

# **CMOS Boost Converter – White LED Driver**



#### **FEATURES**

- Drives up to 5 White LEDs from 3V
- Power Efficiency up to 87%
- Low Quiescent Ground Current 0.1mA
- Adjustable Output Current (up to 30mA)
- High Frequency 1MHz Operation
- "Zero" current shutdown mode
- Operates down to 2V (from two AA batteries)
- Soft start power-up
- Open LED low power mode
- Automatic shutdown at 1.9V (UVLO)
- Thermal shutdown protection
- Thin SOT23 5-Lead (1mm max height)

## **APPLICATIONS**

- LCD Backlighting
- Cellular Phones
- **■** Handheld Devices
- Digital Cameras

## ORDERING INFORMATION

Part Number	Package	Quantity per Reel	Package Marking
CAT4137TD-T3	TSOT23-5 <sup>(1)</sup>	3000	LX
CAT4137TD-GT3	TSOT23-5 <sup>(2)</sup>	3000	UE

Notes: (1) Matte-Tin Plated Finish (RoHS-compliant).

(2) NiPdAu Plated Finish (RoHS-compliant).

# **DESCRIPTION**

The CAT4137 is a DC/DC step-up converter that delivers a regulated output current. Operation at a constant switching frequency of 1MHz allows the device to be used with small value external ceramic capacitors and inductor.

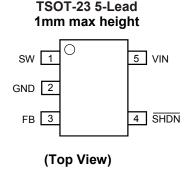
The device drives a string of white LEDs connected in series and provides the regulated current to control the LEDs with inherent uniform brightness and matching. An external resistor R1 sets the output current and allows up to 30mA current to be supported over a wide range of input supply voltages from 2.2V to 5.5V, making the device ideal for battery-powered applications.

LED dimming can be done by using a DC voltage, a logic signal, or a pulse width modulation (PWM) signal. The shutdown control pin allows the device to be placed in power-down mode with "zero" quiescent current.

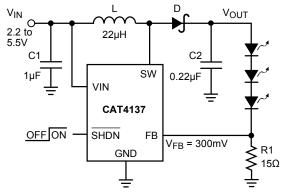
In addition to thermal protection and overload current limiting, the device also enters a very low power operating mode during "Open LED" fault conditions. The device is housed in a low profile (1mm max height) 5-lead thin SOT23 package for space critical applications.

For Ordering Information details see page 15.

## PIN CONFIGURATION



# **TYPICAL APPLICATION CIRCUIT**



L: Murata LQH32CN220

D: Central CMDSH2-3 (rated 30V)

# **ABSOLUTE MAXIMUM RATINGS**

Parameter	Rating	Unit
VIN, FB voltage	-0.3 to +7	V
SHDN voltage	-0.3 to +7	V
SW voltage	-0.3 to 40	V
Storage Temperature Range	-65 to +160	°C
Junction Temperature Range	-40 to +150	°C
Lead Temperature	300	°C

# **RECOMMENDED OPERATING CONDITIONS**

Parameter	Range	Unit
VIN	2.2 to 5.5	V
SW pin voltage	0 to 24	V
Ambient Temperature Range	-40 to +85	°C
LED Bias Current	1 to 30	mA

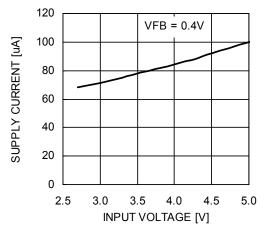
## **ELECTRICAL OPERATING CHARACTERISTICS**

 $V_{IN}$  = 3.6V, ambient temperature of 25°C (over recommended operating conditions unless specified otherwise)

