

Positive Floating Hot-Swap Power Manager

Check for Samples: [UCC2917](#), [UCC3917](#)

FEATURES

- Manages Hot-Swap of 15 V and Above
- Precision Fault Threshold
- Programmable Average Power Limiting
- Programmable Linear Current Control
- Programmable Overcurrent Limit
- Programmable Fault Time
- Internal Charge Pump to Control External N-channel MOSFET Device
- Fault Output and Catastrophic Fault Indication
- Fault Mode Programmable to Latch or Retry
- Shutdown Control
- Undervoltage Lockout

APPLICATIONS

- 390-V DC Distribution
- General High-Voltage Power Management

DESCRIPTION

The UCCx917 family of positive-floating hot-swap managers provides complete power management, hot-swap, and fault handling capability. The voltage limitation of the application is only restricted by the external component voltage limitations. The device provides its own supply voltage via a charge pump referenced to VOUT. The onboard 10-V shunt regulator protects the device from excess voltage. The devices also have catastrophic fault indication to alert the user that the ability to shut off the output N-channel MOSFET has been bypassed. All control and housekeeping functions are integrated and externally programmable. These include the fault current level, maximum output sourcing current, maximum fault time, soft-start time, and average N-channel MOSFET power limiting.

The fault level across the current-sense amplifier is fixed at 50 mV to minimize total drop out. Once 50 mV is exceeded across the current-sense resistor, the fault timer starts. The maximum allowable sourcing current is programmed with a voltage divider from the VREF/CATFLT pin to generate a fixed voltage on the MAXI pin. The current level at which the output appears as a current source is equal to V_{MAXI} divided by the current-sense resistor. If desired, a controlled current startup can be programmed with a capacitor on MAXI.

When the output current is below the fault level, the output device is switched on with full gate drive. When the output current exceeds the fault level, but is less than maximum allowable sourcing level programmed by MAXI, the output remains switched on, and the fault timer starts charging the timing capacitor C_T . Once C_T charges to 2.5 V, the output device is turned off and attempts either a retry sometime later or waits for the state on the LATCH pin to change if in latch mode. When the output current reaches the maximum sourcing current level, the output device appears as a current source.

ORDERING INFORMATION

T _J	PACKAGED DEVICES		
	DIP (J)	DIP (N)	SOIC (D)
–40°C to 85°C	UCC2917J	UCC2917N	UCC2917D
0°C to 70°C	UCC3917J	UCC3917N	UCC3917D



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

ABSOLUTE MAXIMUM RATINGS⁽¹⁾

over operating free-air temperature range (unless otherwise noted)

		VALUE		UNIT
		MIN	MAX	
Output Current	Supply ⁽²⁾		20	mA
	SHTDWN, LATCH, VREF ⁽²⁾		–500	μA
Line Current	PLIM		10	mA
Input voltage	MAXI		$V_{DD} + 0.3$	V
Junction temperature, T_J		–55	150	°C
Storage temperature, T_{stg}		–65	150	°C
Lead temperature (Soldering, 10 sec.)			300	°C

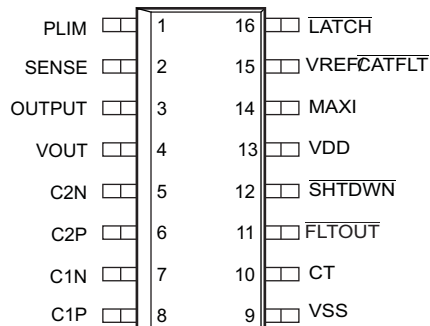
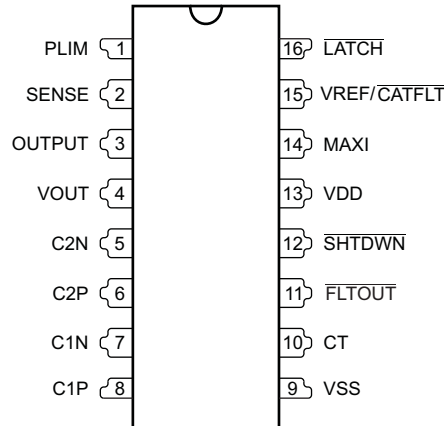
- (1) Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) Currents are positive into, negative out of the specified terminal. Consult the *Packaging* section of the *Interface Products Data Book* (TI Literature Number [SLUD002](#)) for thermal limitations and considerations of package.

ELECTRICAL CHARACTERISTICS

0°C ≤ T_A ≤ 70°C for the UCC3917, −40°C to 85°C for the UCC2917, C_{CT} = 4.7 nF, T_A = T_J, all voltages are with respect to V_{OUT}, current is positive into and negative out of the specified terminal, (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
INPUT SUPPLY						
I _{DD}	Supply current ⁽¹⁾	From V _{OUT}	4.0	5	11	mA
	UVLO turn on threshold		7.9	8.8	9.7	V
	UVLO off voltage		5.5	6.5	7.5	V
	VSS regulator voltage		−6	−5	−4	V
FAULT TIMING						
	Overcurrent threshold	T _A = 25°C	47.5	50	53	mV
		Over operating temperature	46	50	54	mV
	Overcurrent input bias			50	500	
	CT charge current bias	V _{CT} = 1 V	−78	−50	−28	μA
	CT catastrophic fault threshold		3.4		4.5	V
	CT fault threshold		2.25	2.5	2.75	V
	CT reset threshold		0.32	0.5	0.62	V
D	Output duty cycle	Fault condition	1.7%	2.7%	3.7%	
OUTPUT						
V _{OH}	High-level output voltage	I _{OUT} = 0	6	8	10	V
		I _{OUT} = −100 μA	5	7	9	
V _{OL}	Output low voltage	I _{OUT} = 500 μA		0.03	0.50	V
		I _{OUT} = 1 mA		0.6	0.9	
LINEAR CURRENT						
	Sense control voltage	V _{MAXI} = 100 mV	85	100	115	mV
		V _{MAXI} = 400 mV	370	400	430	mV
I _{BIAS}	Input bias current	V _{MAXI} = 200 mV		50	500	nA
SHUTDOWN						
	Shutdown threshold		2.0	2.4	2.8	V
	Input current	V _{SHTDWN} = 0 V	24	40	60	μA
	Shutdown delay			100	500	ns
LATCH						
V _{LATCH}	Latch threshold		1.7	2	2.3	V
	Input current	V _{LATCH} = 0 V	24	40	60	μA
FLTOUT						
	Fault output high	V _{CT} = 0 V, I _{SOURCE} = 0 μA	6	8	10	V
	Fault output low	V _{CT} = 5 V, I _{SINK} = 200 μA		0.01	0.05	V
POWER LIMITING						
	V _{SENSE} regulator voltage	I _{PLIM} = 64 μA	4.5	5	5.5	V
	Duty cycle control	I _{PLIM} = 64 μA	0.6%	1.2%	1.7%	
		I _{PLIM} = 1 mA	0.045%	0.1%	0.2%	
VREF/CATFLT						
	V _{REF} regulator voltage		4.5	5	5.5	V
	Fault output low	I _{VREF/CATFLT} = 5 mA		0.22	0.50	V
I _{SINK}	Output sink current	V _{CT} = 5 V, V _{VREF/CATFLT} = 5 V	15	40	70	mA
	Overload comparator threshold	Relative to MAXI	110	200	290	mV

(1) Set by user using the R_{SS} resistor.

