



## QUAD DIFFERENTIAL PECL RECEIVERS

### FEATURES

- Functional Replacement for the Agere BRF1A
- Pin Equivalent to General Trade 26LS32
- High Input Impedance Approximately 8 kΩ
- <2.6-ns Maximum Propagation Delay
- TB5R3 Provides 50-mV Hysteresis (Typical)
- -1.1-V to 7.1-V Common-Mode Input Voltage Range
- Single 5-V ±10% Supply
- ESD Protection HBM > 3 kV and CDM > 2 kV
- Operating Temperature Range: -40°C to 85°C
- Available in Gull-Wing SOIC (JEDEC MS-013, DW) and SOIC (D) Package

### APPLICATIONS

- Digital Data or Clock Transmission Over Balanced Lines

### DESCRIPTION

These quad differential receivers accept digital data over balanced transmission lines. They translate differential input logic levels to TTL output logic levels.

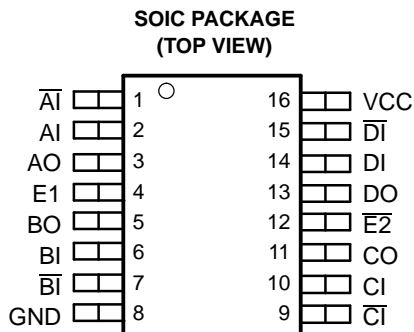
The TB5R3 is a pin- and function-compatible replacement for the Agere systems BRF1A; it includes 3-kV HBM and 2-kV CDM ESD protection.

The power-down loading characteristics of the receiver input circuit are approximately 8 kΩ relative to the power supplies; hence they do not load the transmission line when the circuit is powered down.

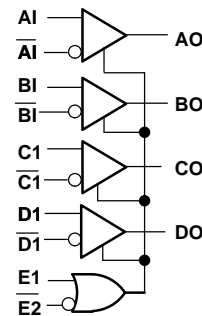
The packaging for this differential line receiver is a 16-pin gull wing SOIC (DW) or a 16 pin SOIC (D).

The enable inputs of this device include internal pull-up resistors of approximately 40 kΩ that are connected to V<sub>CC</sub> to ensure a logical high level input if the inputs are open circuited.

### PIN ASSIGNMENTS



### FUNCTIONAL BLOCK DIAGRAM



### Enable Truth Table

E1	$\overline{E2}$	OUTPUT CONDITION
0	0	Active
1	0	Active
0	1	Disabled
1	1	Active



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

### ORDERING INFORMATION

PART NUMBER <sup>(1)</sup>	PART MARKING	Package	LEAD FINISH	STATUS
TB5R3DW	TB5R3	Gull-Wing SOIC	NiPdAu	Production
TB5R3LDW	TB5R3L	Gull-Wing SOIC	SnPb	Production
TB5R3D	TB5R3	SOIC	NiPdAu	Production
TB5R3LD	TB5R3L	SOIC	SnPb	Production

(1) Add the R suffix for tape and reel carrier (i.e., TB5R3DR)

### POWER DISSIPATION RATINGS

PACKAGE	CIRCUIT BOARD MODEL	POWER RATING $T_A \leq 25^\circ\text{C}$	THERMAL RESISTANCE, JUNCTION-TO-AMBIENT WITH NO AIR FLOW	DERATING FAC- TOR <sup>(1)</sup> $T_A \geq 25^\circ\text{C}$	POWER RATING $T_A = 85^\circ\text{C}$
DW	Low-K <sup>(2)</sup>	831 mW	120.3°C/W	8.3 mW/°C	332 mW
	High-K <sup>(3)</sup>	1240 mW	80.8°C/W	12.4 mW/°C	494 mW
D	Low-K <sup>(2)</sup>	763 mW	131.1°C/W	7.6 mW/°C	305 mW
	High-K <sup>(3)</sup>	1190 mW	84.1 °C/W	11.9 mW/°C	475 mW

(1) This is the inverse of the junction-to-ambient thermal resistance when board-mounted with no air flow.

(2) In accordance with the low-K thermal metric definitions of EIA/JESD51-3.

(3) In accordance with the high-K thermal metric definitions of EIA/JESD51-7.