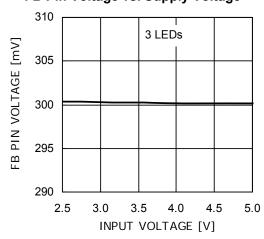
Symbol	Parameter	Conditions	Min	Тур	Max	Unit
IQ	Operating Current	$V_{FB} = 0.3V$ $V_{FB} = 0.4V$ (not switching)		0.4 0.1	1.5 0.3	mA
$I_{SD}$	Shutdown Current	V <sub>SHDN</sub> = 0V		0.1	1	μΑ
$V_{FB}$	FB Pin Voltage	3 LEDs with I <sub>LED</sub> =20mA	285	300	315	mV
I <sub>FB</sub>	FB pin input leakage			0.1	1	μΑ
I <sub>LED</sub>	Programmed LED Current	R1 = 10Ω R1 = 15Ω R1 = 20Ω	28.5 19 14.25	30 20 15	31.5 21 15.75	mA
V <sub>IH</sub> V <sub>IL</sub>	SHDN Logic High SHDN Logic Low	Enable Threshold Level Shutdown Threshold Level	0.4	0.8 0.7	1.5	
F <sub>sw</sub>	Switching Frequency		0.7	1	1.3	MHz
I <sub>LIM</sub>	Switch Current Limit		250	300	400	mA
R <sub>SW</sub>	Switch "On" Resistance	I <sub>SW</sub> = 100mA		1.0	2.0	Ω
I <sub>LEAK</sub>	Switch Leakage Current	Switch Off, V <sub>SW</sub> = 5V		1	5	μΑ
T <sub>SD</sub>	Thermal Shutdown			150		°C
T <sub>HYS</sub>	Thermal Hysteresis			20		°C
η	Efficiency	Typical Application Circuit		86		%
V <sub>UVLO</sub>	Under-voltage lock out (UVLO) threshold			1.9		V
$V_{\text{OV-SW}}$	Output Clamp Voltage	"Open LED" fault		29		V

 $V_{IN}$  = 3.6V,  $C_{IN}$  = 1.0uF,  $C_{OUT}$  = 0.22 $\mu$ F, L = 22 $\mu$ H with 3 LEDs at 20mA,  $T_{AMB}$ =25°C, unless otherwise specified.

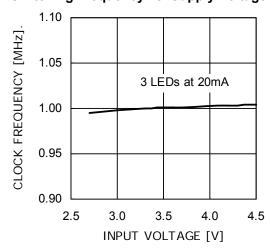
# **Quiescent Current vs. VIN (Not Switching)**



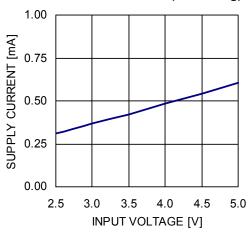
## FB Pin Voltage vs. Supply Voltage



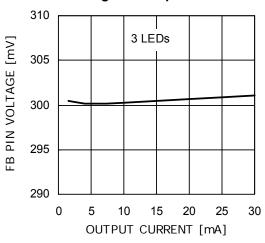
## Switching Frequency vs. Supply Voltage



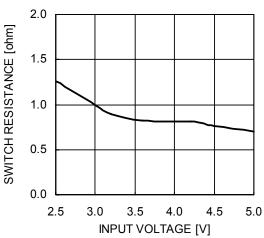
## **Quiescent Current vs. VIN (Switching)**



## FB Pin Voltage vs. Output Current

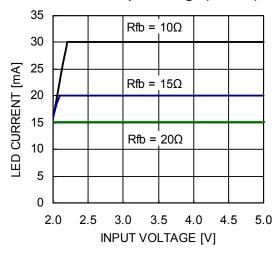


# Switch ON Resistance vs. Input Voltage

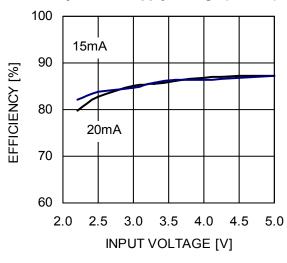


 $V_{IN}$  = 3.6V,  $C_{IN}$  = 1.0uF,  $C_{OUT}$  = 0.22 $\mu$ F, L = 22 $\mu$ H, with 3 LEDs at 20mA,  $T_{AMB}$ =25°C, unless otherwise specified.