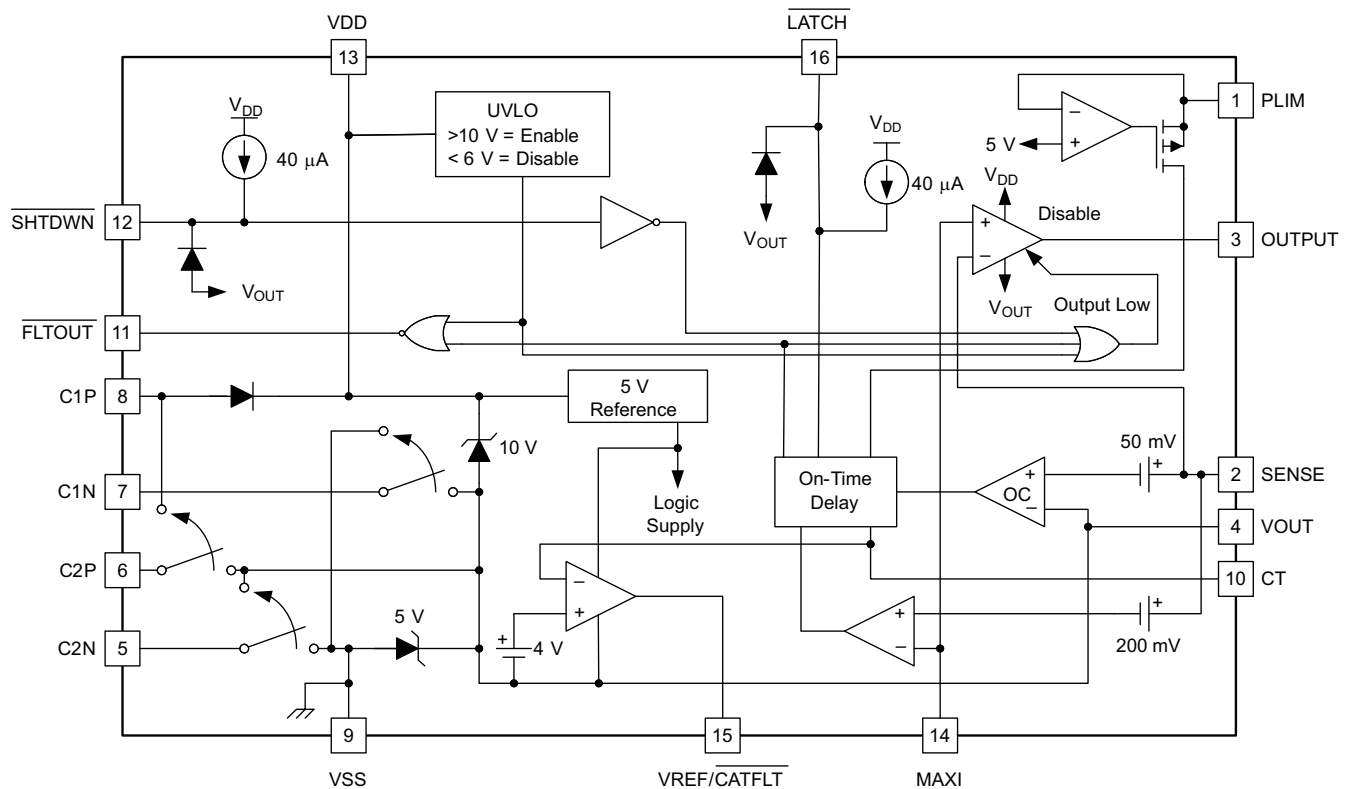
**D PACKAGE
16 PINS
(TOP VIEW)**

**J, N PACKAGE
16 PINS
(TOP VIEW)**

DEVICE INFORMATION
PIN DESCRIPTIONS

PIN		I/O	DESCRIPTION
NAME	NO.		
C1N	7	I	Negative side of the upper charge-pump capacitor.
C1P	8	I	Positive side of the upper charge-pump capacitor.
C2N	5	I	Negative side of the lower charge-pump capacitor.
C2P	6	I	Positive side of lower charge-pump capacitor.
CT	10	I	A capacitor is connected to this pin to set the fault time. The fault time must be more than the time to charge the external load capacitance (see application information).
FLTOUT	11	O	Provides fault output indication. Interface to this pin is usually performed through level-shift transistors. Under a non-fault condition, FLTOUT is pulled to a high state. When a fault is detected by the fault timer or the undervoltage lockout, this pin is driven to a low state, indicating the output N-channel MOSFET is in the off state.
LATCH	16	I	Pulling this pin low causes a fault to latch until this pin is brought high or a power-on reset is attempted. However, pulling this pin high before the reset time is reached does not clear the fault until the reset time is reached. Keeping LATCH high results in normal operation of the fault timer. Users should note there is an R-C delay dependent upon the external capacitor at this pin.
MAXI	14	I	Programs the maximum-allowable sourcing current. Since VREF/CATFLT is a regulated voltage, a voltage divider can be derived to generate the program level for MAXI. The current level at which the output appears as a current source is equal to the voltage on MAXI divided by the current-sense resistor. If desired, a controlled current start-up can be programmed with a capacitor on MAXI (to VOUT), and a programmed start delay can be achieved by driving the shutdown with an open collector/drain device into an RC network.
OUTPUT	3	O	Gate drive to the N-channel MOSFET pass element.
PLIM	1	I	This feature ensures that the average external N-channel MOSFET power dissipation is controlled. A resistor is connected from this pin to the drain of the external N-channel MOSFET pass element. When the voltage across the N-channel MOSFET exceeds 5 V, current flows into PLIM, which adds to the fault timer charge current, reducing the duty cycle from the 3% level.
SENSE	2	I	Input voltage from the current-sense resistor. When there is greater than 50 mV across this pin with respect to VOUT, a fault is sensed, and the C _{CT} capacitor starts to charge.
SHTDWN	12	I	This pin provides shutdown control. Interface to this pin is usually performed through level-shift transistors. When shutdown is driven low, the output disables the N-channel MOSFET pass device.
VOUT	4	I	Ground reference for the device.

PIN DESCRIPTIONS (continued)

PIN		I/O	DESCRIPTION
NAME	NO.		
VDD	13	I	Power to the device is supplied by an external current-limiting resistor on initial power up or if the load is shorted. As the load voltages rises (VOUT), a small amount of power is drawn from VOUT by an internal charge pump. The charge pump's input voltage is regulated by an on-device 5-V zener. Power to VDD is supplied by the charge pump under normal operation (i.e., external FET is on).
VREF/CATFLT	15	O	This pin primarily provides an output reference for the programming of MAXI. Secondly, it provides catastrophic fault indication. In a catastrophic fault, when the device unsuccessfully attempts to shutdown the N-channel MOSFET pass device, this pin pulls to a low state when CT charges above the catastrophic fault threshold. A possible application for this pin is to trigger the shutdown of an auxiliary FET in series with the main FET for redundancy.
VSS	9	I	Negative reference out of the device. This pin is normally current fed via a resistor to load ground.

FUNCTIONAL BLOCK DIAGRAM



UDG-99055

APPLICATION INFORMATION

FAULT TIMING

Figure 1 shows the detailed circuitry for the fault timing function of the UCC3917. For simplicity, first consider a typical fault mode where the overload comparator and the current source I3 do not come into play. A typical fault occurs once the voltage across the current-sense resistor, R_S , exceeds 50 mV. This causes the overcurrent comparator to trip and the timing capacitor to charge with current source I1 plus the current from the power limiting amplifier, or PLIM amplifier. The PLIM amplifier is designed to only source current into the CT pin once the voltage across the output FET exceeds 5 V. The current I_{PL} is related to the voltage across the FET as shown in Equation 1.

$$I_{PL} = \frac{(V_{IN} - V_{VOUT})}{R_{PL}} \quad (1)$$

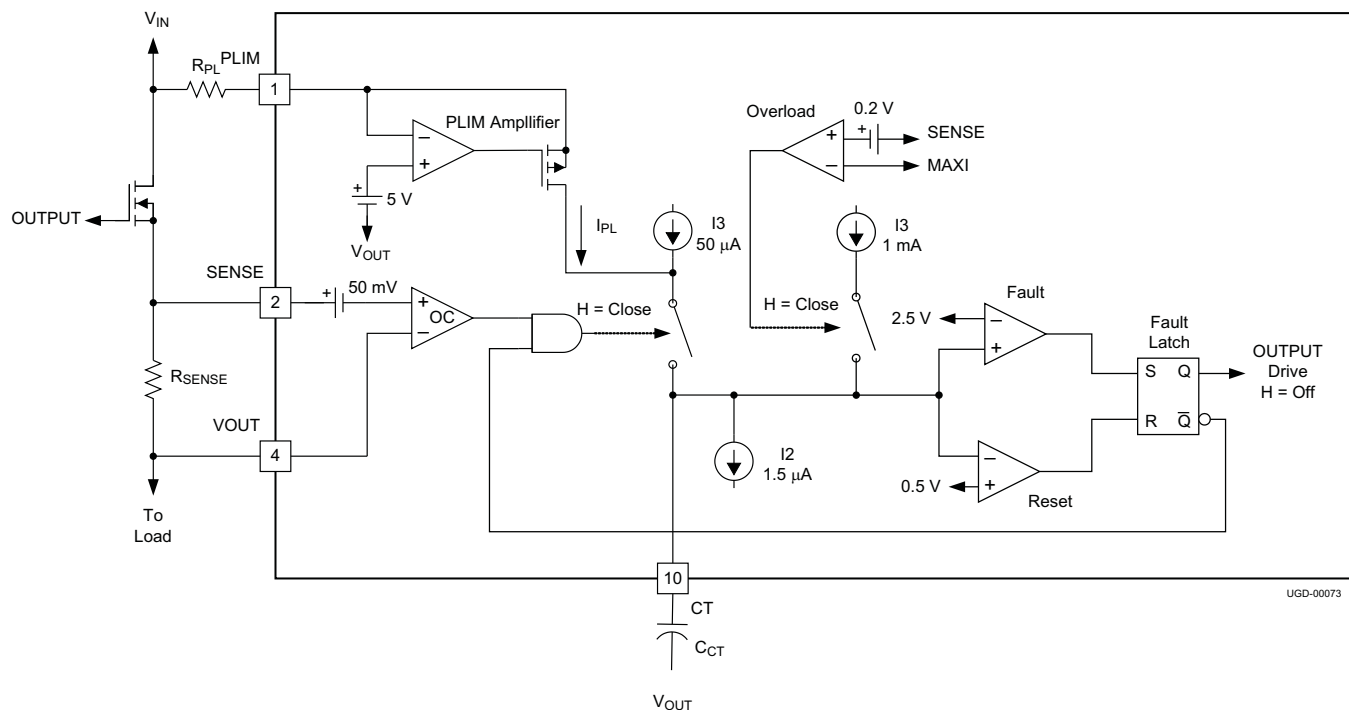


Figure 1. Fault Timing Circuitry for the UCC3917, Including Power Limit and Overload

NOTE

Under normal fault conditions where the output current is slightly above the fault level, $V_{\text{OUT}} \cong V_{\text{IN}}$, $I_{\text{PL}} = 0$, and the C_{CT} charging current is I_1 .