### THERMAL CHARACTERISTICS

PARAMETER	PACKAGE	VALUE	UNIT
$\theta_{JB}$	DW	53.7	°C/W
	D	47.5	
$\theta_{JC}$	DW	47.1	°C/W
	D	44.2	

### ABSOLUTE MAXIMUM RATINGS

over operating free-air temperature range unless otherwise noted<sup>(1)</sup>

	UNIT		
Supply voltage, $V_{CC}$	0 V to 6 V		
Magnitude of differential bus (input) voltage, $ V_{A1} - V_{A1} $ , $ V_{B1} - V_{B1} $ , $ V_{C1} - V_{C1} $ , $ V_{D1} - V_{D1} $	8.4 V		
ESD	Human Body Model <sup>(2)</sup>	All pins	±3.5 kV
	Charged-Device Model <sup>(3)</sup>	All pins	±2 kV
Continuous power dissipation	See Dissipation Rating Table		
Storage temperature, $T_{stg}$	-65°C to 150°C		

(1) Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) Tested in accordance with JEDEC Standard 22, Test Method A114-A.

(3) Tested in accordance with JEDEC Standard 22, Test Method C101.

## RECOMMENDED OPERATING CONDITIONS

	MIN	NOM	MAX	UNIT
Supply voltage, $V_{CC}$	4.5	5	5.5	V
Bus pin input voltage, $V_{AI}$ , $V_{\overline{AI}}$ , $V_{BI}$ , $V_{\overline{BI}}$ , $V_{CI}$ , or $V_{\overline{CI}}$ , $V_{DI}$ , $V_{\overline{DI}}$	-1.2 <sup>(1)</sup>		7.2	V
Magnitude of differential input voltage, $ V_{AI} - V_{\overline{AI}} $ , $ V_{BI} - V_{\overline{BI}} $ , $ V_{CI} - V_{\overline{CI}} $ , $ V_{DI} - V_{\overline{DI}} $	0.1		6	V
Low-level enable input voltage <sup>(2)</sup> , $V_{IL}$ ( $V_{CC} = 5.5$ V)			0.8	V
High-level enable input voltage <sup>(2)</sup> , $V_{IH}$ ( $V_{CC} = 5.5$ V)	2			V
Operating free-air temperature, $T_A$	-40		85	°C

- (1) The algebraic convention, in which the least positive (most negative) limit is designated as minimum is used in this data sheet, unless otherwise noted.
- (2) The input levels and difference voltage provide no noise immunity and should be tested only in a static, noise-free environment.

## DEVICE ELECTRICAL CHARACTERISTICS

over operating free-air temperature range unless otherwise noted

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$I_{CC}$	Supply current <sup>(1)</sup>	Outputs disabled			50	mA
		Outputs enabled			48	mA

- (1) Current is dc power draw as measured through GND pin and does not include power delivered to load.

## RECEIVER ELECTRICAL CHARACTERISTICS

over operating free-air temperature range unless otherwise noted

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT	
$V_{OL}$	Output low voltage	$V_{CC} = 4.5$ V, $I_{OL} = 8$ mA			0.4	V	
$V_{OH}$	Output high voltage	$V_{CC} = 4.5$ V, $I_{OH} = -400$ $\mu$ A	2.4			V	
$V_{IK}$	Enable input clamp voltage	$V_{CC} = 4.5$ V, $I_I = -5$ mA			-1 <sup>(1)</sup>	V	
$V_{TH+}$	Positive-going differential input threshold voltage <sup>(2)</sup> , ( $V_{xI} - V_{\overline{xI}}$ )	x = A, B, C, or D			100	mV	
$V_{TH-}$	Negative-going differential input threshold voltage <sup>(2)</sup> , ( $V_{xI} - V_{\overline{xI}}$ )	x = A, B, C, or D			100 <sup>(1)</sup>	mV	
$V_{HYST}$	Differential input threshold voltage hysteresis, ( $V_{TH+} - V_{TH-}$ )			50		mV	
$I_{OZL}$	Output off-state current, (High-Z)	$V_{CC} = 5.5$ V			$V_O = 0.4$ V	-20 <sup>(1)</sup>	$\mu$ A
$I_{OZH}$					$V_O = 2.4$ V	20	$\mu$ A
$I_{OS}$	Output short circuit current	$V_{CC} = 5.5$ V			400 <sup>(1)</sup>	mA	
$I_{IL}$	Enable input low current	$V_{CC} = 5.5$ V, $V_{IN} = 0.4$ V			400 <sup>(1)</sup>	$\mu$ A	
$I_{IH}$	Enable input high current	$V_{CC} = 5.5$ V			$V_{IN} = 2.7$ V	20	$\mu$ A
	Enable input reverse current				$V_{IN} = 5.5$ V	100	$\mu$ A
$I_{IL}$	Differential input low current	$V_{CC} = 5.5$ V, $V_{IN} = -1.2$ V			-2 <sup>(1)</sup>	mA	
$I_{IH}$	Differential input high current	$V_{CC} = 5.5$ V, $V_{IN} = 7.2$ V			1	mA	
$R_O$	Small-signal output resistance	Output High		50		$\Omega$	
		Output Low		25			