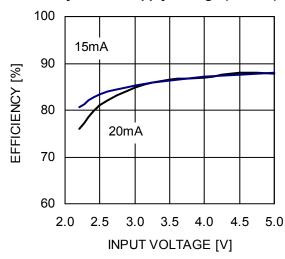
## LED Current vs. Input Voltage (3 LEDs)



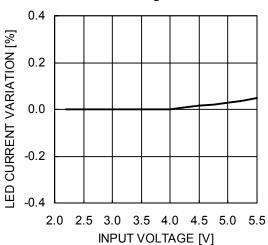
## Efficiency across Supply Voltage (3 LEDs)



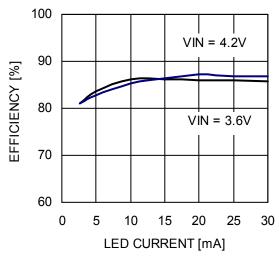
## Efficiency across Supply Voltage (4 LEDs)



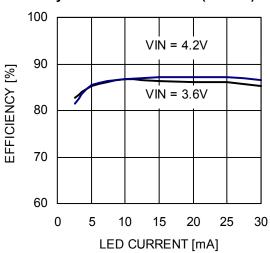
# **LED Current Regulation**



# Efficiency across Load Current (3 LEDs)

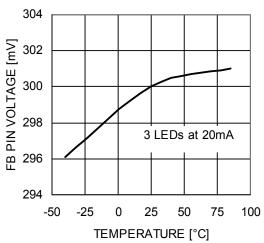


## **Efficiency across Load Current (4 LEDs)**

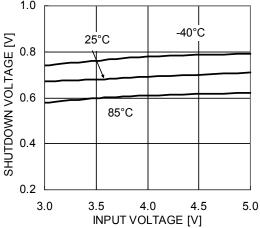


 $V_{IN}$  = 3.6V,  $C_{IN}$  = 1.0uF,  $C_{OUT}$  = 0.22 $\mu$ F, L = 22 $\mu$ H, with 3 LEDs at 20mA,  $T_{AMB}$ =25°C, unless otherwise specified.

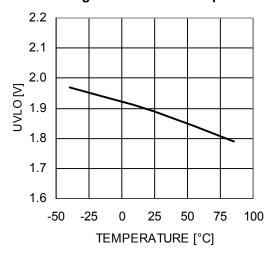
# FB Pin Voltage vs. Temperature



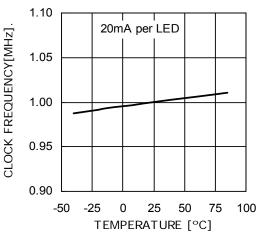
# Shutdown Voltage vs. Input Voltage



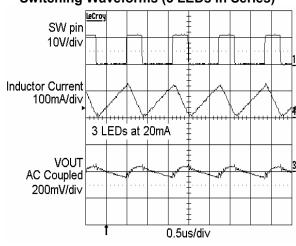
## **Under Voltage Lock Out vs. Temperature**



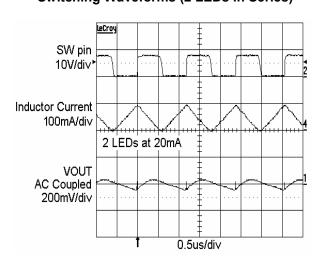
# **Switching Frequency vs. Temperature**



