# **NEO-M8L**

# u-blox M8 ADR modules with 3D sensors

# Continuous accurate navigation under all signal conditions

- · Integrated 3D sensors with speed information from vehicle
- · Continuous navigation during signal loss
- · Automatic configuration of wheel-tick/speed input
- · Real-time positioning up to 30 Hz rate
- · GPS/QZSS, GLONASS, BeiDou, Galileo
- Zero PPM program for automotive grade NEO-M8L-02A



NEO-M8L 12.2 x 16.0 x 2.4 mm

# **Product description**

The NEO-M8L 3D Automotive Dead Reckoning (ADR) modules combine GNSS, inertial sensing, and speed information from the vehicle to provide continuous and accurate positioning for Telematics, navigation and Vehicle-to-Everything applications.

Incorporating u-blox's latest advancements in multi-GNSS signal processing, the latest version of NEO-M8L delivers the ideal solution where navigation performance is the priority, regardless of GNSS signal quality or availability. In addition to the on-board sensors, NEO-M8L further eases installation with automatic configuration of speed or wheel-tick inputs, and compensation for in-vehicle antennas.

The intelligent combination of GNSS and sensor measurements enables accurate, real-time positioning, speed and heading information at rates up to 30 Hz, as essential for smooth and responsive interactive display. Access to native, high rate sensor data enables host applications to make full use of the receiver's assets.

The NEO-M8L includes u-blox's latest generation GNSS technology with multi-constellation reception including Galileo, GPS, GLONASS, BeiDou and QZSS. The module provides high sensitivity and fast GNSS signal acquisition and tracking

UART, USB, DDC (I2C compliant) and SPI interface options provide flexible connectivity and enable simple integration with most u-blox cellular modules.

NEO-M8L modules use GNSS chips qualified according to AEC-Q100 and are manufactured in ISO/TS 16949 certified sites. Qualification tests are performed as stipulated in the ISO16750 standard: "Road vehicles - Environmental conditions and testing for electrical and electronic equipment".

The NEO-M8L-02A automotive grade module adheres to automotive industry standard quality specifications and production flow.

#### **Product selector**

Model		Cat	egory				GNS	ss		Sup	oply	1	nter	face	s				Feat	ures	•			(	irad	е
	Standard Precision GNSS	High Precision GNSS	Dead Reckoning	Timing	GPS / QZSS	GLONASS	Galileo	BeiDou	Number of Concurrent GNSS	2.7 V - 3.6 V	3.0 V - 3.6 V	UART	USB	SPI	DDC (I <sup>2</sup> C compliant)	Programmable (Flash)	Data logging	Additional SAW	Additional LNA	RTC crystal	Oscillator	Built-in sensor	Timepulse	Standard	Professional	Automotive
NEO-M8L-0			ADR		•	•	•	•	3	•		•	•	٠	•	•	•			•	С	•	1			
NEO-M8L-02A			ADR			•	•		3			•			•						Т		1			

ADR = Automotive Dead Reckoning / UDR = Untethered Dead Reckoning

C = Crystal / T = TCXO





#### **Features**

Receiver type 72-channel u-blox M8 engine

GPS/QZSS L1 C/A, GLONASS L10F,

BeiDou B1I, Galileo E1B/C

SBAS L1 C/A: WAAS, EGNOS, MSAS, GAGAN

26 s

Nav. update rate Up to 30 Hz

Position accuracy Autonomous

Autonomous 2.5 m CEP with SBAS 1.5 m CEP

ADR position error 2 % of distance travelled

without GNSS

Acquisition Cold starts:

Aided starts: 3 s Reacquisition: 1 s

Sensitivity Tracking & Nav: -160 dBm¹
Cold starts: -148 dBm

Hot starts: -157 dBm

Assistance AssistNow GNSS Online

AssistNow GNSS Offline (up to 35 days) AssistNow Autonomous (up to 6 days) OMA SUPL & 3GPP compliant

Oscillator Crystal (NEO-M8L-0)

TCXO (NEO-M8L-02A)

RTC Built-in

Sensor Onboard 3D accelerometer and 3D

gyroscope

Supported antennas Active or passive antenna

Raw Data Code phase output

Navigation outputs Position, speed, acceleration, heading,

heading rate, attitude, time

Data-logger For position, velocity, time, and

odometer data

# **Electrical data**

Supplyvoltage 2.7 V to 3.6 V (NEO-M8L-0)

3.0 V to 3.6 V (NEO-M8L-02A)

Power consumption 29 mA @ 3.0 V

(Continuous, default concurrent mode)

Backup Supply 1.4 to 3.6 V

#### Interfaces

Serial interfaces 1 UART

1 USB V2.0 full speed 12 Mbit/s

1 SPI (optional) 1 DDC (I<sup>2</sup>C compliant)

Digital I/O Configurable timepulse

Timepulse Configurable 0.25 Hz to 10 MHz

Protocols NMEA, UBX binary, RTCM

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#### **Package**

24 pin LCC (Leadless Chip Carrier): 12.2 x 16.0 x 2.4 mm

Pinout

13 GND	NEO-M8	GND <b>L</b>	
14 LNA_EN 15 FWD	TOP VIEW	RF_IN GND	
16 RESERVED		VCC_RF	9
17 RESERVED		RESET_N	8
18 SDA / SPI C	_	VDD_USB USB_DP	_
20 TXD / SPI N		USB_DM	
21 RXD / SPI N		WHEELTICK	
22 V_BCKP 23 VCC		D_SEL	2
<b>24</b> GND	SA	FEBOOT_N	1

# Environmental data, quality & reliability

Operating temp. -40° C to 85° C Storage temp. -40° C to 85° C

RoHS compliant (lead-free)

Qualification according to ISO 16750

Manufactured and fully tested in ISO/TS 16949 certified production sites

Uses u-blox M8 chips qualified according to AEC-Q100

## Support products

u-blox M8 Evaluation Kits:

Easy-to-use kits to get familiar with u-blox M8 positioning technology, evaluate functionality, and visualize GNSS performance.

EVK-M8L u-blox M8 3D Dead Reckoning GNSS Evaluation

Kit; supports NEO-M8L modules

## **Product variants**

NEO-M8L-0 u-blox M8 GNSS LCC module with 3D

Dead Reckoning and onboard sensors,

Professional Grade

NEO-M8L-02A u-blox M8 GNSS LCC module with 3D

Dead Reckoning and onboard sensors,

Automotive Grade

#### **Further information**

For contact information, see www.u-blox.com/contact-us. For more product details and ordering information, see the product data sheet.

<sup>1</sup> Limited by FW for best DR performance