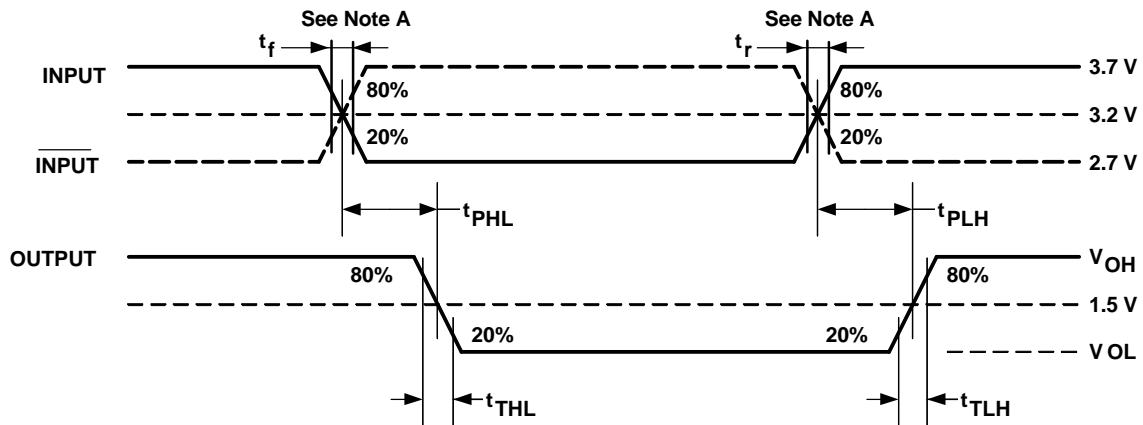
- (1) This parameter is listed using a magnitude and polarity/direction convention, rather than an algebraic convention, to match the original Agere data sheet.
- (2) The input levels and difference voltage provide no noise immunity and should be tested only in a static, noise-free environment.