## **Switching Waveforms (3 LEDs in Series)**

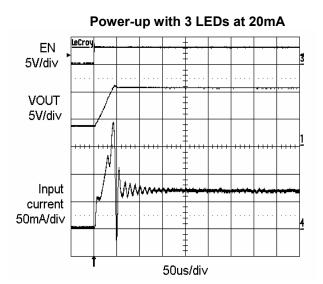


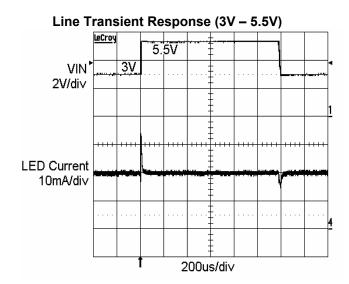
## **Switching Waveforms (2 LEDs in Series)**



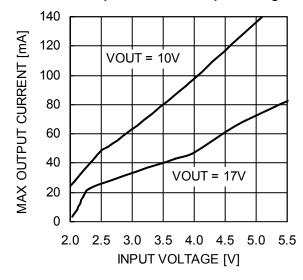
 $V_{IN}$  = 3.6V,  $C_{IN}$  = 1.0uF,  $C_{OUT}$  = 0.22 $\mu$ F, L = 22 $\mu$ H, with 3 LEDs at 20mA,  $T_{AMB}$ =25°C, unless otherwise specified.

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## Maximum Output Current vs. Input Voltage



## PIN DESCRIPTION

VIN is the supply input for the internal logic. The device is compatible with supply voltages down to 2.2V and up to 5.5V. A small bypass ceramic capacitor of 1μF is recommended between the VIN and GND pins near the device. The under-voltage lockout (UVLO) circuitry will place the device into an idle mode (not switching) whenever the supply falls below 1.9V.

**SHDN** is the shutdown logic input. When the pin voltage is taken below 0.4V, the device immediately enters shutdown mode, drawing nearly zero current. At voltages greater than 1.5V, the device becomes fully enabled and operational.

**GND** is the ground reference pin. This pin should be connected directly to the ground plane on the PCB.

**SW** pin is the drain terminal of the internal low resistance power switch. The inductor and the Schottky diode anode should be connected to the SW pin. Traces going to the SW pin should be as short as possible with minimum loop area. This pin contains over-voltage circuitry which becomes active above 24V. In the event of an "Open-Led" fault condition, the device will enter a low power mode and the SW pin will be clamped to approximately 30V.

**FB** feedback pin is regulated at 0.3V. A resistor connected between the FB pin and ground sets the LED current according to the formula:

$$I_{LED} = 0.3V/R1$$

The lower LED cathode is connected to the FB pin.

Pin#	Name	Function
1	SW	Switch pin. This is the drain of the internal power switch.
2	GND	Ground pin. Connect the pin to the ground plane.
3	FB	Feedback pin. Connect to the last LED cathode.
4	SHDN	Shutdown pin (Logic Low). Set high to enable the driver.
5	VIN	Power Supply input.

#### **DEVICE OPERATION**

The CAT4137 is a fixed frequency (1MHz), low noise, inductive boost converter providing constant current to the load. A high voltage internal CMOS power switch is used to energize the external inductor. When the power switch is then turned off, the stored energy inductor is released into the load via the external Schottky diode.

The on/off duty cycle of the power switch is internally adjusted and controlled to maintain a constant regulated voltage of 0.3V across the external feedback resistor connected to the feedback pin (FB). The value of external resistor will accurately set the LED bias current accordingly (0.3V/R1).

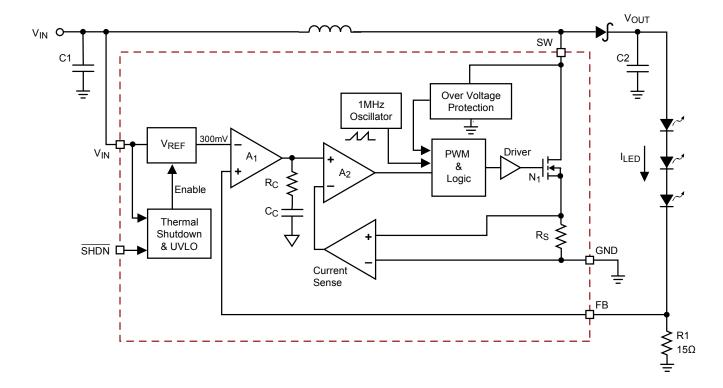
During the initial power-up stage, the duty cycle of the internal power switch is limited to prevent excessive in-rush currents and thereby provide a "soft-start" mode of operation.

