
**Nominal frequency (f0)**
**10 MHz**
**Features**

- SMD
- SC Cut Crystal
- hermetically sealed

**Application**

- Wander generation (Standard / ZLAN Group)  
MTIE & TDEV compliant with: - G.812(zR1)
- S3E compliant according GR1244

**Performance Specifications**

Frequency stabilities					
Parameter	Min	Typical	Max	Units	Condition
Over all (df/f0)	-4.6		+4.6	ppm	-40...85°C
initial tolerance (df/f0)	-200		+200	ppb	@25 °C
vs. supply voltage change (df/f)	-2		+2	ppb	static; 3.3 V ±5 %
vs. load change (df/f)	-2		+2	ppb	static; Load +5 % -5 %
vs. aging / day (df/f)	-0.3		+0.3	ppb	after 30 days ; @ 25 °C
vs. aging / year (df/f)	-60		+60	ppb	after 30 days ; @ 25 °C
vs. operating temp. range (df/f@25°C)			1	ppb [pk-pk]	-10...70°C
			2	ppb [pk-pk]	-40..85°C
Holdover/Drift over 8 hours			3.8	μsec	temperature change of +5°C or -5°C after Holdover starts. (slope 0,5°C/ min); no voltage supply change and load change; To fulfill with an 4 sigma (99.38%) probability

Frequency stabilities					
Parameter	Min	Typical	Max	Units	Condition
Holdover/Drift over 4 hours		1	1.5	$\mu\text{sec}$	temperature change of +5°C or -5°C after Holdover starts. (slope 0,5°C/ min); no voltage supply change and load change; To fulfill with an 4 sigma (99.38%) probability
		0.6	0.9	$\mu\text{sec}$	temperature change of +2°C or -2°C after Holdover starts. (slope 0,5°C/ min); no voltage supply change and load change; To fulfill with an 4 sigma (99.38%) probability
			1	$\mu\text{sec}$	temperature change of +5°C or -5°C after Holdover starts. (linear change; slope: 0.02083°C/min); no voltage supply change and load change; To fulfill with an 4 sigma (99.38%) probability
Holdover/Drift over 1 hours			0.27	$\mu\text{sec}$	temperature change of +5°C or -5°C after Holdover starts. (slope 0,5°C/ min); no voltage supply change and load change; To fulfill with an 4 sigma (99.38%) probability
Holdover/Drift over 30 minutes			0.13	$\mu\text{sec}$	temperature change of +5°C or -5°C after Holdover starts. (slope 0,5°C/ min); no voltage supply change and load change; To fulfill with an 4 sigma (99.38%) probability
Note:	For all Holdover/ Drift parameter a minimum power on time is required: see appendix page "recommended power on time after x days of power of"				

RF output					
Parameter	Min	Typical	Max	Units	Condition
Signal	LVCMOS				
Load	13.5	15	16.5	pF	
Rise Time			5	ns	@10 to 90 %Vout
Fall Time			5	ns	@90 to 10 %Vout
Duty cycle	45		55	%	@1.65 V
V Low			0.4	V	
V High	2.4			V	
Sub Harmonics			-40	dBc	
Spurious			-90	dBc	

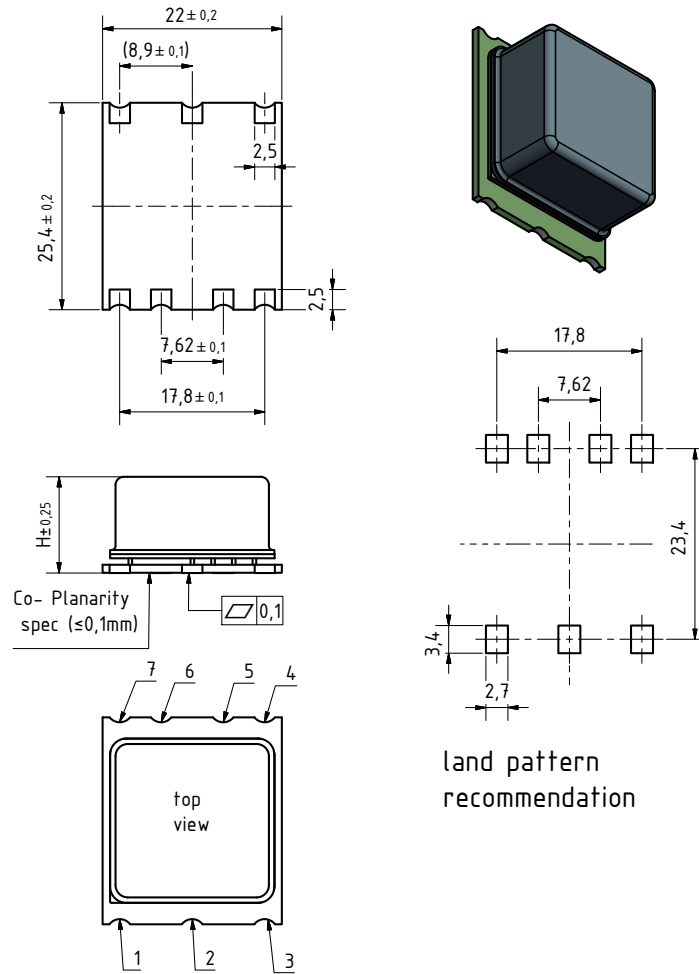
Supply voltage					
Parameter	Min	Typical	Max	Units	Condition
Supply voltage (Vs)	3.14	3.3	3.47	V	
Current consumption steady state			400	mA	@ Vsnom & 25 °C
			700	mA	@ Vsnom & -40 °C
Current consumption during warm up			1200	mA	@ Vs