### SWITCHING CHARACTERISTICS

over operating free-air temperature range unless otherwise noted

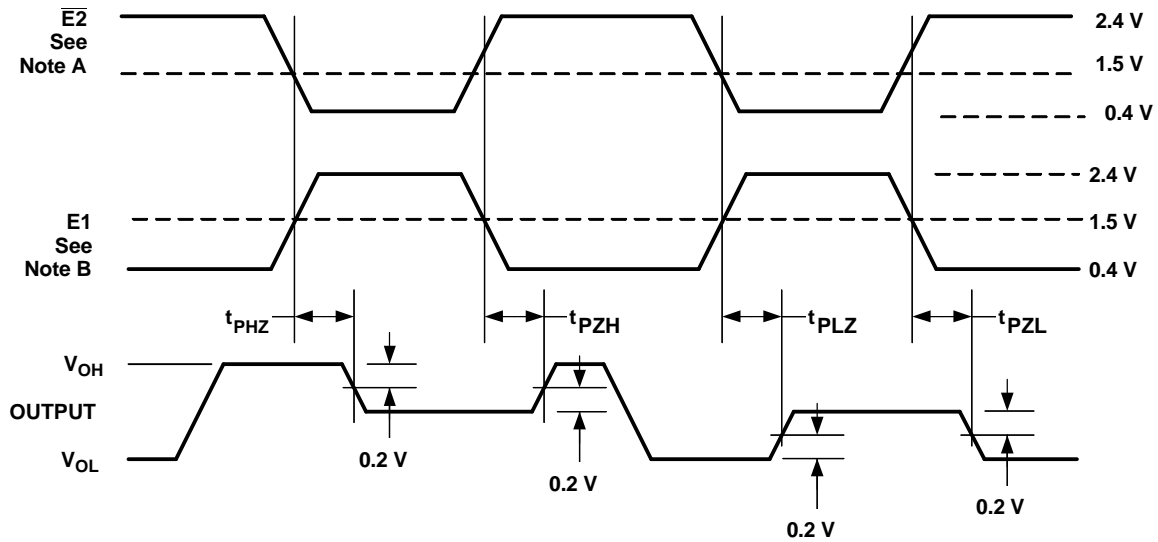
PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$t_{PLH}$	Propagation delay time, low-to-high-level output	$C_L = 0 \text{ pF}^{(1)}$ , See Figure 2 and Figure 4		1.64	<2.6	ns
$t_{PHL}$	Propagation delay time, high-to-low-level output			1.57	<2.6	
$t_{PLH}$	Propagation delay time, low-to-high-level output	$C_L = 50 \text{ pF}$ , See Figure 2 and Figure 4 <sup>(2)</sup>		2.2	3.5	ns
$t_{PHL}$	Propagation delay time, high-to-low-level output			2.1	3.5	
$t_{PHZ}$	Output disable time, high-level-to-high-impedance output <sup>(3)</sup>	$C_L = 5 \text{ pF}$ , See Figure 3 and Figure 5		7.7	12	ns
$t_{PLZ}$	Output disable time, low-level-to-high-impedance output <sup>(3)</sup>			5.2	12	
$t_{skew1}$	Pulse-width distortion, $ t_{PHL} - t_{PLH} $	$C_L = 10 \text{ pF}$ , See Figure 2 and Figure 4			0.7	ns
		$C_L = 150 \text{ pF}$ , See Figure 2 and Figure 4			4	ns
$\Delta t_{skew1p-p}$	Part-to-part output waveform skew	$C_L = 10 \text{ pF}$ , $T_A = 75^\circ\text{C}$ , See Figure 2 and Figure 4		0.8	1.4	ns
		$C_L = 10 \text{ pF}$ , See Figure 2 and Figure 4			1.5	ns
$\Delta t_{skew}$	Same part output waveform skew	$C_L = 10 \text{ pF}$ , See Figure 2 and Figure 4			0.3	ns
$t_{PZH}$	Output enable time, high-impedance-to-high-level output <sup>(3)</sup>	$C_L = 10 \text{ pF}$ , See Figure 3 and Figure 4		6.9	12	ns
$t_{PZL}$	Output enable time, high-impedance-to-low-level output <sup>(3)</sup>			6.3	12	
$t_{TLH}$	Rise time (20%-80%)	$C_L = 10 \text{ pF}$ , See Figure 2 and Figure 4			1	ns
$t_{THL}$	Fall time (80%-20%)				1	

- (1) The propagation delay values with a 0 pF load are based on design and simulation.
- (2)  $t_r/t_f$ : 3 ns (20% - 80%)
- (3) See Table 1.



A.  $t_r/t_f$ : 3 ns (20% - 80%)

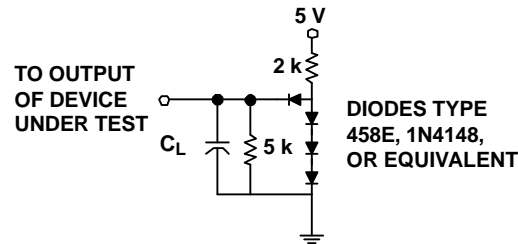
Figure 1. Receiver Propagation Delay Times



- A.  $\overline{E2} = 1$  while E1 changes states.
- B. E1 = 0 while  $\overline{E2}$  changes states.

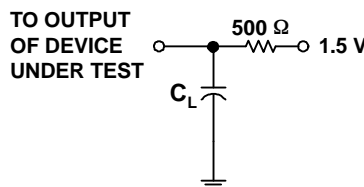
**Figure 2. Receiver Enable and Disable Timing**

Parametric values specified under the Electrical Characteristics and Timing Characteristics sections for the data transmission driver devices are measured with the following output load circuits.



$C_L$  includes test-fixture and probe capacitance.