While in normal operation, the device will comfortably deliver up to 30mA of bias current into a string of up to 5 white LEDs.

In the event of a "Open-Led" fault condition, where the feedback control loop becomes open, the output voltage will continue to increase. Once this voltage exceeds 24V, an internal protection circuit will become active and place the device into a very low power safe operating mode. In addition, an internal clamping circuit will limit the peak output voltage to 29V. If this fault condition is repaired, the device will automatically resume normal operation.

Thermal overload protection circuitry has been included to prevent the device from operating at unsafe junction temperatures above 150°C. In the event of a thermal overload condition the device will automatically shutdown and wait till the junction temperatures cools to 130°C before normal operation is resumed.

#### **BLOCK DIAGRAM**



## **APPLICATION INFORMATION**

#### **EXTERNAL COMPONENT SELECTION**

#### **Capacitors**

The CAT4137 only requires small ceramic capacitors of 1uF on the input and  $0.22\mu F$  on the output. The output capacitor should be rated at 30V or greater. Under normal conditions, a  $1\mu F$  input capacitor is sufficient. For applications with higher output power, a larger input capacitor of  $2.2\mu F$  or  $4.7\mu F$  may be appropriate. X5R and X7R capacitor types are ideal due to their stability across temperature range.

#### Inductor

A 22µH inductor is recommended for most of the CAT4137 applications. In cases where the efficiency is critical, inductances with lower series resistance are preferred. Several inductor types from various vendors can be used. Figure 1 shows how different inductor types affect the efficiency across the load range.

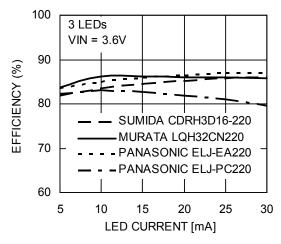


Figure 1. Efficiency for various inductors

#### **Schottky Diode**

The current rating of the Schottky diode must exceed the peak current flowing through it. The Schottky diode performance is rated in terms of its forward voltage at a given current. In order to achieve the best efficiency, this forward voltage should be as low as possible. The response time is also critical since the driver is operating at 1MHz. Central Semiconductor Schottky CMDSH2-3 (200mA rated) or the CMDSH-3 (100mA rated) is recommended for most applications.

## **LED Current Setting**

The LED current is set by the external resistor between the feedback pin (FB) and ground. The formula below gives the relationship between the resistor and the current:

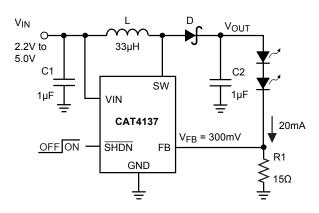
R1 = 0.3V/LED current

LED current (mA)	R1 (Ω)
5	60
10	30
15	20
20	15
25	12
30	10

Table 1. Resistor R1 and LED current

## **TYPICAL APPLICATIONS**

## **CAT4137 Driving Two LEDs**

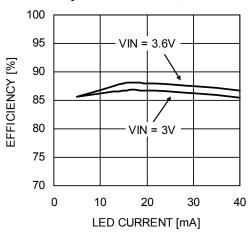


- L: Sumida CDRH3D16-330
- D: Central CMDSH2-3 (rated 30V)
- C2: Taiyo Yuden GMK212BJ105KG-T (rated 35V)

For best performance, a  $33\mu H$  inductor and a  $1\mu F$  output capacitor are recommended for 2-LED applications.

In 2-LED configuration, the CAT4137 can be powered from two AA alkaline cells or from a Li-ion battery.