Additional Parameters					
Parameter	Min	Typical	Max	Units	Condition
Warm up time			5	min	@ 25 °C to final frequency
Phase Noise		-80		dBc/Hz	@1Hz
		-120		dBc/Hz	@10Hz
		-130		dBc/Hz	@100Hz
		-135		dBc/Hz	@1kHz
		-142		dBc/Hz	@10kHz
		-143		dBc/Hz	@100kHz
		-150		dBc/Hz	@1MHz
Processing & Packing	handling&processing note				
Jitter		0.7		psec (RMS)	@ 12kHz to 5MHz

Additional Environmental Conditions	
Parameter	Description
RoHS compliance	100% RoHS 6 compliant
Washable	washable device
MSL-Level	1
ESD HBM	JESD22-A114F Class 1C - 10* 2000V
Mechanical Shock	MIL-STD-202 Meth 213B Cond. C - 100g 6ms 6 shocks in each direction
Vibration, Sine	JESD22-B103 Cond.2 - 10g 10-2000Hz 4x in each 3 axis 4min sweep time
Moisture Sen. Level	JESD22-A113-B - only if > MSL 1
Solderability	J-STD-002C Cond. A, Trough hole device; Cond.B, SMD ( correspond to MIL-STD-883 Meth 2003) - 255°C (dipping Time 5 ±0,5sec.) Dip&Look with 8h damp pre-treatment: solder wetting >95%
High temp operating life(HTOL)	MIL-STD-202 Meth108A Cond C - 1000h @ 105°C under voltage
Low temp operating life(LTOL)	IEC 60068-2-1 Cond. Ae - Ta= -40°C, >1000 hours with bias for OCXO
Reflow Simulation Test	MIL-STD-202G Meth 210F Cond. K - Total 3x Lead free profile (for SMD)
Temperature Cycling	MIL-STD-883G Meth.1010.8 Cond.B - 1000cycles -55/+125°C; cycle time 30 min.

Absolute Maximum Ratings					
Parameter	Min	Typical	Max	Units	Condition
Supply voltage (Vs)			5.5	V	
Operable temperature range	-40		+85	°C	
Storage temperature range	-40		+85	°C	

## G275



all units in mm

Enclosure Info	
Parameter	Description
Type	G275D
Height (H)	12.1 mm
Weight	9 g
Pin Connections	1: I.C. (Do not connect) 2: I.C. (Do not connect) 3: Vs (supply voltage input) 4: RF-Output 5: SCL (I2C - Interface) 6: SDA (I2C - Interface) 7: GND

Enclosure Info	
Parameter	Description
Marking	OX-2211-EAE-1090 10,000 MHz Ser.No. AYYWW * * pin-1 marking
Package cover material	Metal
Package base material	FR4

## Solder profile

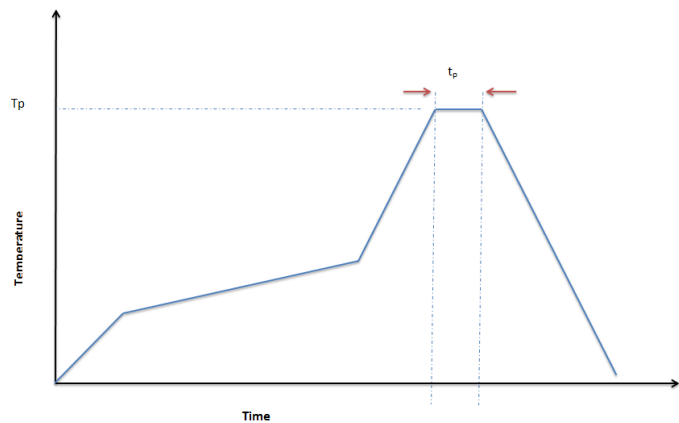
TP: max 260°C (@ solder joint, customer board level)

T<sub>p</sub>: max: 10...30 sec

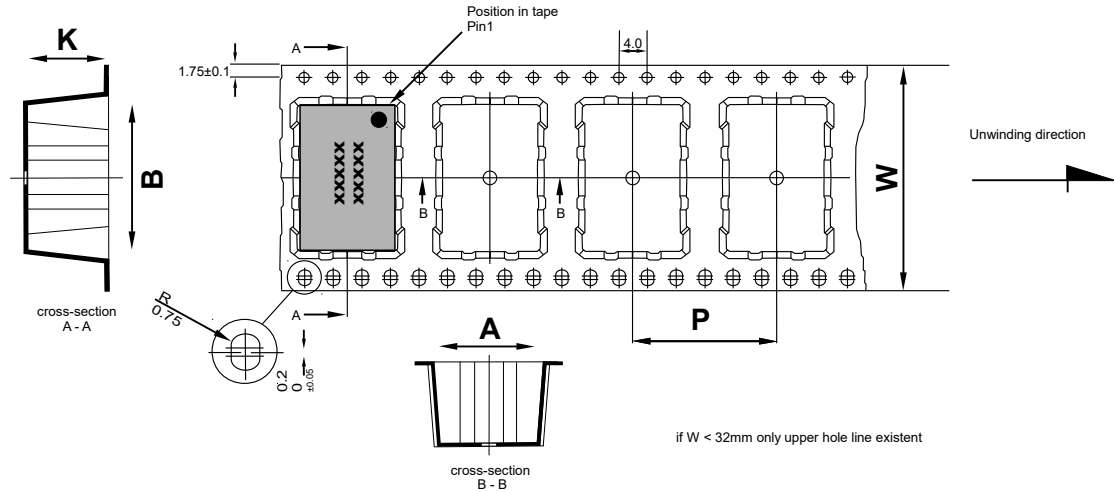
Additional Information:

This SMD oscillator has been designed for pick and place reflow soldering

SMD oscillators must be on the top side of the PCB during the reflow process.