During a fault, C_{CT} charges at a rate determined by the internal charging current and the external timing capacitor, CT. Once C_{CT} charges to 2.5 V, the fault comparator switches and sets the fault latch. Setting the fault latch causes both the output to switch off and the charging switch to open. CT must now discharge with current source I2 until 0.5 V is reached. Once the voltage at C_{CT} reaches 0.5 V, the fault latch resets (assuming $\overline{LATCH}$ is high, otherwise the fault latch does not reset until the $\overline{LATCH}$ pin is brought high or a power-on reset occurs). This re-enables the output and allows the fault circuitry to regain control of the charging switch. If a fault is still present, the overcurrent comparator closes the charging switch causing the cycle to repeat.

Under a constant fault the duty cycle is shown in [Equation 2](#).

$$D = \frac{I_2}{I_{PL} - I_1} = \frac{1.5\mu A}{I_{PL} + 50\mu A}$$

where

- I_{PL} is 0 μA under normal operations (see [Figure 2](#)) (2)

However, during large transients average power dissipations can be limited using the PLIM pin. The average dissipation in the pass element is shown in [Equation 3](#).

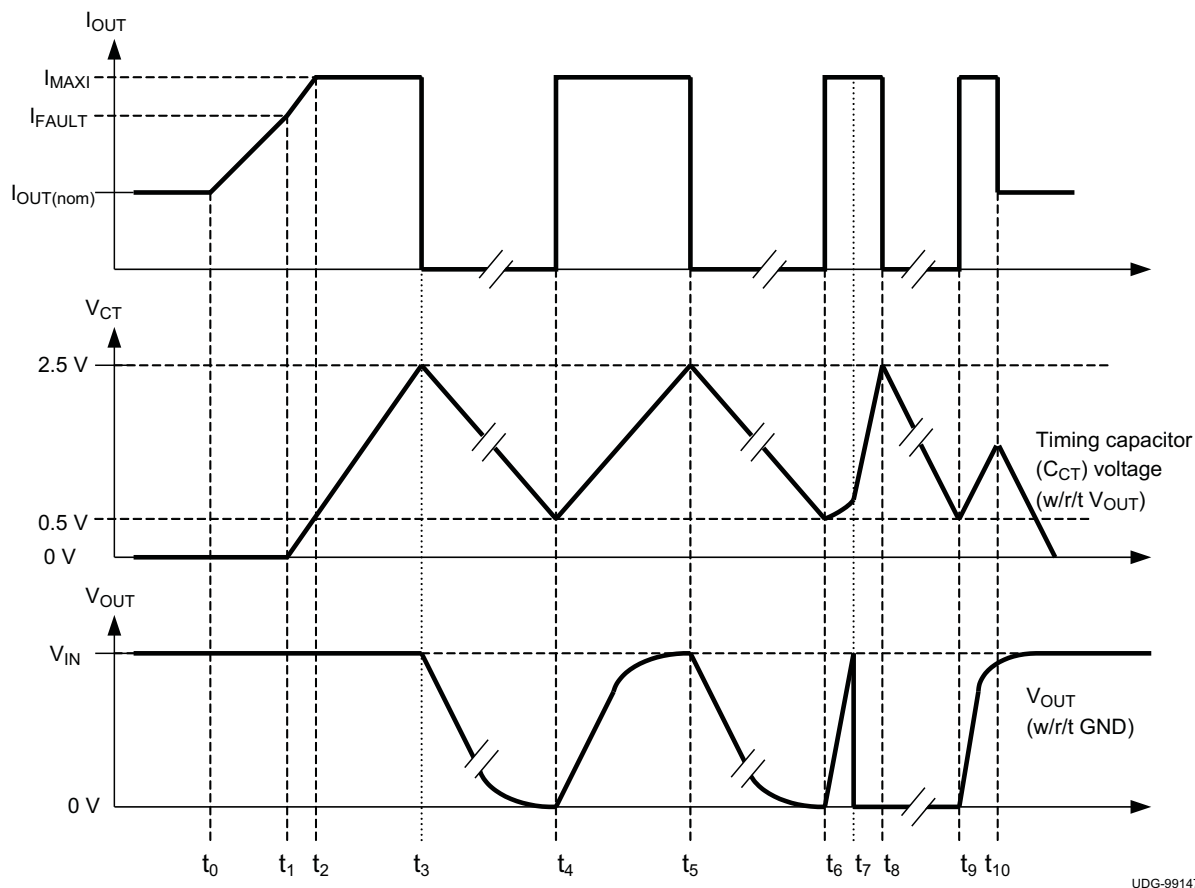
$$P_{FET(avg)} = (V_{IN} - V_{VOUT}) \times I_{MAXI} \times D = (V_{IN} - V_{VOUT}) \times I_{MAXI} \times \frac{1.5\mu A}{I_{PL} + 50\mu A}$$

where

- both [Equation 4](#) and [Equation 5](#) are true (3)

$$V_{IN} - V_{OUT} \gg 5V \quad (4)$$

$$I_{PL} = \frac{(V_{IN} - V_{VOUT})}{R_{PL}} \quad (5)$$



UDG-99147

Figure 2. Typical Timing Diagram

Table 1. Timing Stages

TIME	CONDITION	DESCRIPTION
t0	Safe condition	Output current is nominal, output voltage is at the positive rail, V_{IN}
t1	Fault control reached	Output current rises above the programmed fault value, C_T begins to charge with approximately 50 μA
t2	Maximum current reached	Output current reaches the programmed maximum level and becomes a constant current with value I_{MAX} .
t3	Fault occurs	C_{CT} has charged to 2.5 V, fault output goes low, the FET turns off allowing no output current to flow, V_{OUT} discharges to ground
t4	Retry	C_T has discharged to 0.5 V, but fault current is still exceeded, C_T begins charging again, FET is on, V_{VOUT} rises to V_{IN} .
t5	t5 = t3	This illustrates 3% duty cycle.
t6	t6 = t4	
t7	Output short circuit	if V_{OUT} is short circuited to ground, C_T charges at a higher rate depending upon the values for V_{IN} and R_{PL} .
t8	Fault occurs	Output is still short circuited, but the occurrence of a fault turns the FET off so no current is conducted.
t9	Fault remains	Output short circuit released, still in fault mode.
t10	t10 = t0	Fault released, safe condition – return to normal operation of the circuit breaker.

Note that $t_6 - t_5 \approx 36 \times (t_5 - t_4)$.

and where $I_{PL} \gg 50 \mu A$, the duty cycle can be approximated in Equation 6.

$$D = \frac{1.5 \mu A \times R_{PL}}{(V_{IN} - V_{VOUT})} \quad (6)$$

Therefore the average power dissipation in the MOSFET can be approximated by Equation 7.

$$P_{FET(avg)} = (V_{IN} - V_{VOUT}) \times I_{MAX} \times \frac{1.5 \mu A \times R_{PL}}{(V_{IN} - V_{VOUT})} = I_{MAX} \times 1.5 \mu A \times R_{PL} \quad (7)$$

Notice that since $(V_{IN} - V_{VOUT})$ cancels, average power dissipation is limited in the N-channel MOSFET pass element (see Figure 3). Also, a value for R_{PL} can be approximated by using Equation 8.

$$R_{PL} = \frac{P_{FET(avg)}}{I_{MAX} \times 1.5 \mu A} \quad (8)$$

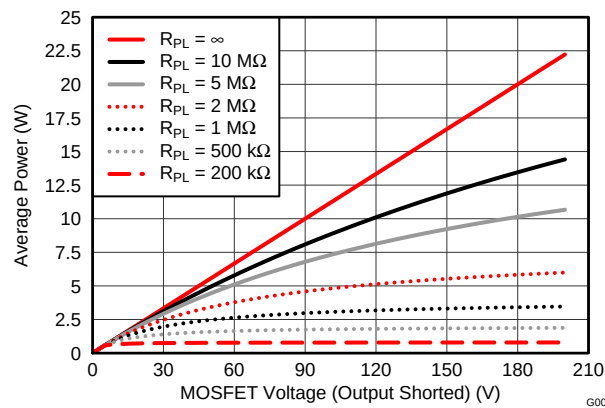


Figure 3.

OVERLOAD COMPARATOR

The overload comparator provides protection against a shorted load during normal operation when the external N-channel FET is fully enhanced. Once the FET is fully enhanced the linear current amplifier essentially saturates and the system is in effect operating open loop. Once the FET is fully enhanced the linear current amplifier requires a finite amount of time to respond to a shorted output possibly destroying the external FET. The overload comparator is provided to quickly shutdown the external MOSFET in the case of a shorted output (if the FET is fully enhanced). During an output short, C_T is charged by I_3 at $\approx 1 \text{ mA}$. The current threshold for the overload comparator is a function of I_{MAX} and a fixed offset and is defined as:

$$I_{OVERLOAD} = I_{MAX} \times \frac{200 \text{ mV}}{R_S} \quad (9)$$

When the overcurrent comparator trips, the UCC3917 enters a programmed fault mode (hiccup or latched). It should be noted that on subsequent retries during hiccup mode or if a short should occur when the UCC3917 is actively limiting the current, the output current does not exceed I_{MAX} . In the event that the external FET does not respond during a fault the UCC3917 sets the VREF/CATFLT pin low to indicate a catastrophic failure.