## Efficiency vs. LED Current, Two LEDs



#### **DIMMING CONTROL**

There are several methods available to control the LED brightness.

## 1. PWM signal on the SHDN pin

LED brightness dimming can be done by applying a PWM signal to the SHDN input. The LED current is repetitively turned on and off, so that the average current is proportional to the duty cycle. A 100% duty cycle, with SHDN always high, corresponds to the LEDs at nominal current. Figures 2 and 3 show 1kHz and 4kHz signals with a 50% duty cycle applied to the SHDN pin. The PWM frequency range is from 100Hz to 10kHz. The recommended PWM frequency range is from 100Hz to 4kHz.

## Switching waveforms PWM on SHDN

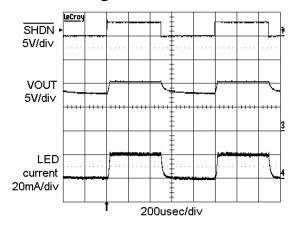


Figure 2. PWM at 1kHz

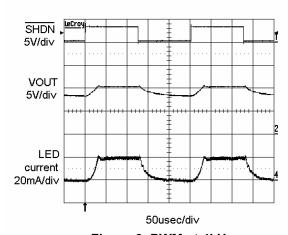


Figure 3. PWM at 4kHz

## 2. Filtered PWM signal

A filtered PWM signal can be used as a variable DC voltage that can be used to control the LED current. Figure 4 shows the PWM control circuitry connected to the CAT4137 FB pin. The PWM signal has a voltage swing of 0V to 2.5V. The LED current can be dimmed within a range from 0 to 22mA. The PWM signal frequency can vary from very low frequency up to 100kHz.

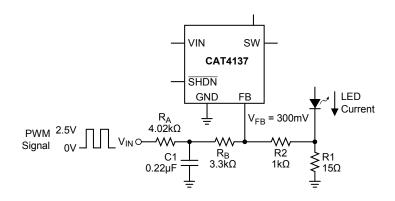
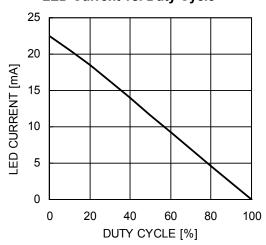


Figure 4. Circuit for filtered PWM signal

A PWM signal at 0V DC, or a 0% duty cycle, results in a max LED current of about 22mA. A PWM signal with a 100% duty cycle results in an LED current of 0mA.

#### **LED Current vs. Duty Cycle**

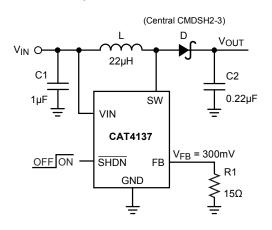


#### **OPEN LED PROTECTION**

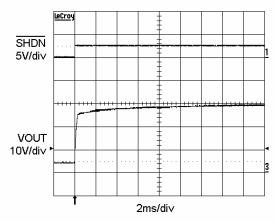
In the event of an "Open LED" fault condition, the CAT4137 will continue to boost the output voltage with maximum power until the output voltage reaches approximately 24V. Once the output exceeds this level, internal circuitry immediately places the device into a very low power mode where the total input power consumed is less than 10mW.

In low power mode, the input supply current will typically drop to 2mA. An internal clamping circuit will limit the subsequent output voltage to approximately 29V. This operating mode eliminates the need for any external protection zener diode. This protection scheme also fully protects the device against any malfunction in the external Schottky diode (opencircuit).