## Standard shipping method

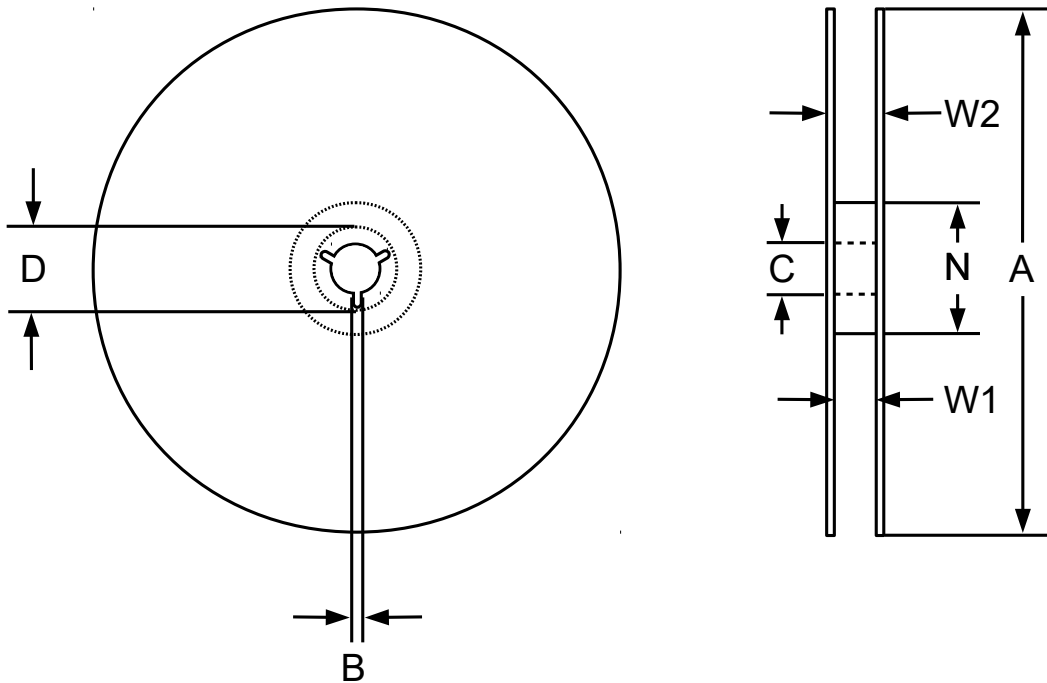


Dimension in mm:

A, B and K are dependent upon component dimensions  
production tolerance complying DIN IEC 286-3

All dimensions in millimeters unless otherwise stated

Tape Info						
Tape width W [mm]	Quantity per meter	Quantity per reel	P [mm]	A [mm]	B [mm]	K [mm]
44	35.7	100	28	22.5	25.9	12.8



Reel Info						
A [mm]	B [mm]	Size C [mm]	D [mm]	N [mm]	W1 [mm]	W2 [mm]
330	1.5	13	20.2	152	45.5	49.7

**Notes:** Unless otherwise stated all values are valid after warm-up time and refer to typical conditions for supply voltage, frequency control voltage, load, temperature (25°C).  
Subject to technical modification.

## Contact Information

**USA:**

100 Watts Street  
Mt Holly Springs, PA 17065

Tel: 1.717.486.3411  
Fax: 1.717.486.5920

**Europe:**

Landstrasse  
74924 Neckarbischofsheim  
Germany

Tel: +49 (0) 7268.801.0  
Fax: +49 (0) 7268.801.281



 **Vectron™ Oscillators**

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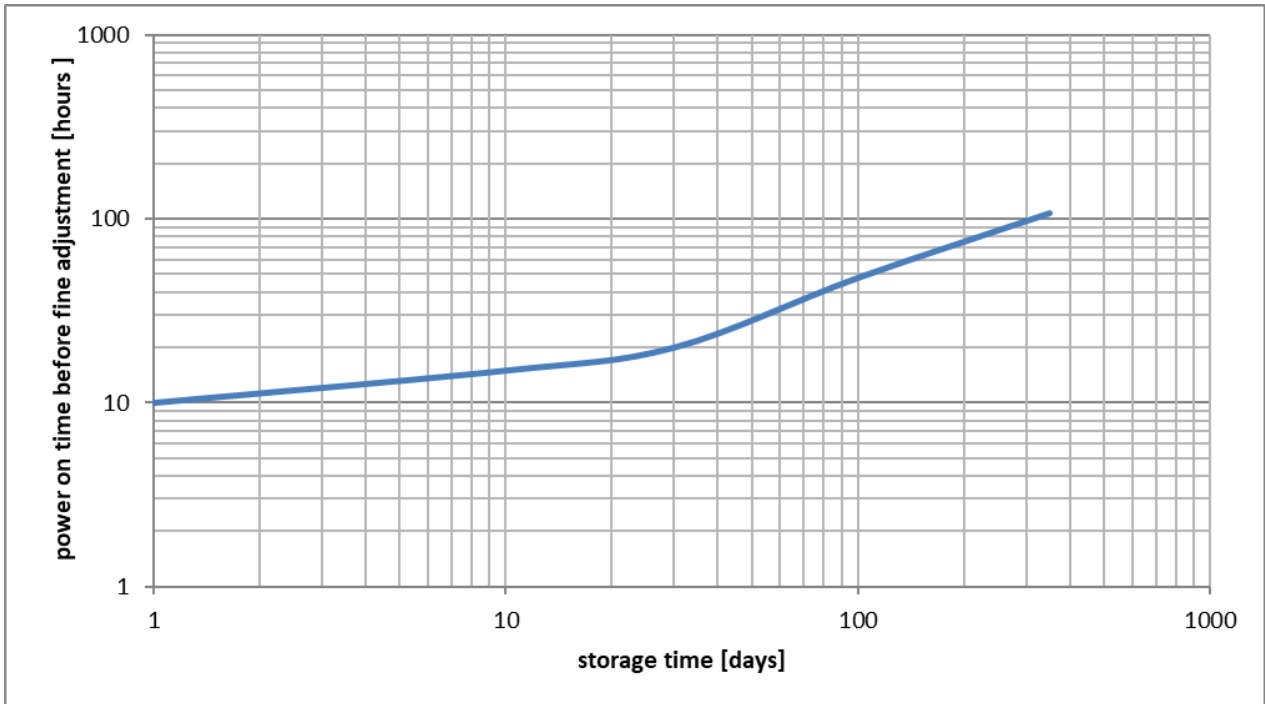
**Trademarks**