SELECTING THE MINIMUM TIMING CAPACITANCE

To ensure that the device starts up correctly the designer must ensure that the fault time programmed by CT exceeds the startup time of the load. The startup time (t_{START}) is a function of several components; load resistance and load capacitance, soft-start components R1, R2 and C_{SS} , the power limit current contribution determined by R_{PL} and C_{IN} .

Use [Equation 10](#) to calculate the start time using a parallel capacitor-constant current load.

$$t_{\text{START}} = \frac{C_{\text{LOAD}} \times V_{\text{IN}}}{(I_{\text{MAX}} - I_{\text{LOAD}})} \quad (10)$$

Use [Equation 11](#) to calculate the start time using a parallel R-C load.

$$t_{\text{START}} = R_{\text{LOAD}} \times C_{\text{LOAD}} \times \ln \times \left(1 - \frac{V_{\text{IN}}}{I_{\text{MAX}} \times R_{\text{LOAD}}} \right) \quad (11)$$

If the power limit function is not be used, then $C_{\text{CT}(\text{min})}$ can be found using [Equation 12](#).

$$C_{\text{T}(\text{min})} = \frac{I_{\text{CH}} \times t_{\text{START}}}{dV_{\text{CT}}}$$

where

- dV_{CT} is the hysteresis on the fault detection circuitry (12)

During operation in the latched fault mode configuration $dV_{\text{CT}} = 2.5 \text{ V}$. When the UCC3917 is configured for the hiccup or retry mode of fault operation $dV_{\text{CT}} = 2.0 \text{ V}$.

If the power limit function is used, the C_{CT} charging current becomes a function of $I_{\text{CH}} + I_{\text{PL}}$. $C_{\text{CT}(\text{min})}$ is found by integrating [Equation 13](#) with respect to V_{CT} .

$$C_{\text{T}(\text{min})} = \left(I_{\text{CH}} + \frac{V_{\text{IN}} - (I_{\text{MAX}} \times R_{\text{LOAD}}) \times \left[1 - e^{\left(\frac{-t}{R_{\text{LOAD}} \times C_{\text{LOAD}}} \right)} \right]}{R_{\text{PL}}} \right) \times \frac{dt}{dV_{\text{CT}}} \quad (13)$$

The minimum timing capacitance is calculated in [Equation 14](#).

$$C_{\text{T}(\text{min})} = \frac{1}{R_{\text{PL}} \times dV_{\text{CT}}} \times \left[((I_{\text{CH}} \times R_{\text{PL}}) + V_{\text{IN}} - (I_{\text{MAX}} \times R_{\text{LOAD}})) \times t_{\text{START}} + V_{\text{IN}} \times R_{\text{LOAD}} \times C_{\text{LOAD}} \right] \quad (14)$$

SELECTING OTHER EXTERNAL COMPONENTS

Other external components are necessary for correct operation of the device. Referring to Figure 13, resistors R_{SENSE} , R_{SS} , R_{DD} , R_{17} , R_{18} , and R_{19} and Equation 15 through Equation 17 apply:

$$R_{SENSE} = \frac{50\text{mV}}{I_{FAULT}} \quad (15)$$

$$R_{SS} = \left(\frac{(V_{IN} - 5\text{V})}{I_{DD}} \right) \quad (16)$$

$$R_{DD} = \left(\frac{(V_{IN} - 10\text{V})}{I_{DD}} \right) \quad (17)$$

$(R_{17} + R_{18} + R_{19}) > 20\text{ k}\Omega$ (current limit out of VREF)

Use a value of 0.1 μF for the external charge pump capacitors.

SOFT-START OPERATION

The soft-start circuits in Figure 4, and Figure 5 gradually ramp up the load current on power-up, retry, or if the $\overline{\text{SHTDWN}}$ pin is pulled high. Control circuitry (not shown) turns on Q1 to discharge C1 when $\overline{\text{FLTOUT}}$ or $\overline{\text{SHTDWN}}$ are low (i.e., external power MOSFET is off) so the load current always ramps from zero. The circuit in Figure 4 uses an inexpensive bipolar transistor for Q1 so the component cost is lower than the circuit in Figure 5.

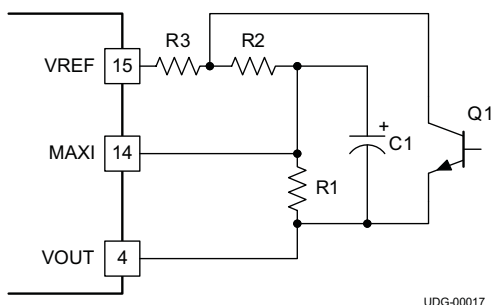


Figure 4. Soft-Start Circuit Using A Higher-Cost Bi-Polar Transistor

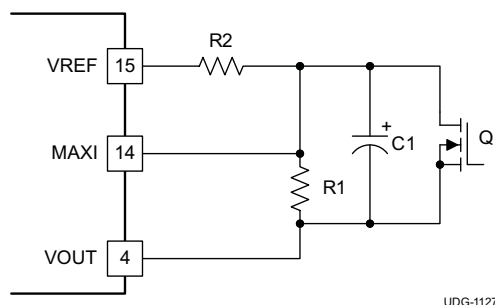


Figure 5. Soft-Start Circuit Using A Lower-Cost MOSFET

Soft-start operation minimizes the voltage disturbance on the power bus when a circuit card is inserted into a live back plane. This disturbance could reset a system, which is not desirable when high availability is required. A server is an example of a high availability system.

Soft-start operation is initiated with the $\overline{\text{SHTDWN}}$ pin in as shown in Figure 6. The anode of D2 is grounded when the card is in the back plane. R2 limits the $\overline{\text{SHTDWN}}$ pin current to between 60 μA and 500 μA (i.e., $60\text{ }\mu\text{A} < 0.65\text{ V} / R2 < 500\text{ }\mu\text{A}$).

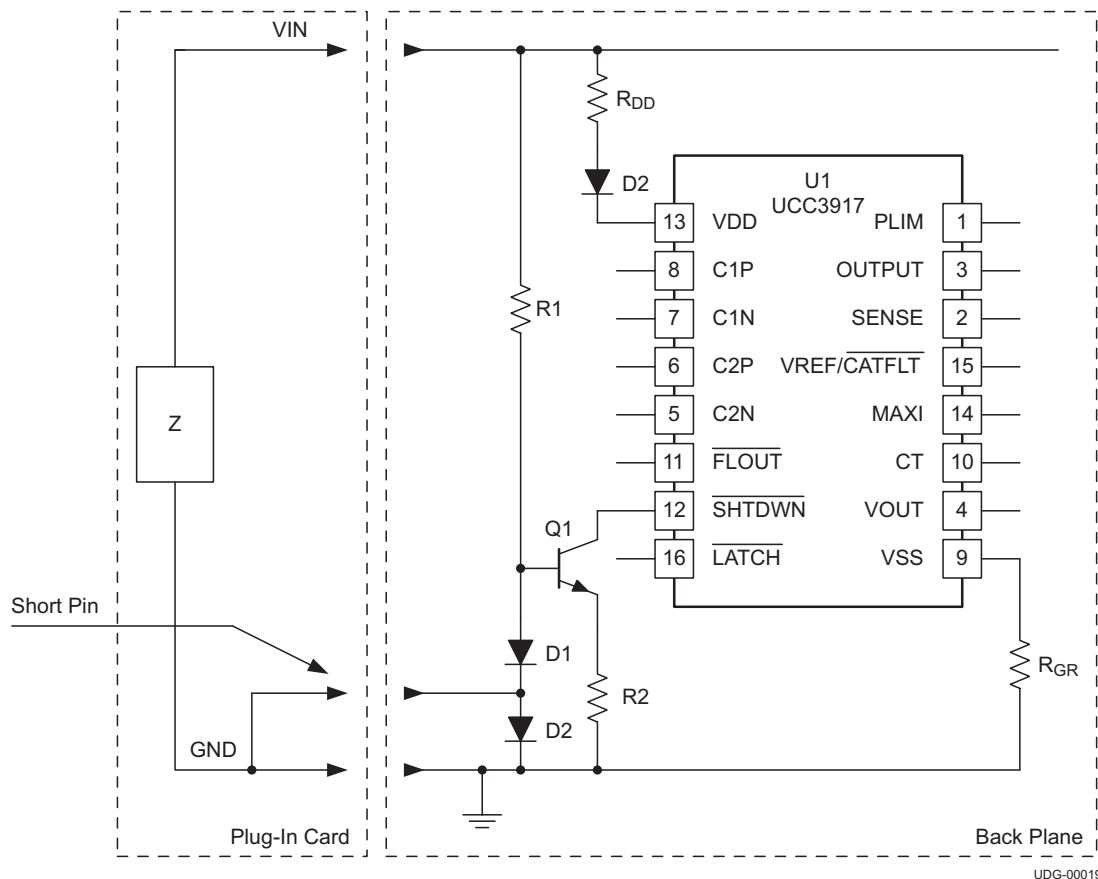


Figure 6. Soft-Start Operation with $\overline{\text{SHTDWN}}$

I/O INTERFACE

The $\overline{\text{SHTDWN}}$ and $\overline{\text{LATCH}}$ inputs and $\overline{\text{FLOUT}}$ output are referenced to VOUT. Level-shifting circuits are needed if the device communicates with logic that is referenced to load/system ground.