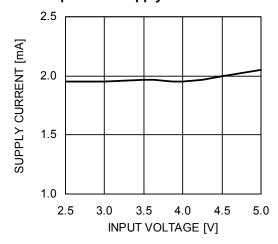
## **Open LED Protection**



## **Open LED Power-up Waveforms**



#### **Open LED Supply Current vs. VIN**



## **BOARD LAYOUT**

The CAT4137 is a high-frequency switching regulator. Traces carrying high-frequency switching current have to be carefully layout on the board in order to minimize EMI, ripple and noise in general. The thicker lines shown on Figure 4 indicate the switching current path. All these traces have to be short and wide enough to minimize the parasitic inductance and resistance. The loop shown on Figure 4 corresponds to the current path when the CAT4137 internal switch is closed. On Figure 5 is shown the current loop when the CAT4137 switch is open. Both loop areas should be as small as possible.

Capacitor C1 has to be placed as close as possible to the VIN pin and GND. The capacitor C2 has to be connected separately to the top LED anode. A ground plane under the CAT4137 allows for direct connection of the capacitors to ground. The resistor R1 must be connected directly to the GND pin of the CAT4137 and not shared with the switching current loops and any other components.

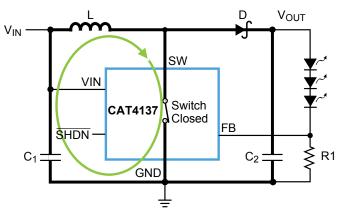


Figure 4. Closed-switch current loop

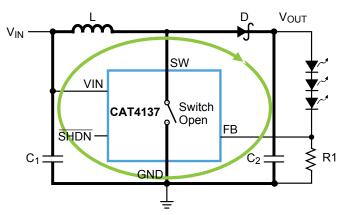
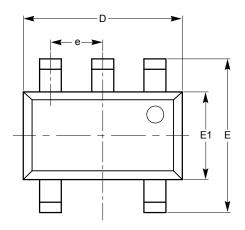


Figure 5. Open-switch current loop

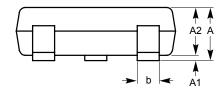
# **PACKAGE OUTLINE DRAWING**

TSOT-23 5-Lead (TD) (1)(2)

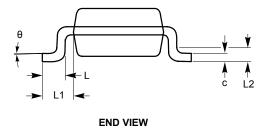


**TOP VIEW** 

SYMBOL	MIN	NOM	MAX
Α			1.00
A1	0.01	0.05	0.10
A2	0.80	0.87	0.90
b	0.30		0.45
С	0.12	0.15	0.20
D	2.90 BSC		
Е	2.80 BSC		
E1	1.60 BSC		
е	0.95 TYP		
L	0.30	0.40	0.50
L1	0.60 REF		
L2	0.25 BSC		
θ	0°		8°



SIDE VIEW

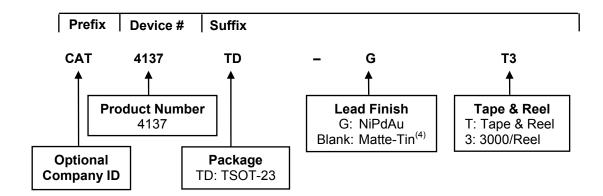


For current Tape and Reel information, download the PDF file from: http://www.catsemi.com/documents/tapeandreel.pdf.

#### Notes:

- (1) All dimensions are in millimeters. Angles in degrees.
- (2) Complies with JEDEC standard MO-193.

## **EXAMPLE OF ORDERING INFORMATION**



#### Notes:

- (1) All packages are RoHS-compliant (Lead-free, Halogen-free).
- (2) The standard lead finish is NiPdAu.
- (3) The device used in the above example is a CAT4137TD-GT3 (TSOT-23, NiPdAu Plated Finish, Tape & Reel 3000).
- (4) For Matte-Tin package option, please contact your nearest ON Semiconductor Sales office.

#### **REVISION HISTORY**

Date	Rev.	Reason
13-Dec-05	00	Initial Issue
11-Jan-08	В	Add NiPdAu lead finish Add Extended Temperature range Update Package Outline Drawing Add Example of Ordering Information Change Document Number from 25093, Rev. 00 to MD-5016, Rev. B
17-Nov-08	С	Change logo and fine print to ON Semiconductor

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