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recommended power on time after x days of power of

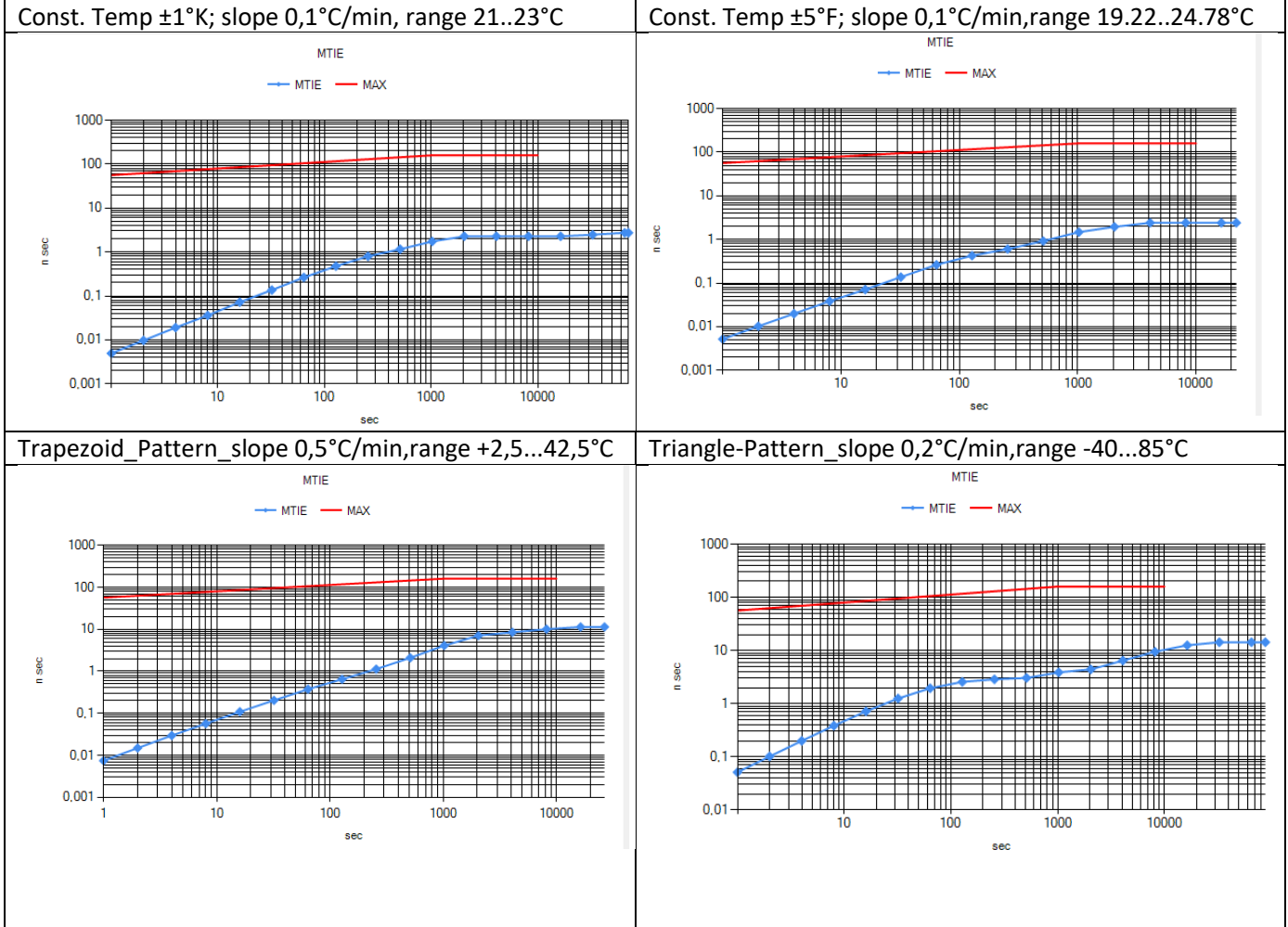


## Typical MTIE & TDEV performance

The following MTIE TDEV plots were generated from data collected on production devices over the course of a year and represent typical performance. Frequency is measured every second and converted to phase using Microchip's golden standard TimeMonitor software. Filtering is applied to the data per standards requirements, and limits where applicable, are shown in red. Additional information on standards and oscillator recommendations can be found in ZLAN-830 and ZLAN-3467 (formerly ZLAN-442 and ZLAN-68).

