# **Speed-Torque Characteristics**

The dynamic torque curve is an important aspect of stepping motor's output performance. The followings are some keyword explanations.



A. Working frequency point express the stepping motors rotational speed versus the drive pulse rate. n = q \* Hz / (360 \* D)

n: rev/sec

Hz: the frequency value or the driver pulse rate.

D:the subdividing value of motor driver

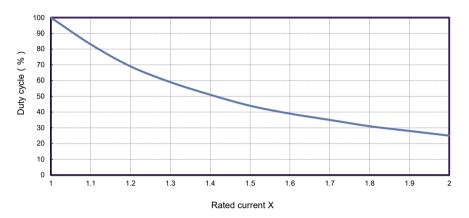
a: the step angle of stepping motor

- B. Start/Stop region: the region in which a stepping motor can be directly started or stopped.
- C. Slew Range: the motor cannot be started directly in this area. It must be started in the start/stop region first and then accelerated to this area. In this area, the motor can not be directly stopped, either. Otherwise this will lead to losing-step. The motor must be decelerated back to the start/stop region before it can be stopped.
- D. Maximum starting frequency point at this point, the stepping motor can reach its maximum starting speed under unloaded condition.
- E. Maximum running frequency point at this point the stepping motor can reach its maximum running speed under an unloaded condition.
- F. Pull-in Torque: the maximum dynamic torque value that a stepping motor can load directly at the particular operating frequency point.
- G. Pull-out Torque: the maximum dynamic torque value that a stepping motor can load at the particular operating frequency point when the motor has been started. Because of the inertia of rotation the Pull-Out Torque is always larger than the Pull-In Torque.

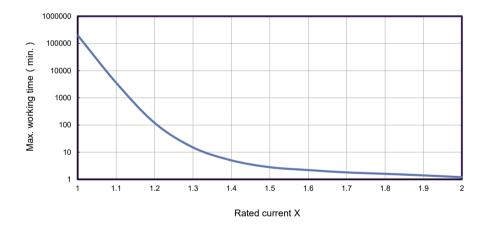
Rated current of PM stepper is limited by thermal characteristics.

In actual application, to get higher output torque we can supply with higher current, which extend rated value. In such case, the motor can't be in continuous working, otherwise the winding will be overheat even damage device. Duty cycle need to be not reach to 100%, also we must consider Max. working time - Ton Max.

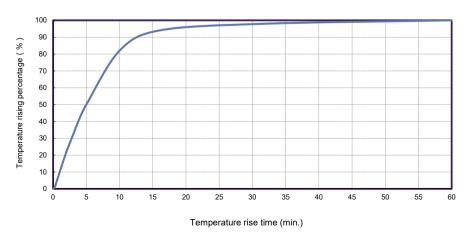
# How to define the duty cycle with multiple of rated current



# How to calculate the max. Single working time with multiple of rated current



# Motor winding temperature rising curve



Rotary Motors

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# **Conversion Factors**

# • Length

A	mm	cm	m	inch	feet	
mm		0.1	0.001	0.03937	0.003281	
cm	<b>cm</b> 10		0.01	0.3937	0.03281	
m	n 1,000 100			39.37	3.281	
inch	25.4	2.54	0.0254		0.08333	
feet	304.8	30.48	0.348	12		

Multiply "A" units by conversion factor to obtain "B" units

# Force

A	Bg		oz	lb	Newton	
g		0.001	0.03527	0.002205	0.0098	
kgf	<b>kgf</b> 1,000		35.27	22.05	9.807	
oz	28.35 0.02835			0.0625	0.278	
lb	453.6	0.4536	16		4.448	
Newton	<b>ewton</b> 102 0.102		3.597	0.2248		

# • Torque

A	Nm	Ncm	mNm	kgm*	kgcm*	gcm*	oz-in	lb-ft	lb-in
Nm		100	1,000	0.102	10.2	10,200	141.6	0.7376	8.851
Ncm	0.01		10	0.00102	0.102	102	1.416	0.007376	0.08851
mNm	0.001	0.1		0.000102	1.0102	10.2	0.1416	0.000738	0.008851
kgm*	9.807	980.7	9807		100	100,000	1,389	7.233	86.8
kgcm*	0.09807	9.807	98.07	0.01		1,000	13.89	0.07233	0.868
gcm*	9.81E-05	0.009807	0.09807	0.00001	0.001		0.01389	7.23E-05	0.000868
oz-in	0.007062	0.7062	7.062	0.00072	0.07201	72.01		0.00521	0.0625
lb-ft	1.356	135.6	135.6	0.1383	13.83	13,830	192		12
lb-in	0.113	11.3	113	0.01152	1.152	1,152	16	0.0833	