INTERFACING TO $\overline{\text{LATCH}}$ AND $\overline{\text{SHTDWN}}$

Two level shift circuits for $\overline{\text{LATCH}}$ and $\overline{\text{SHTDWN}}$ are shown in Figure 7. The optocoupler (Figure 7) is simple, but the constant-current sink (Figure 8) is a low-cost solution.

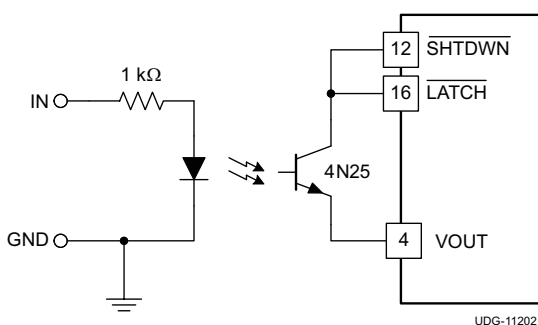


Figure 7. Optocoupler Interface

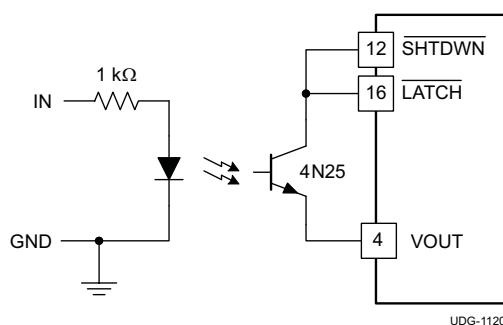


Figure 8. Constant-Current Sink Interface

Design Example 1: Using the TTL Signal to Control the $\overline{\text{LATCH}}$ Pin Input

A TTL signal controls the $\overline{\text{LATCH}}$ input of the UCC3917 using the circuit in [Figure 8](#). Determine the component values if the maximum load voltage is 60 V.

The assumptions for this analysis are:

- $V_{BE} \approx 0.65 \text{ V}$
- $V_{CE(sat)} \approx 0.1 \text{ V}$
- $R_1 || R_2 \ll h_{fe} \times R_3$
- Voltage measurements are with respect to load ground

Calculation Steps

Step 1. Select Q1.

The LATCH input is internally pulled up to the charge pump voltage, which is 10 V above the load voltage. Q1 is therefore subjected to 70 V in a 60 V system. A FMMTA06 transistor, with a $V_{CEO(max)}$ of 80 V, is suitable for Q1 in this application.

Step 2. Determine R1, R2 and R3.

The interface circuit responds to a TTL input as follows.

- Logic "0" input: $0 \text{ V} < V_{IL} < 0.8 \text{ V} \Rightarrow 0 \mu\text{A} < I_C < 60 \mu\text{A}$ and $V_C > 1.7 \text{ V}$
- Logic "1" input: $2 \text{ V} < V_{IH} < 5 \text{ V} \Rightarrow 60 \text{ mA} < I_C < 500 \mu\text{A}$ and $V_C < 1.7 \text{ V}$

This response establishes the relationship between R1, R2, and R3.

$$\text{If } V_{IN} = V_{IL(max)} = 0.8 \text{ V, then Q1 is off and } V_B - V_{IL(max)} \times \left(\frac{R_2}{R_1 + R_2} \right) < V_{BE} \longrightarrow \frac{R_1}{R_2} > 0.23$$

If $V_{IN} = V_{IH(max)} = 5 \text{ V}$, then:

$$V_B - V_{IL(max)} \times \left(\frac{R_2}{R_1 + R_2} \right) < V_{BE} \longrightarrow \frac{R_1}{R_2} > 0.23 \quad I_C = \left(\frac{1.7 \text{ V} - V_{CE(sat)}}{R_3} \right) < 500 \mu\text{A} \longrightarrow R_3 > 3.2 \text{ k}\Omega$$

$$V_C = V_{CE(sat)} + V_E < 1.7 \text{ V} \longrightarrow V_E < 1.6 \text{ V} \quad V_E = (V_B - V_{BE}) < 1.6 \text{ V} \longrightarrow V_B < 2.25 \text{ V}$$

$$\frac{(V_B - V_{IH(max)}) \times R_2}{R_1 + R_2} < 2.25 \text{ V} \longrightarrow \frac{R_1}{R_2} > 1.222$$

If $V_{IN} = V_{IH(max)} = 2 \text{ V}$, then:

$$V_B = \frac{(V_{IH(min)} \times R_2)}{(R_1 + R_2)} \longrightarrow \frac{2 \text{ V}}{1 + \left(\frac{R_1}{R_2} \right)}$$

$$I_C = \frac{(V_B - V_{BE})}{R_3} > 60 \mu\text{A} \longrightarrow R_3 < \frac{(V_B - V_{BE})}{60 \mu\text{A}}$$

In summary, R1, R2, and R3 obey the inequalities:

$$\frac{R_1}{R_2} > 1.222 \quad \text{and} \quad 3.2 \text{ k}\Omega < R_3 < \frac{(V_B - 0.65)}{60 \mu\text{A}}, \quad \text{where } V_B = \frac{2 \text{ V}}{1 + \left(\frac{R_1}{R_2} \right)}$$

If $R_1 / R_2 = 1.3$, then $3.2 \text{ k}\Omega < R_3 < 3.66 \text{ k}\Omega$. $R_1 = 4.64 \text{ k}\Omega$ for the case where $R_2 = R_3 = 3 \text{ k}\Omega$.

The same design can be used to control the UCC3917's $\overline{\text{SHTDWN}}$ input.

Interfacing to $\overline{\text{FLTOUT}}$

The level shift circuit in Figure 9 is a way to interface to $\overline{\text{FLTOUT}}$. The operation of this circuit and the $\overline{\text{SHTDWN}}$ / LATCH level shift circuit in Figure 8 are similar.

Design Example 2: A TTL-Compatible Output Level Shifter Using $\overline{\text{FLTOUT}}$

This design example describes a TTL compatible output level shifter for $\overline{\text{FLTOUT}}$. The maximum system voltage is 60 V.

Use a level shift circuit as shown in Figure 9. The $\overline{\text{FLTOUT}}$ output can swing to the charge pump voltage, which is 10 V above the load voltage. In a 60-V application, the collector-emitter of Q1 can be as high as –70 V. A FMMT593 transistor, with a $V_{\text{CEO(max)}}$ rating of –100 V, is a suitable choice for Q1.

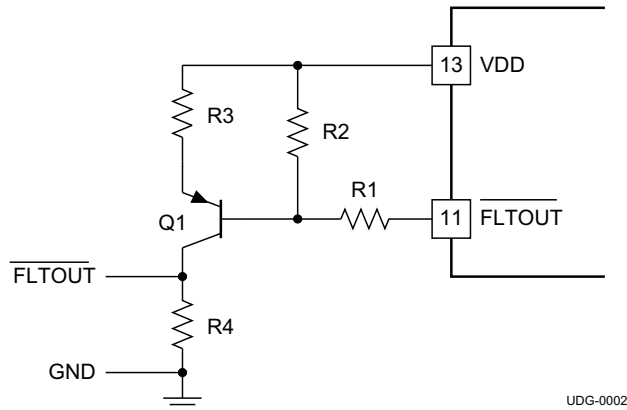


Figure 9. Interfacing to $\overline{\text{FLTOUT}}$

Calculation Steps

Step 1. Output saturation voltage constraint.

$$V_{\text{C(on)}} = V_{\text{E}} + V_{\text{CE(sat)}} > 2.4 \text{ V (TTL output high)} \quad (18)$$

$$\text{If } V_{\text{C(on)}} = 2.6 \text{ V, then } V_{\text{E}} = (2.6 \text{ V} + (-0.1 \text{ V})) = 2.5 \text{ V} \quad (19)$$

Step 2. Source current constraint.

$$I_{\text{C}} = 100 \mu\text{A}$$

Step 3. Calculate the value of R3.

$$R_3 = \frac{(6 \text{ V} - V_{\text{E}})}{I_{\text{E}}} = \frac{(6 \text{ V} - V_{\text{E}})}{I_{\text{C}}} = \frac{(6 \text{ V} - 2.5 \text{ V})}{100 \mu\text{A}} = 35 \text{ k}\Omega \quad (20)$$

Step 4. Calculate the base voltage.

$$V_{\text{B}} = V_{\text{E}} + V_{\text{BE}} = (2.5 \text{ V} - 0.65 \text{ V}) = 1.85 \text{ V} \quad (21)$$

Step 5. Calculate the voltage divider.