### Typical MTIE & TDEV performance for Oscillator Group R1 (G.812) requirements

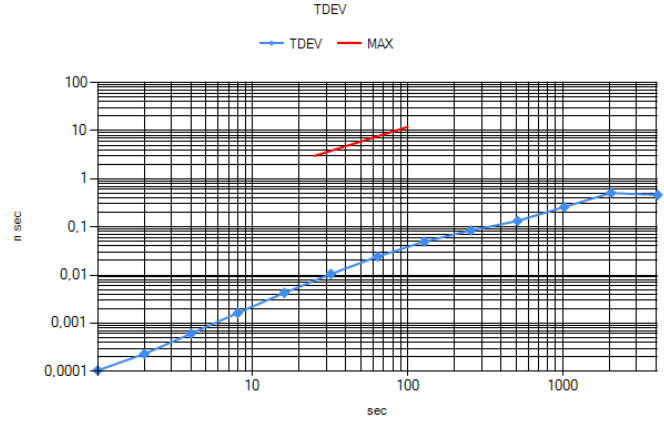
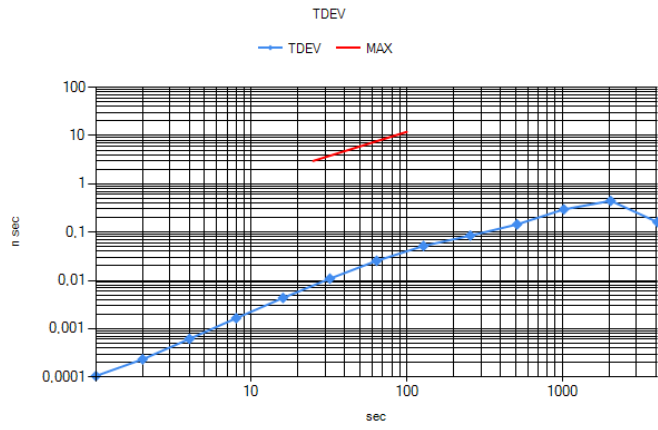
#### Typical MTIE performance; Oscillator group zR1 ( loop bandwidth 3mHz)



Typical TDEV performance; Oscillator group zR1 ( loop bandwidth 3mHz)

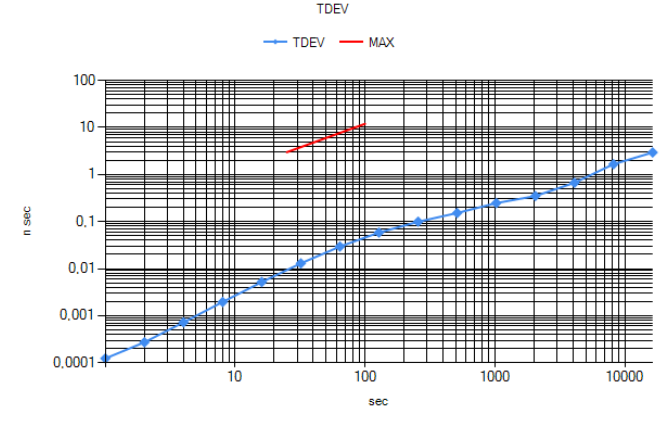
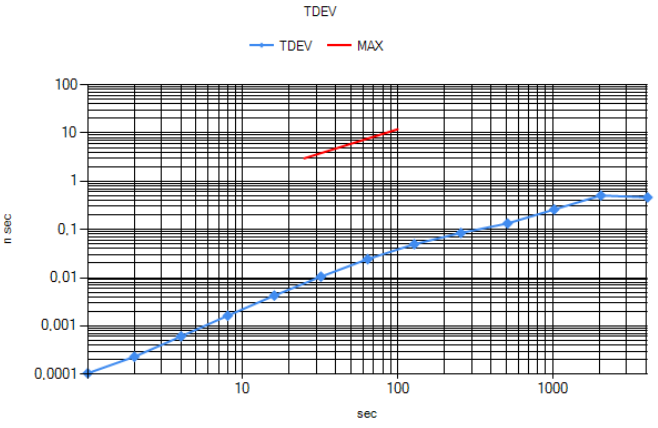
Const. Temp  $\pm 1^{\circ}\text{K}$ ; slope  $0,1^{\circ}\text{C}/\text{min}$ , range  $21..23^{\circ}\text{C}$

Const. Temp  $\pm 5^{\circ}\text{F}$ ; slope  $0,1^{\circ}\text{C}/\text{min}$ , range  $19.22..24.78^{\circ}\text{C}$



Trapezoid\_Pattern\_slope  $0,5^{\circ}\text{C}/\text{min}$ , range  $+2,5..42,5^{\circ}\text{C}$

Triangle-Pattern\_slope  $0,2^{\circ}\text{C}/\text{min}$ , range  $-40..85^{\circ}\text{C}$