# Inertia

A	kgm²	kgcm²	gcm²	oz-in²	oz-in- sec²	lb-in²	lb-in- sec²	lb-ft²	lb-ft- sec² (slug ft²)
kgm²		10,000	10,000,000	54,700	142	3,420	8.85	23.7	0.738
kgcm²	0.0001		1,000	5.47	0.0142	0.342	0.000885	0.00237	7.38E-05
gcm²	1E-07	0.001		0.00547	1.42E-05	0.000342	8.85E-07	2.37E-06	7.38E-08
oz-in²	1.83E-05	0.1829	183		0.00259	0.0625	0.000162	0.000434	1.35E-05
oz-in-sec²	0.00706	70.62	70,600	386		24.1	0.0625	0.168	0.00521
lb-in²	0.000293	2.926	2,930	16	0.0414		0.00259	0.00694	0.000216
lb-in-sec²	0.113	1,130	1,130,000	6,180	1.6	386		2.68	0.0833
lb-ft²	0.0421	421.4	421,000	2,300	5.97	144	0.373		0.318
lb-ft-sec² (slug ft²)	1.36	13,600	13,600,000	74,100	192	4,630	12	32.2	

168 Mingjia Road, Minhang District, Shanghai 201107,

P.R. China

Tel: +86 (0)21 52634688

Fax:+86 (0)21 52634098

# ■ MOONS' International Trading Company

4/F, Building 30, 69 Guiqing Road, Cao He Jin Hi-Tech

Park, Shanghai 200233, P.R. China

Tel: +86 (0)21 64952755 Fax:+86 (0)21 64951993

# Domestic Offices

## Shenzhen

Room 2209, 22/F, Kerry Center, 2008 Renminnan Road,

Luohu District, Shenzhen 518001, P.R. China

Tel: +86 (0)755 25472080 Fax:+86 (0)755 25472081

Beijing

Room 816, Tower B, China Electronics Plaza, 3 Danling

Street, Haidian District, Beijing 100080, P.R. China

Tel: +86 (0)10 58753312

Fax:+86 (0)10 58752279

# Nanjing

Room 1101-1102, Building 2, New Town Development

Center, No.126 Tianyuan Road, Moling Street,

Jiangning District, Nanjing 211199, P.R. China Tel: +86 (0)25 52785841

Fax:+86 (0)25 52785485

# Qingdao

Room 1012, Zhuoyue Tower, No.16 Fengcheng Road,

Shibei District, Qingdao 26000, P.R. China

Tel: +86 (0)532 80969935

Fax:+86 (0)532 80919938

## Wuhan

Room 3001, World Trade Tower, 686 Jiefang Avenue,

Jianghan District, Wuhan 430022, P.R. China

Tel: +86 (0)27 85448742

Fax:+86 (0)27 85448355

## Chengdu

Room 1917, Western Tower, 19, 4th Section of South People

Road, Wuhou District, Chengdu 610041, P.R. China

Tel: +86 (0)28 85268102

Fax:+86 (0)28 85268103

# Xi'an

Room 1006, Tower D, Wangzuo International City,

1 Tangyan Road, Xi'an 710065, P.R. China

Tel: +86 (0)29 81870400

Fax:+86 (0)29 81870340

# Ningbo

Room 309, Tower B, Taifu Plaza, 565 Jiangjia Road,

Jiangdong District, Ningbo, 315040, P.R. China

Tel: +86 (0)574 87052739

Fax:+86 (0)574 87052365

## Guangzhou

Room 4006, Tower B, China Shine Plaza, 9 Linhe Xi Road,

Tianhe District, Guangzhou 510610, P.R. China

Tel: +86 (0)20 38010153

Fax:+86 (0)20 38103661

# North America Company

## MOONS' INDUSTRIES (AMERICA) INC.

1113 North Prospect Avenue, Itasca, IL 60143 USA

Tel: +1 630 8335940

Fax: +1 630 8335946

## APPLIED MOTION PRODUCTS INC.

404 Westridge Dr. Watsonville, CA 95076, USA

Tel: +1 831 7616555

## LIN ENGINEERING, INC.

16245 Vineyard Blvd., Morgan Hill, CA 95037

Tel: +1 408 9190200

Fax:+1 408 9190201

# European Company

## MOONS' INDUSTRIES (EUROPE) S.R.L.

Via Torri Bianche n.1 20871 Vimercate(MB) Italy

Tel: +39 039 6260521

Fax: +39 039 9631409

# ■ South-East company

## MOONS' INDUSTRIES (SOUTH-EAST ASIA) PTE. LTD.

33 Ubi Avenue 3 #08-23 Vertex Singapore 408868

Tel: +65 66341198

Fax: +65 66341138

# Japan Company

## MOONS' INDUSTRIES JAPAN CO., LTD.

Room 601, 6F, Shin Yokohama Koushin Building,

2-12-1, Shin-Yokohama, Kohoku-ku, Yokohama,

Kanagawa, 222-0033, Janpan

Tel: +81 (0)45 4755788

Fax: +81 (0)45 4755787



http://www.moons.com.cn E-mail: info@moons.com.cn

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