The voltage divider formula for R1 and R2 is shown in Equation 22

$$\frac{R_2}{(R_1 + R_2)} \times 6 \text{ V} \cong (6 \text{ V} - V_{\text{B}}) \text{ or } \frac{R_1}{R_2} = \frac{6 \text{ V}}{(V_{\text{B}} - 1)} \quad (22)$$

Equation 23 assumes negligible loading by Q1.

$$\frac{R_1}{R_2} \ll h_{\text{fe}} \times R_3 \quad (23)$$

If $h_{fe} = 100$, then:

$$\frac{R_1}{R_2} = \left(\frac{6}{(1.85 - 1)} \right) = 2.24 \text{ and } \frac{R_1}{R_2} \ll (100 \times 35 \text{ k}\Omega) = 3.5 \text{ M} \quad (24)$$

If $R_2 = R_3 = 34.8 \text{ k}\Omega$, then $R_1 = 15.4 \text{ k}\Omega$

Step 6. Calculate the output voltage.

The output voltage is set by R_4 .

$$I_C \times R_4 > 2.4 \text{ V}, \quad R_4 > \frac{2.4 \text{ V}}{100 \mu\text{A}} = 24 \text{ k}\Omega \quad (25)$$

Choose an R_4 value of $49.9 \text{ k}\Omega$.

PRELOADING THE OUTPUT

R_{DD} provides a sneak path for current between 3 mA and 11 mA (e.g., at 0 V output) to trickle into the load when the power FET is off (see [Figure 10](#)).

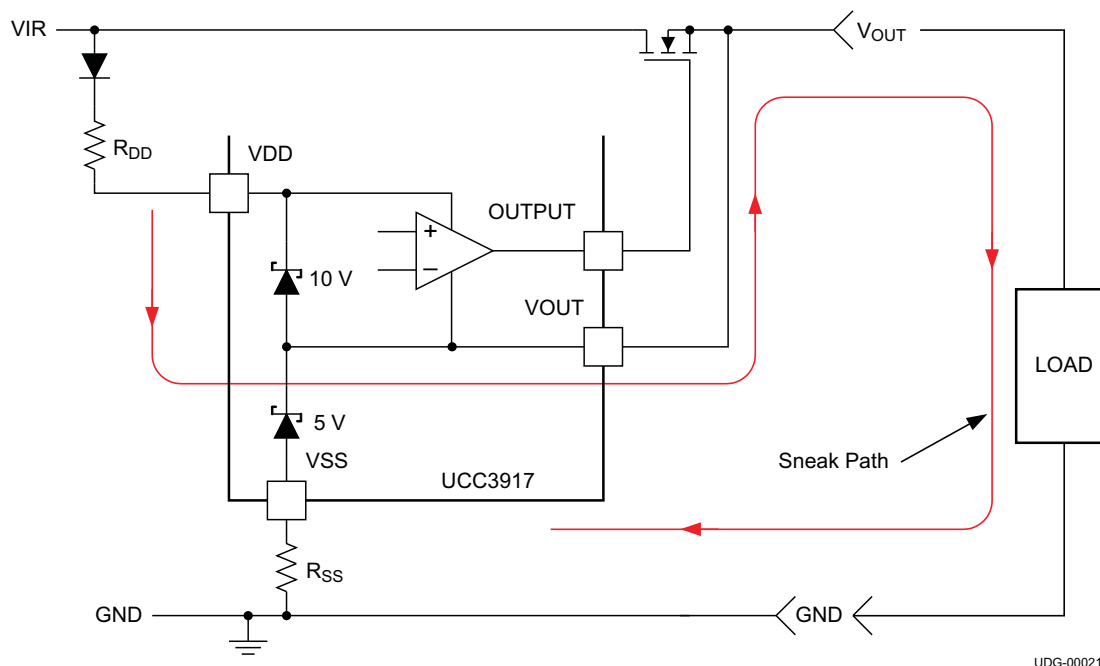


Figure 10. Simplified Schematic Illustrating I_{DD} Sneak Path

This current causes an unacceptably high output voltage at shutdown if the output is not adequately loaded. In this case, it is necessary to preload the HSPM output to keep the shutdown voltage level acceptable. The preload also insures reliable start-up of the UCC3917 by holding the output voltage low when power is first applied to the HSPM.

A resistor is usually an unacceptable preload because it creates a power dissipation problem when the FET turns on. For example, a 90.9- Ω preload (used to limit the shutdown voltage of a 48-V HSPM to less than 1 V) adds 25-W of power dissipation to the system. In a 100-V system, this dissipation increases to 110 W. The power dissipation overhead increases with the system voltage squared for a resistive preload.

Figure 11 shows how the active load limits the shutdown voltage without creating a power dissipation problem.

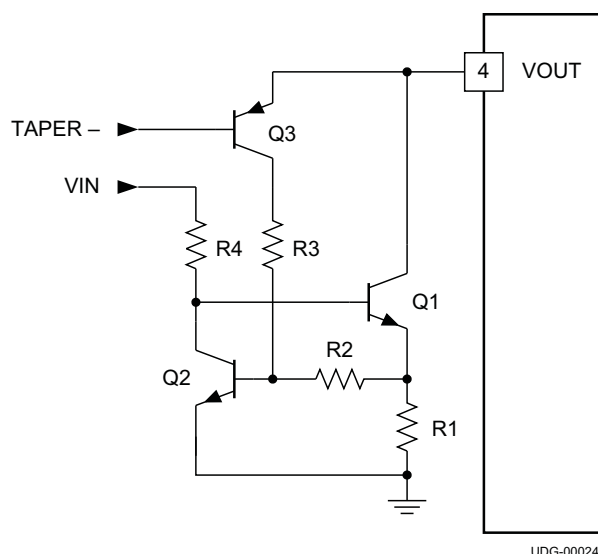


Figure 11. Active Preload

This load is a constant-current sink (i.e., Q3 is off) when the power FET is off. The shutdown voltage is less than 0.85 V if the sink current, set by R1, is greater than 11 mA.

$$I_{\text{SNKFET(off)}} = \frac{V_{\text{BE}}}{R_1} > 11 \text{ A} \quad (26)$$

The power dissipation of Q1 is kept to a minimum when the power FET turns on by tapering the sink current as the load voltage rises as shown in Equation 27.

$$I_{\text{SNKFET(on)}} = \left(\left(\frac{V_{\text{BE}}}{R_1} \right) - V_{\text{OUT}} \right) \times \left(\frac{R_2}{(R_1 \times R_3)} \right) \quad (27)$$

For $R_1 \ll R_2 \ll R_3$

Control circuitry turns on Q3 to activate current tapering. Tapering the current causes the power dissipation of Q1 to peak when the load voltage is calculated in Equation 28.

$$V_{\text{OUT}} = \frac{V_{\text{BE}}}{2} \times \frac{R_3}{R_2} \quad (28)$$

The power dissipated by Q1 at this voltage is shown in Equation 29.

$$P_{\text{D(max)Q1}} = \left(\frac{V_{\text{BE}}}{2} \right)^2 \times \frac{R_3}{(R_1 \times R_2)} \quad (29)$$

In the case of a brownout or if the input voltage rises slowly (e.g., adjustable lab power supply), it is possible for Q1 to remain in the maximum power dissipation region for a significant time. Limiting the power dissipation of Q1 below its maximum rating insures reliable operation in this case.

Design Example 3: A 14-mA Active Preload for a 60-V Hot Swap Power Manager (HSPM)**Calculation Steps****Step 1. Set the sink current.**

$$R_1 = \frac{V_{BE}}{I_{SNKFET(off)}} = \frac{0.65\text{ V}}{14\text{ mA}} = 46.4\ \Omega \quad (30)$$

Use a BC846B transistor for Q1. This device has a collector breakdown voltage of 65 V and power dissipation rating of 225 mW.

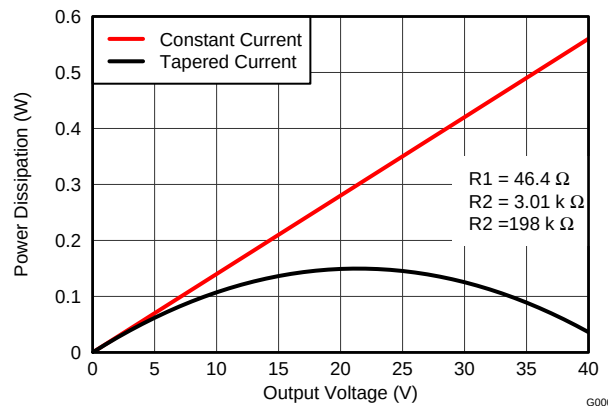
Step 2. Select R2 and R3.

Select R2 and R3 to limit the power dissipation of Q1 to less than 225 mW, in this example 150 mW is chosen.

$$\frac{R_3}{R_2} = \left(\frac{2}{V_{BE}} \right)^2 \times R_1 \times P_{D(max)Q1} = \left(\frac{2}{0.65\text{ V}} \right)^2 \times 46.4\ \Omega \times 0.15\text{ W} = 65.9 \quad (31)$$

If R2 = 3.01 kΩ, then R3 = 198 kΩ.