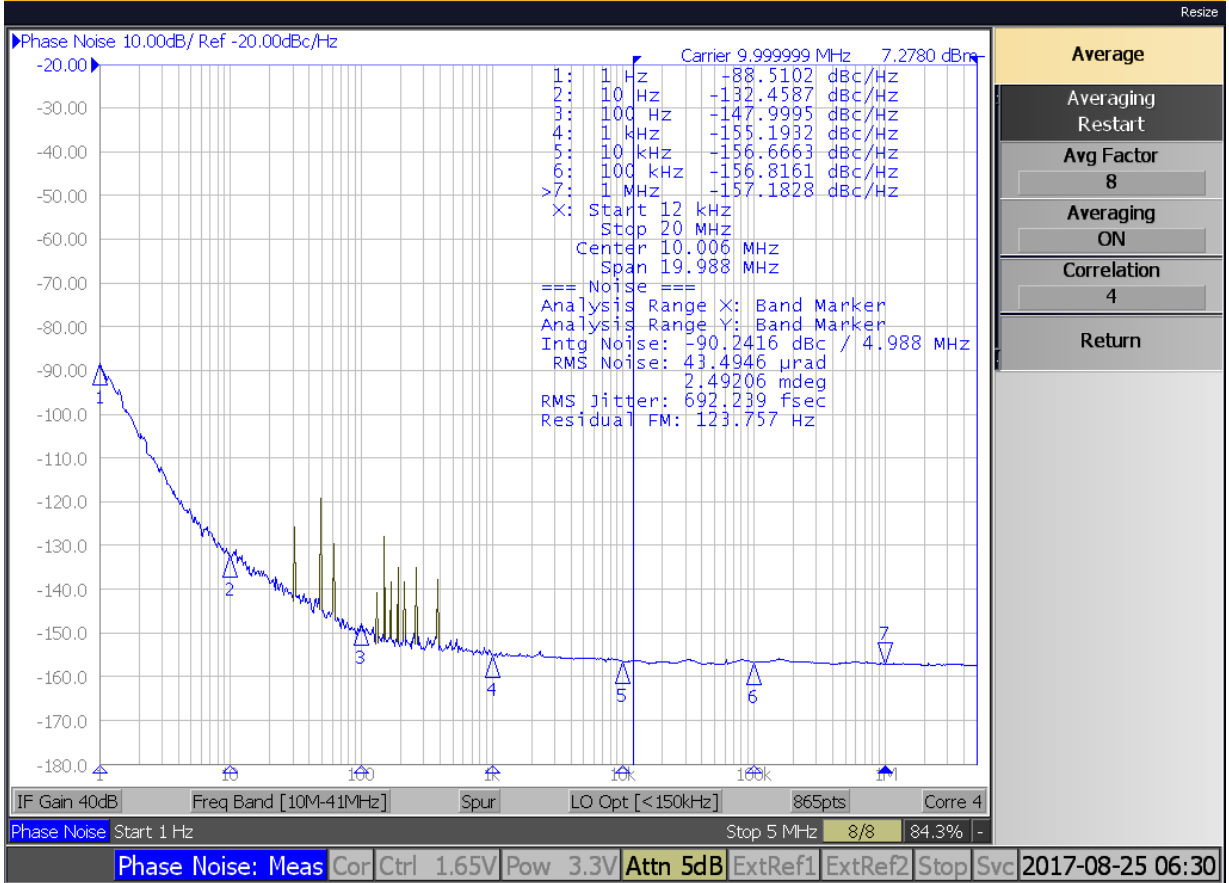


## Typical Performance Data

### Typical Phase Noise and Jitter

**OX-2211-EAE-1009-10M000**

Agilent E5052B Signal Source Analyzer



## Appendix (I<sup>2</sup>C Interface)

The I<sup>2</sup>C interface option is available since manufacturing DC 2301

### AP1 Electrical Definition

The I<sup>2</sup>C interface shall be compliant with the I<sup>2</sup>C-Bus specification for standard speed operation.

I<sup>2</sup>C Bus Voltage  $V_{I2C} = 2.8V$

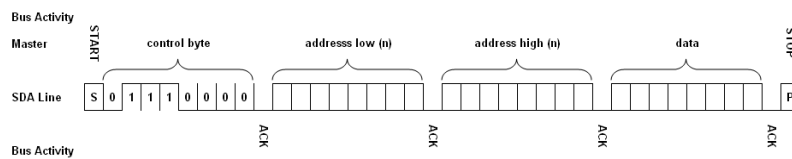
#### I<sup>2</sup>C-Device interface (SDA, SCL) Characteristics

Parameter	Min.	Typ.	Max.	Units	Condition
<b>DC Electrical Characteristics</b>					
High Level Input Voltage (V <sub>ih</sub> )	0.7*V <sub>I2C</sub>		V <sub>I2C</sub> +0.25	V <sub>dc</sub>	SDA and SCL
Low Level Input Voltage (V <sub>il</sub> )	-0.3		0.3 * V <sub>I2C</sub>	V <sub>dc</sub>	SDA and SCL
<b>Electrical Characteristics (Note 1)</b>					
SCL Clock Frequency	10		100	kHz	
<b>Communication (Note 2)</b>					
I <sup>2</sup> C-Device	I <sup>2</sup> C-Device 7-bit Address: 1010100				
1) Product is to communicate via industry standard I <sup>2</sup> C™ bus timing. I <sup>2</sup> C™ is a Phillips Semiconductor registered trademark.					

## AP2 I<sup>2</sup>C Protocol

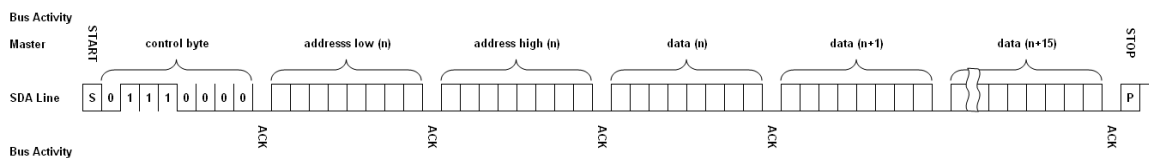
### AP2.1 Byte write operation

Following the Start condition from the master, the device code (7 bits) and the R/W bit is placed onto the bus by the master transmitter. This indicates to the addressed slave receiver that 2 bytes with a word address (little endian format) will follow once it has generated an Acknowledge bit during the ninth clock cycle. Therefore, the next 2 bytes transmitted by the master is the word address and will be written into the Address Pointer of the slave device. After receiving another Acknowledge signal from the slave device, the master device will transmit the data word to be written into the addressed memory location. The slave device acknowledges again and the master generates a Stop condition. This initiates the internal write cycle and, during this time, the slave device will not generate Acknowledge signals.