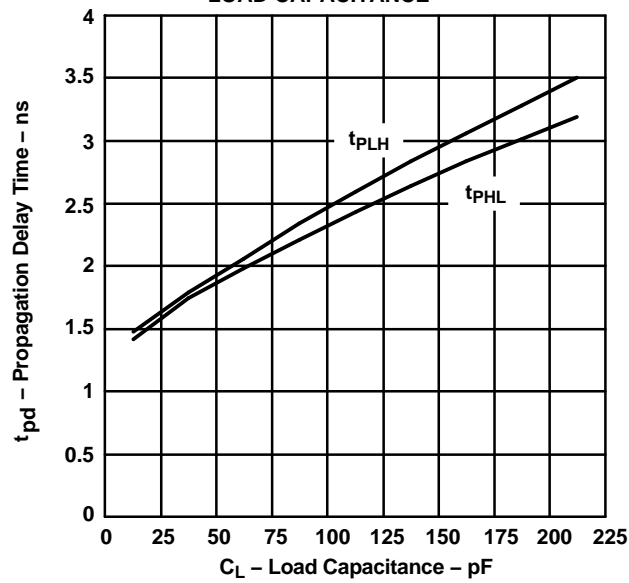
**Figure 3. Receiver Propagation Delay Time and Enable Time ( $t_{PZH}$ ,  $t_{PZL}$ ) Test Circuit**



$C_L$  includes test-fixture and probe capacitance.

**Figure 4. Receiver Disable Time ( $t_{PHZ}$ ,  $t_{PLZ}$ ) Test Circuit**

**TYPICAL CHARACTERISTICS**  
TYPICAL PROPAGATION DELAY  
vs  
LOAD CAPACITANCE



NOTE: This graph is included as an aid to the system designers. Total circuit delay varies with load capacitance. The total delay is the sum of the delay due to external capacitance and the intrinsic delay of the device. Intrinsic delay is listed in the table above as the 0 pF load condition. The incremental increase in delay between the 0 pF load condition and the actual total load capacitance represents the extrinsic, or external delay contributed by the load.

Figure 5.

**TYPICAL CHARACTERISTICS (continued)**

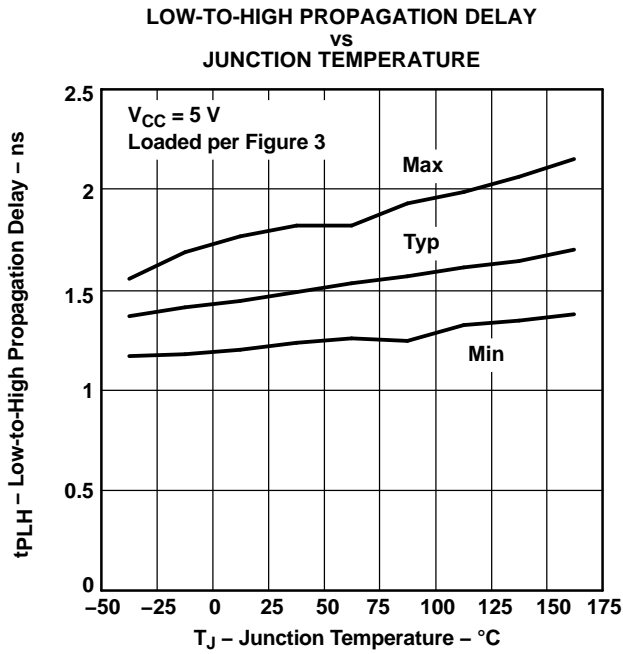


Figure 6.

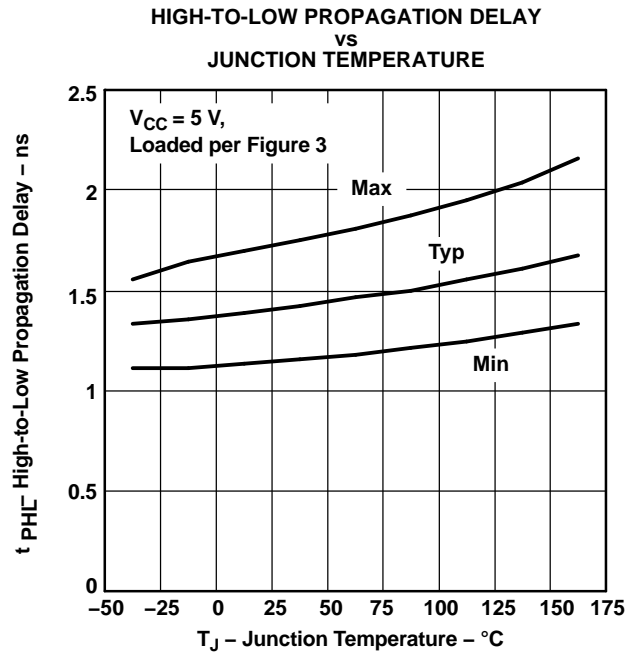


Figure 7.