The power dissipation of Q1 is shown in [Figure 12](#).

**Figure 12. Output Voltage vs. Power Dissipation****PROTECTING THE 5-V REGULATOR**

The UCC3917's 5-V regulator can overvoltage if VOUT is loaded with less than 11 mA (min) on power up. The overvoltage mechanism is best understood by recognizing that the 5-V Zener diode in the UCC3917 block diagram, is actually a feedback shunt regulator. This regulator turns on when the voltage across the UCC3917's 10-V Zener diode is greater than the UVLO threshold. If VOUT is unloaded and power is applied to the UCC3917, the UVLO threshold cannot be reached and the 5-V regulator impedance is infinite.

Consequently, the entire input voltage appears across the shunt regulator causing it to break down. Clamping its voltage with Zener diode to 5.6 V can protect the regulator.

NOTE

The Zener diode is unnecessary if the current drawn from VOUT is greater than 11 mA when power is *initially* applied to the UCC3917.

EVALUATION CIRCUIT EXAMPLE

A 28 V to 60 V at 1-A HSPM evaluation circuit is shown in [Figure 13](#). Level translation circuitry allows communications with logic referenced to load ground. This circuit is available as a DV3917 Evaluation Board. Contact your local Texas Instruments sales representative for more information.

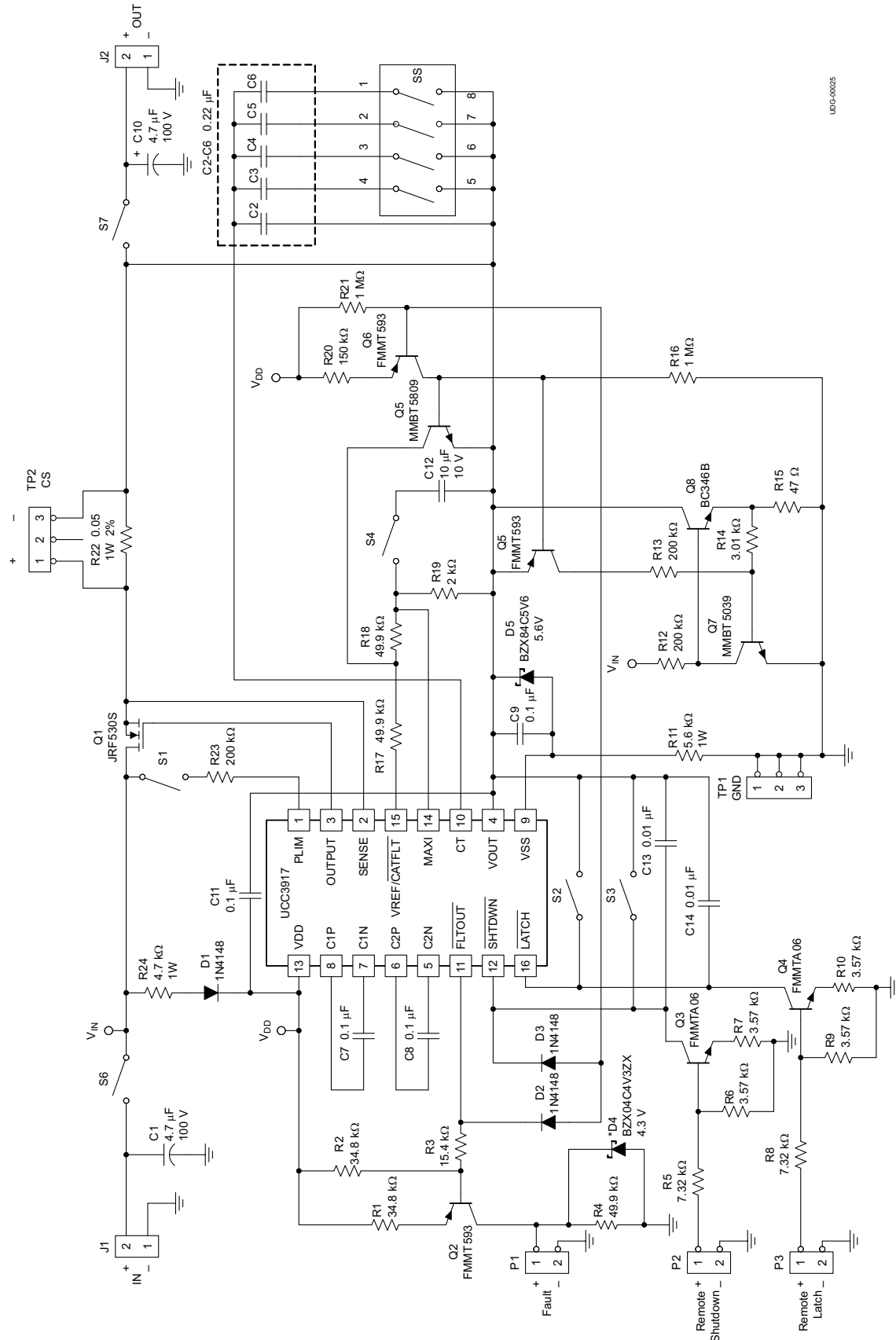


Figure 13. A 28 V to 60 V at 1-A Positive Floating HSPM Evaluation Circuit Using the UCC3917

SAFETY RECOMMENDATIONS

Although the UCC3917 is designed to provide system protection for all fault conditions, all integrated circuits can ultimately fail short. For this reason, if the UCC3917 is intended for use in safety critical applications where UL or some other safety rating is required, a redundant safety device such as a fuse should be placed in series with the power device. The UCC3917 prevents the fuse from blowing for virtually all fault conditions, increasing system reliability and reducing maintenance cost, in addition to providing the hot-swap benefits of the device.

REVISION HISTORY

Changes from Revision C (February, 2013) to Revision D	Page
Changed the UCC2917 and UCC3917 marketing status from Product Preview to Production Data.	1

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
UCC2917D	OBSOLETE	SOIC	D	16		TBD	Call TI	Call TI	-40 to 85	UCC2917D	
UCC2917DTR	OBSOLETE	SOIC	D	16		TBD	Call TI	Call TI	-40 to 85	UCC2917D	
UCC2917N	OBSOLETE	PDIP	N	16		TBD	Call TI	Call TI	-40 to 85	UCC2917N	
UCC3917D	OBSOLETE	SOIC	D	16		TBD	Call TI	Call TI	0 to 70	UCC3917D	
UCC3917DTR	OBSOLETE	SOIC	D	16		TBD	Call TI	Call TI	0 to 70	UCC3917D	
UCC3917N	OBSOLETE	PDIP	N	16		TBD	Call TI	Call TI	0 to 70	UCC3917N	

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

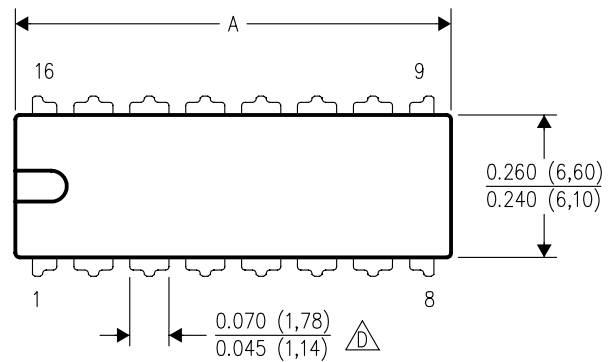
Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

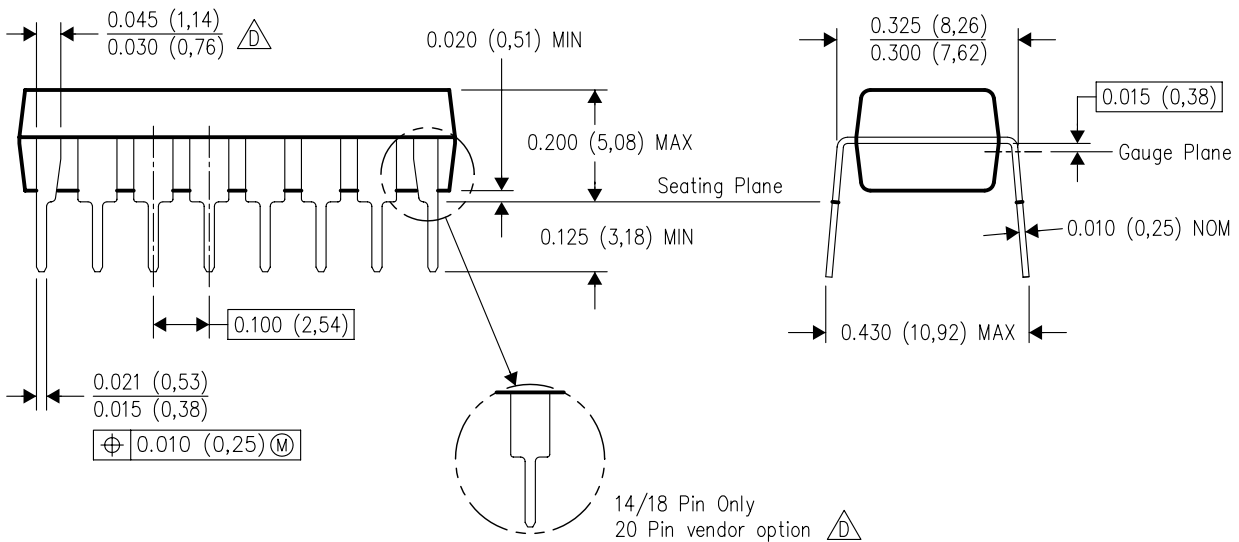
N (R-PDIP-T**)