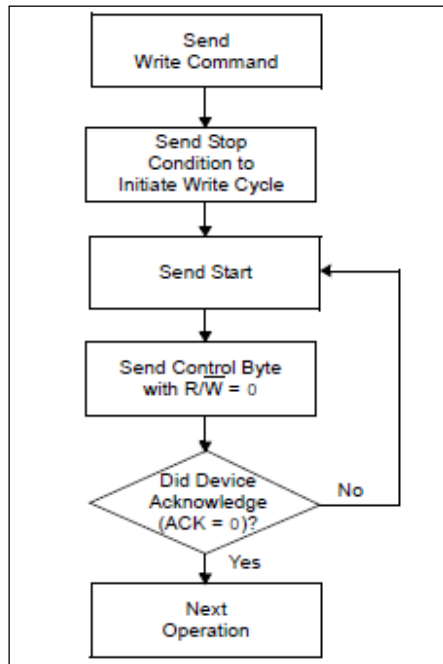
### AP2.2 Page write operation

The write control byte, word address and the first data byte are transmitted to the slave device in the same way as in a byte write. However, instead of generating a Stop condition, the master transmits up to 16 data bytes to the slave device, which are temporarily stored in the on chip page buffer and will be written into memory once the master has transmitted a Stop condition. Upon receipt of each word, the Address Pointer bits are internally incremented by '1'. As with the byte write operation, once the Stop condition is received an internal write cycle will begin.



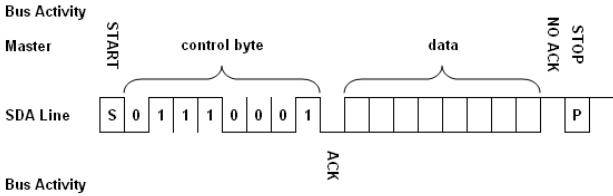
### AP2.3 Acknowledge polling

Since the device will not acknowledge during a write cycle, this can be used to determine when the cycle is complete (this feature can be used to maximize bus throughput). Once the Stop condition for a Write command has been issued from the master, the device initiates the internally-timed write cycle and ACK polling can then be initiated immediately. This involves the master sending a Start condition followed by the control byte for a Write command (R/W = 0). If the device is still busy with the write cycle, no ACK will be returned. If the cycle is complete, the device will return the ACK and the master can then proceed with the next Read or Write command. See the figure below for a flow diagram of this operation.



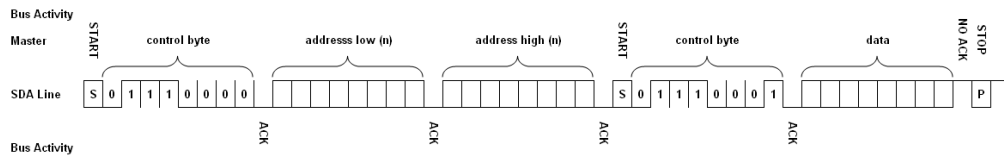
### AP2.4 Current address read

The slave device contains an address counter that maintains the address of the last word accessed, internally incremented by '1'. Therefore, if the previous access (either a read or write operation) was to address n, the next current address read operation would access data from address n + 1. Upon receipt of the slave address with R/W bit set to '1', the slave device issues an acknowledge and transmits the 8-bit data word. The master will not acknowledge the transfer, but does generate a Stop condition and the slave device discontinues transmission.



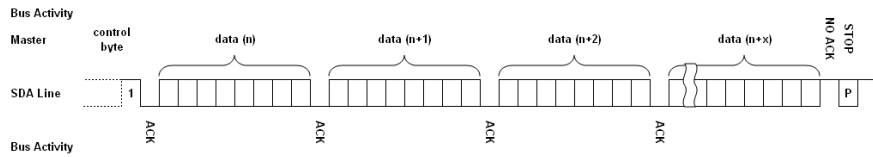
### AP2.5 Random read

Random read operations allow the master to access any memory location in a random manner. To perform this type of read operation, the word address must first be set. This is accomplished by sending the 2 byte word address to the slave device as part of a write operation. Once the word address is sent, the master generates a Start condition following the acknowledge. This terminates the write operation, but not before the internal Address Pointer is set. The master then issues the control byte again, but with the R/W bit set to a '1'. The slave device will then issue an acknowledge and transmit the 8-bit data word. The master will not acknowledge the transfer, but does generate a Stop condition and the slave device will discontinue transmission.



## AP2.6 Sequential read

Sequential reads are initiated in the same way as a random read, except that once the slave device transmits the first data byte, the master issues an acknowledge as opposed to a Stop condition in a random read. This directs the slave device to transmit the next sequentially addressed 8-bit word.





### Application

Unless otherwise noted, the products listed in the catalogue are designed for use with ordinary electrical devices, such as stationary and portable communication, control, measurement equipment etc.. They are designed and manufactured to meet a high degree of reliability (lifetime more than 15 years) under normal „commercial“ application conditions. Products dedicated for automotive and H-Rel applications are specifically identified for these applications.

If you intend to use these „commercial“ products for airborne, space or critical transport applications, nuclear power control, medical devices with a direct impact on human life, or other applications which require an exceptionally high degree of reliability or safety, please contact the manufacturer.

### Electrostatic Sensitivity

Crystal oscillators are electrostatic sensitive devices. Proper handling according to the established ESD handling rules as in IEC 61340-5-1 and EN 100015-1 is mandatory to avoid degradations of the oscillator performance due to damages of the internal circuitry by electrostatics. If not otherwise stated, our oscillators meet the requirements of the Human Body Model (HBM) according to JESD22-A114F.

### Handling

Excessive mechanical shocks during handling as well as manual and automatic assembly have to be avoided. If the oscillator was unintentionally dropped or otherwise subject to strong shocks, please verify that the electrical function is still within specification.

Improper handling may also deteriorate the coplanarity of bended leads of SMD components.

### Soldering

Oscillators can be processed using conventional soldering processes such as wave soldering, convection, infrared, and vapour phase reflow soldering under normal conditions. Solderability is guaranteed for one year storage under normal climatic conditions (+5°C to +35°C @ 40% to 75% relative humidity), however typically sufficient solderability –depending on the process – is maintained also for longer time periods. In cases of doubt, components older than one year should undergo a sample solderability test.

The recommended reflow solder profile for SMT components is according IPC/JEDEC J-STD-020 (latest revision)

SMD oscillators must be on the top side of the PCB during the reflow process.