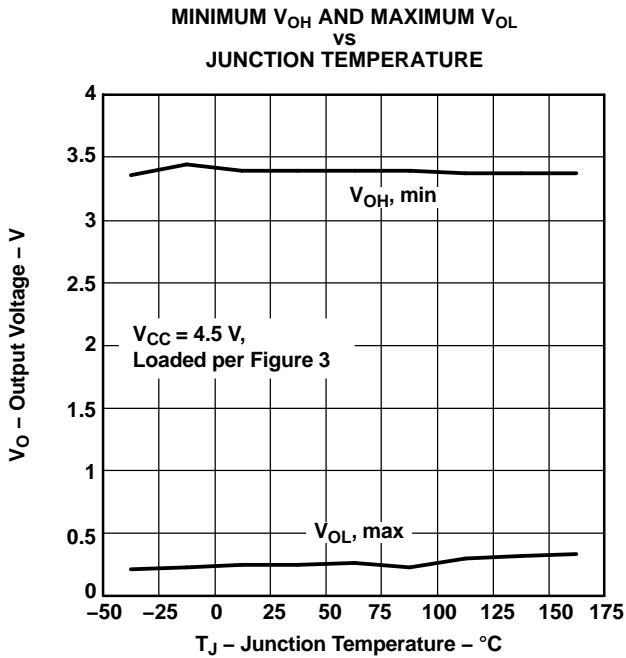


Figure 8.

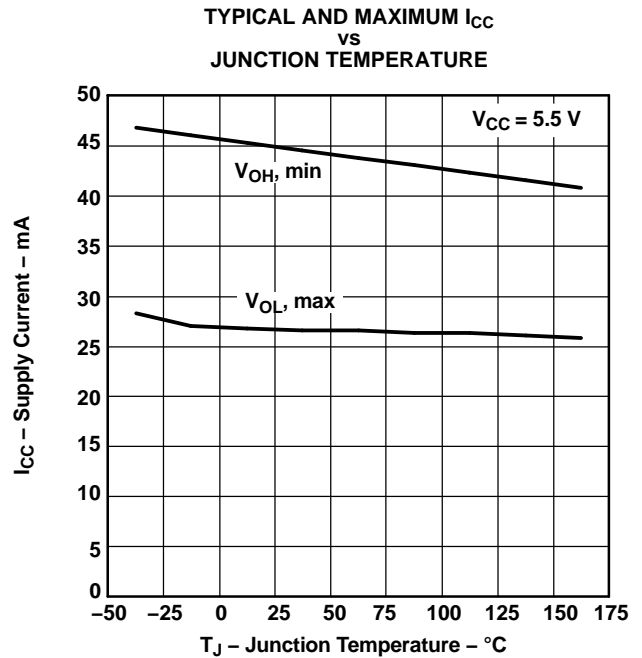


Figure 9.

## APPLICATION INFORMATION

### Power Dissipation

The power dissipation rating, often listed as the package dissipation rating, is a function of the ambient temperature,  $T_A$ , and the airflow around the device. This rating correlates with the device's maximum junction temperature, sometimes listed in the absolute maximum ratings tables. The maximum junction temperature accounts for the processes and materials used to fabricate and package the device, in addition to the desired life expectancy.

There are two common approaches to estimating the internal die junction temperature,  $T_J$ . In both of these methods, the device internal power dissipation  $P_D$  needs to be calculated. This is done by totaling the supply power(s) to arrive at the system power dissipation:

$$\sum (V_{Sn} \times I_{Sn}) \quad (1)$$

and then subtracting the total power dissipation of the external load(s):

$$\sum (V_{Ln} \times I_{Ln}) \quad (2)$$

The first  $T_J$  calculation uses the power dissipation and ambient temperature, along with one parameter:  $\theta_{JA}$ , the junction-to-ambient thermal resistance, in degrees Celsius per watt.