16 PINS SHOWN

PLASTIC DUAL-IN-LINE PACKAGE



PINS **	14	16	18	20
DIM				
A MAX	0.775 (19,69)	0.775 (19,69)	0.920 (23,37)	1.060 (26,92)
A MIN	0.745 (18,92)	0.745 (18,92)	0.850 (21,59)	0.940 (23,88)
MS-001 VARIATION	AA	BB	AC	AD



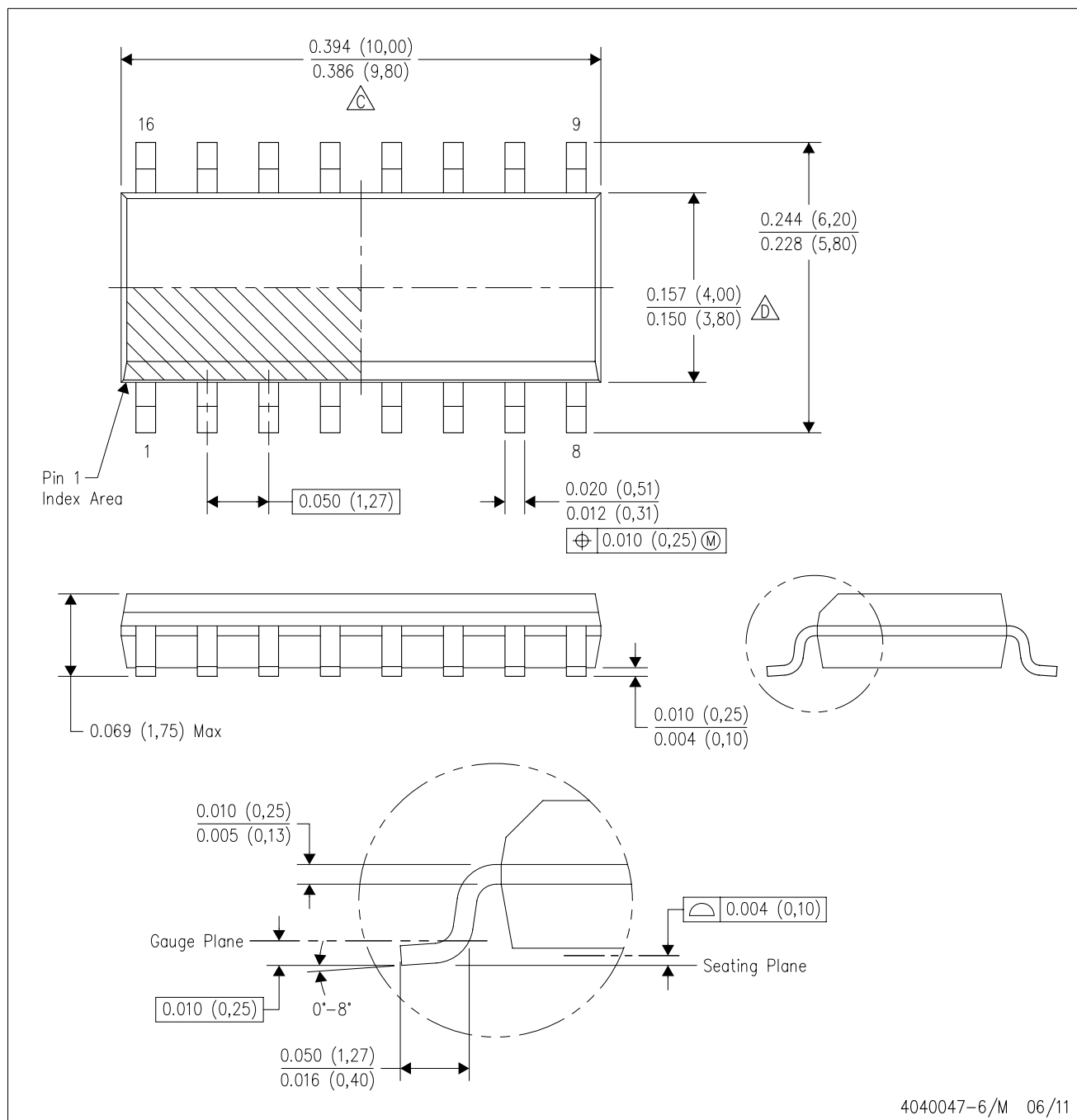
14/18 Pin Only
20 Pin vendor option

4040049/E 12/2002

- NOTES:
- A. All linear dimensions are in inches (millimeters).
 - B. This drawing is subject to change without notice.
 - Falls within JEDEC MS-001, except 18 and 20 pin minimum body length (Dim A).
 - The 20 pin end lead shoulder width is a vendor option, either half or full width.

D (R-PDSO-G16)

PLASTIC SMALL OUTLINE



NOTES:

- A. All linear dimensions are in inches (millimeters).
- B. This drawing is subject to change without notice.
- $\triangle C$ Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.006 (0,15) each side.
- $\triangle D$ Body width does not include interlead flash. Interlead flash shall not exceed 0.017 (0,43) each side.
- E. Reference JEDEC MS-012 variation AC.

IMPORTANT NOTICE

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, enhancements, improvements and other changes to its semiconductor products and services per JESD46, latest issue, and to discontinue any product or service per JESD48, latest issue. Buyers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All semiconductor products (also referred to herein as "components") are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its components to the specifications applicable at the time of sale, in accordance with the warranty in TI's terms and conditions of sale of semiconductor products. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by applicable law, testing of all parameters of each component is not necessarily performed.

TI assumes no liability for applications assistance or the design of Buyers' products. Buyers are responsible for their products and applications using TI components. To minimize the risks associated with Buyers' products and applications, Buyers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any patent right, copyright, mask work right, or other intellectual property right relating to any combination, machine, or process in which TI components or services are used. Information published by TI regarding third-party products or services does not constitute a license to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of significant portions of TI information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. TI is not responsible or liable for such altered documentation. Information of third parties may be subject to additional restrictions.

Resale of TI components or services with statements different from or beyond the parameters stated by TI for that component or service voids all express and any implied warranties for the associated TI component or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Buyer acknowledges and agrees that it is solely responsible for compliance with all legal, regulatory and safety-related requirements concerning its products, and any use of TI components in its applications, notwithstanding any applications-related information or support that may be provided by TI. Buyer represents and agrees that it has all the necessary expertise to create and implement safeguards which anticipate dangerous consequences of failures, monitor failures and their consequences, lessen the likelihood of failures that might cause harm and take appropriate remedial actions. Buyer will fully indemnify TI and its representatives against any damages arising out of the use of any TI components in safety-critical applications.

In some cases, TI components may be promoted specifically to facilitate safety-related applications. With such components, TI's goal is to help enable customers to design and create their own end-product solutions that meet applicable functional safety standards and requirements. Nonetheless, such components are subject to these terms.

No TI components are authorized for use in FDA Class III (or similar life-critical medical equipment) unless authorized officers of the parties have executed a special agreement specifically governing such use.

Only those TI components which TI has specifically designated as military grade or "enhanced plastic" are designed and intended for use in military/aerospace applications or environments. Buyer acknowledges and agrees that any military or aerospace use of TI components which have **not** been so designated is solely at the Buyer's risk, and that Buyer is solely responsible for compliance with all legal and regulatory requirements in connection with such use.

TI has specifically designated certain components as meeting ISO/TS16949 requirements, mainly for automotive use. In any case of use of non-designated products, TI will not be responsible for any failure to meet ISO/TS16949.

Products

Audio	www.ti.com/audio
Amplifiers	amplifier.ti.com
Data Converters	dataconverter.ti.com
DLP® Products	www.dlp.com
DSP	dsp.ti.com
Clocks and Timers	www.ti.com/clocks
Interface	interface.ti.com
Logic	logic.ti.com
Power Mgmt	power.ti.com
Microcontrollers	microcontroller.ti.com
RFID	www.ti-rfid.com
OMAP Applications Processors	www.ti.com/omap
Wireless Connectivity	www.ti.com/wirelessconnectivity

Applications

Automotive and Transportation	www.ti.com/automotive
Communications and Telecom	www.ti.com/communications
Computers and Peripherals	www.ti.com/computers
Consumer Electronics	www.ti.com/consumer-apps
Energy and Lighting	www.ti.com/energy
Industrial	www.ti.com/industrial
Medical	www.ti.com/medical
Security	www.ti.com/security
Space, Avionics and Defense	www.ti.com/space-avionics-defense
Video and Imaging	www.ti.com/video

TI E2E Community

e2e.ti.com