After reflow soldering the frequency of the products may have shifted several ppm, which relaxes after several hours or days, depending on the products. For details please contact the manufacturer.

## **Cleaning**

Cleaning is only allowed for hermetically sealed oscillators. Devices with non hermetical enclosures (e.g. with trimmer holes) shall not be cleaned by soaking or in vapour, because residues from the cleaning process may penetrate into the interior, and degrade the performance.

Our products are laser marked. The marking of our oscillators is resistant to usual solvents, such as given in IEC 60068-2-45 Test XA. For applicable test conditions see IEC 60679-1.

Ultrasonic cleaning is usually not harmful to oscillators at ultrasonic frequencies of 20kHz at the sound intensities conventional in industry. Sensitive devices may suffer mechanical damage if subjected to 40kHz ultrasound at high sound pressure. In cases of doubt, please conduct tests under practical conditions with the oscillators mounted on the PC board.

## **Hermetical Seal**

If the device is specified as hermetically sealed, it meets the requirements of IEC 60679-1, i.e. for enclosures with a volume smaller than 4000mm<sup>3</sup> the leak rate is below 5\*10<sup>-8</sup> bar cm<sup>3</sup>/s, for larger enclosures it is below 1\*10<sup>-6</sup> bar cm<sup>3</sup>/s, tested according to IEC 60068-2-17 Test Qk.

Glass feed-throughs may be damaged as a result of mechanical overload, such as bending the connection leads or cutting them with an unappropriated tool. In order to avoid microcracking, the wire must be held fixed in position by a pressure pad between glass feed-through and the bending point during the bending process. Check: there should be no damaged edges on the glass feed-through after the bending.

## **Tape & Reel**

The packing in tape and reel is according to IEC 60286-3.

Details see tape & reel data sheets.

## **Qualification**

Vectron products are undergoing regular qualification/reliability tests as per product family definition. Results are available upon request. Customer specific qualification tests are subject to agreement.

If not otherwise stated, the product qualifications are performed according to IEC 60679-5 or other valid industry standards.

## **Screening**

Our oscillators are 100% tested, and all key manufacturing processes are controlled by Statistical Process Control (SPC). Additional screening is therefore usually not required.

On request, we can perform screening tests according to MIL-PRF-55310, class B for discrete or hybrid constructions of commercial (COTS) products. For special requirements see the High Reliability Clock section.

### **Demounting/Desoldering of Oscillator device for analysis:**

The removal or desoldering of oscillators from customer application after SMT process may cause damage to the device if not handled appropriately. It may lead to parametric change such as frequency shift (like OCXO: up to +/- 200 ppb) . It is utmost important to minimize the direct heat exposure to the device in order to avoid such effects. Use of hot air gun for desoldering should be avoided.

A mechanical stress could also destroy the part, if exposed to excessive mechanical shock after removal process. Appropriate shock protection & ESD designated packaging must be used to avoid any external mechanical shock for FA return process.

In general, the products\* withstand the tests listed in the following Table 1, which are based on valid industry standards.

**\*Additional note:** Test conditions could vary for different product families and individual product specifications depending on the customer as well as product requirements.

## Recommended Environmental Test Conditions

**Table 1**

Test	Test condition	Test Standard
Dimensions	acc. outline drawing	MIL-STD-883 Meth2016
External visual	no visible damage	MIL-STD-883 Meth2009
Internal visual	30-50x	MIL-STD-883 Meth2014
Electrostatic discharge (ESD) sensitivity testing Human Body Model (HBM)	10 discharges, both polarities, 1kV...8kV	JESD 22-A114F
Seal Fine/Gross Leak	only for hermetically sealed parts 100% tested	MIL-STD-883 Meth1014 A1/C4
Solderability	255°C (dipping Time 5 ±0,5sec.) Dip&Look with 8h damp pre-treatment: solder wetting >95%	J-STD-002C Cond. A, Trough hole device; Cond. B, SMD ( correspond to MIL-STD-883 Meth 2003)
Reflow Simulation Test	3X Lead free profile	J-STD-020D
Mechanical Shock	1. 100g 6ms 6 shocks in each direction; 2. 1500G 0,5ms 6 shocks in each direction.	1. MIL-STD-202 Meth 213B Cond. C; 2. MIL-STD-202 Meth 213B Cond. F (for ceramics parts).
Free fall	Test Ed procedure 1, 2 drops from 1m height	IEC 60068-2-32
Vibration, Sine	20g 20-2000Hz 4x in each 3 axis 4min sweep time	JESD22-B103 Cond.1
Vibration, random	optional on customers request	MIL-STD-202 Meth214A Figure 214-1
Temperature Cycling	1.1000 cycles - 55/+125°C; cycle time 30 min.; 2.1000 cycles - 40/+125°C;cycle time 30 min.	1. MIL-STD-883G Meth1010.8 Cond. B 2. JESD22-A104-D Cond. G
Low temperature operating Life (LTOL)	Ta= -40°C, >1000 h	IEC 60068-2-1
Steady State Temperature Humidity Bias Life Test	Non hermetic parts 85°C/85% RH 1008h	JESD22-A101-C
High Temperature Storage Operating Life (HTOL)	1000h @ 105°C under voltage	MIL-STD-202 Meth108A Cond C
Aktive Aging at Elevated Temperatures	1000h @ 85°C with fit calculation (for not OCXO)	MIL-PRF-55310 Meth.4.8.35
Aktive Aging at Room Temperature	1000h with fit calculation- only for OCXO @crystal operating temp.	MIL-PRF-55310 Meth.4.8.35
Immersion in cleaning solvents		IEC 60068-2-45 Test Xa ; IEC 60068-2-70 Test Xb (rubbing finger)