The product of  $P_D$  and  $\theta_{JA}$  is the junction temperature rise above the ambient temperature. Therefore:

$$T_J = T_A + (P_D \times \theta_{JA}) \quad (3)$$

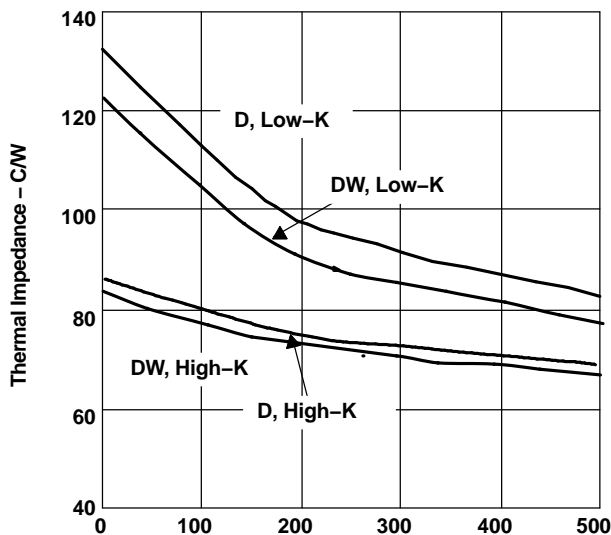


Figure 10. Thermal Impedance vs Air Flow

Note that  $\theta_{JA}$  is highly dependent on the PCB on

which the device is mounted and on the airflow over the device and PCB. JEDEC/EIA has defined standardized test conditions for measuring  $\theta_{JA}$ . Two commonly used conditions are the low-K and the high-K boards, covered by EIA/JESD51-3 and EIA/JESD51-7 respectively. Figure 10 shows the low-K and high-K values of  $\theta_{JA}$  versus air flow for this device and its package options.

The standardized  $\theta_{JA}$  values may not accurately represent the conditions under which the device is used. This can be due to adjacent devices acting as heat sources or heat sinks, to nonuniform airflow, or to the system PCB having significantly different thermal characteristics than the standardized test PCBs. The second method of system thermal analysis is more accurate. This calculation uses the power dissipation and ambient temperature, along with two device and two system-level parameters:

- $\theta_{JC}$ , the junction-to-case thermal resistance, in degrees Celsius per watt
- $\theta_{JB}$ , the junction-to-board thermal resistance, in degrees Celsius per watt
- $\theta_{CA}$ , the case-to-ambient thermal resistance, in degrees Celsius per watt
- $\theta_{BA}$ , the board-to-ambient thermal resistance, in degrees Celsius per watt.

In this analysis, there are two parallel paths, one through the case (package) to the ambient, and another through the device to the PCB to the ambient. The system-level junction-to-ambient thermal impedance,  $\theta_{JA(S)}$ , is the equivalent parallel impedance of the two parallel paths:

$$T_J = T_A + (P_D \times \theta_{JA(S)}) \quad (4)$$

where

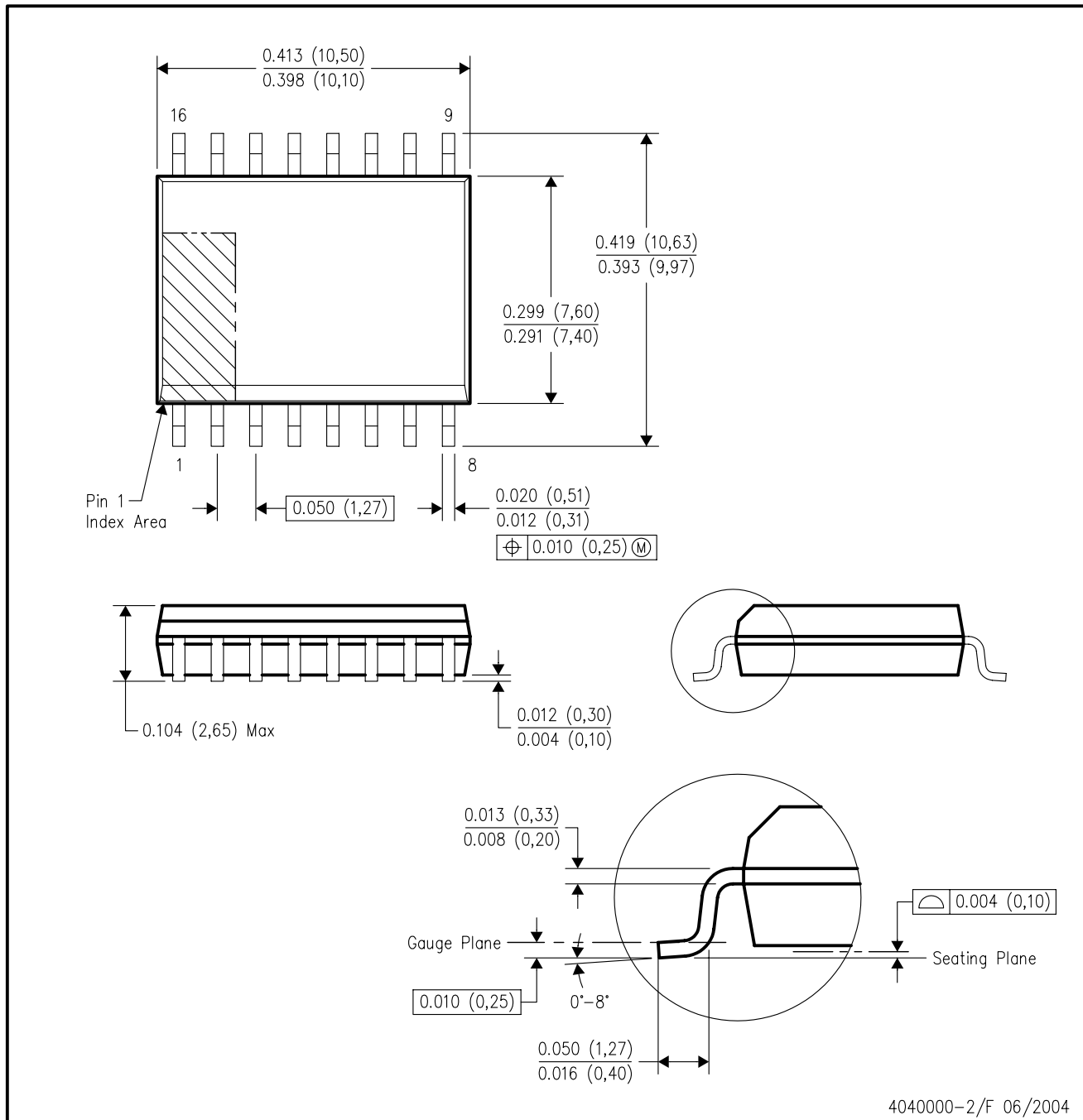
$$\theta_{JA(S)} = \frac{[(\theta_{JC} + \theta_{CA}) \times (\theta_{JB} + \theta_{BA})]}{(\theta_{JC} + \theta_{CA} + \theta_{JB} + \theta_{BA})} \quad (5)$$

The device parameters  $\theta_{JC}$  and  $\theta_{JB}$  account for the internal structure of the device. The system-level parameters  $\theta_{CA}$  and  $\theta_{BA}$  take into account details of the PCB construction, adjacent electrical and mechanical components, and the environmental conditions including airflow. Finite element (FE), finite difference (FD), or computational fluid dynamics (CFD) programs can determine  $\theta_{CA}$  and  $\theta_{BA}$ . Details on using these programs are beyond the scope of this data sheet, but are available from the software manufacturers.



DW (R-PDSO-G16)

PLASTIC SMALL-OUTLINE PACKAGE



4040000-2/F 06/2004

- NOTES:
- A. All linear dimensions are in inches (millimeters).
  - B. This drawing is subject to change without notice.
  - C. Body dimensions do not include mold flash or protrusion not to exceed 0.006 (0,15).
  - D. Falls within JEDEC MS-013 variation AA.

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DSP	<a href="http://dsp.ti.com">dsp.ti.com</a>	Broadband	<a href="http://www.ti.com/broadband">www.ti.com/broadband</a>
Interface	<a href="http://interface.ti.com">interface.ti.com</a>	Digital Control	<a href="http://www.ti.com/digitalcontrol">www.ti.com/digitalcontrol</a>
Logic	<a href="http://logic.ti.com">logic.ti.com</a>	Military	<a href="http://www.ti.com/military">www.ti.com/military</a>
Power Mgmt	<a href="http://power.ti.com">power.ti.com</a>	Optical Networking	<a href="http://www.ti.com/opticalnetwork">www.ti.com/opticalnetwork</a>
Microcontrollers	<a href="http://microcontroller.ti.com">microcontroller.ti.com</a>	Security	<a href="http://www.ti.com/security">www.ti.com/security</a>
Low Power Wireless	<a href="http://www.ti.com/lpw">www.ti.com/lpw</a>	Telephony	<a href="http://www.ti.com/telephony">www.ti.com/telephony</a>
		Video & Imaging	<a href="http://www.ti.com/video">www.ti.com/video</a>
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