

# PIC16C65A → PIC16C65B Migration

#### **DEVICE MIGRATIONS**

This document is intended to describe the functional differences and the electrical specification differences that are present when migrating from one device to the next.

**Note:** This device has been designed to perform to the parameters of its data sheet. It has been tested to an electrical specification designed to determine its conformance with these parameters. Due to process differences in the manufacture of this device, this device may have different performance characteristics than its earlier version. These differences may cause this device to perform differently in your application than the earlier version of this device.

**Note:** The user should verify that the device oscillator starts and performs as expected. Adjusting the loading capacitor values and/or the oscillator mode may be required.

Table 1 shows the considerations that must be taken into account when migrating from the PIC16C65A to the PIC16C65B.

## **TABLE 1:** PIC16C65A → PIC16C65B DIFFERENCES

| Functional Differences due to Errata or Module Update |            |  |     |          |       |  |  |  |  |  |  |  |
|---|------------|--|-----|----------|-------|--|--|--|--|--|--|--|
| No.   | Module     | Difference   | H/W | S/W      | Prog. |  |  |  |  |  |  |  |
| 1   | ССР        | CCP Special Event Trigger clears Timer1.   | _   | 1        | _     |  |  |  |  |  |  |  |
| 2   |            | Compare mode drives pin correctly.   | _   | <b>✓</b> | _     |  |  |  |  |  |  |  |
| 3   | Timers     | Reading or writing TMR1H or TMR1L may affect TMR1H or TMR1L unexpectedly.  | _   | 1        | _     |  |  |  |  |  |  |  |
| 4   |            | WDT/TMR0 prescaler assignment changes do not affect TMR0 count.  | _   | <b>✓</b> | _     |  |  |  |  |  |  |  |
| 5   | SSP        | TMR2 SPI™ clock synchronized to start of SPI Transmission.   | _   | <b>✓</b> | _     |  |  |  |  |  |  |  |
| 6   |            | Can now transmit multiple words in SPI mode.   | _   | 1        | _     |  |  |  |  |  |  |  |
| 7   |            | Supports all four SPI modes. (Now uses SSP vs BSSP module.) See SSP module in the PICmicro™ Mid-Range MCU Family Reference Manual (DS33023). | _   | 1        | _     |  |  |  |  |  |  |  |
| 8   |            | I <sup>2</sup> C™ no longer generates ACK pulses when module is enabled.   | _   | 1        | _     |  |  |  |  |  |  |  |
| 9   | USART      | Async receive errors due to BRGH setting corrected.  | _   | <b>√</b> | _     |  |  |  |  |  |  |  |
| 10  | Oscillator | Tost delay may be skipped when waking from SLEEP.  | _   | 1        | _     |  |  |  |  |  |  |  |
| 11  | RESET      | Short MCLR pulses may cause improper operation on the PIC16C65B.   | 1   | _        | _     |  |  |  |  |  |  |  |
| 12  |            | Operating voltage and frequency ranges have been redefined.  | 1   | _        | _     |  |  |  |  |  |  |  |

H/W - Issues may exist with regard to the application circuits.

S/W - Issues may exist with regard to the user program.

Prog. - Issues may exist when writing the program to the controller.

TABLE 2: ELECTRICAL SPECIFICATION DIFFERENCES

| Param           |                      | Characteristic   |             | PIC16C65A       |      |                 | PIC16C65B                         |      |                                 | T           |
|-----------------|----------------------|--|-------------|-----------------|------|-----------------|-----------------------------------|------|---------------------------------|-------------|
| No.             | Symbol               |  |             | Min             | Тур† | Max             | Min                               | Тур† | Max                             | Unit        |
| Core            |                      |  |             |                 |      |                 |                                   |      |                                 |             |
| D001<br>D001A   | VDD                  | Supply Voltage XT, LP and RC mode HS mode BOR enabled (Note 1) |             | 4.0<br>4.5<br>— |      | 6.0<br>5.5<br>— | 4.0<br><b>4.0</b><br><b>V</b> BOR |      | <b>5.5</b><br>5.5<br><b>5.5</b> | V<br>V<br>V |
| D005            | VBOR                 | Brown-out Reset \  | 3.7         | 4.0             | 4.3  | 3.65            | _                                 | 4.35 | V                               |             |
| D150            | Vod                  | Open Drain High \  | _           | _               | 14.0 | _               |                                   | 8.5  | V                               |             |
| SSP in S        | SPI mode             |  |             |                 |      | •               |                                   |      |                                 |             |
| 71              | TscH                 | SCK input high   | Continuous  | Tcy+20          | _    | _               | 1.25Tcy + 30                      | _    | _                               | ns          |
| 71A             |                      | time (Slave mode)  | Single Byte |                 |      |                 | 40                                | _    | 1                               | ns          |
| 72              | TscL                 | SCK input low  | Continuous  | Tcy+20          |      | _               | 1.25Tcy + 30                      |      |                                 | ns          |
| 72A             |                      | time (Slave mode)  | Single Byte |                 |      |                 | 40                                |      |                                 | ns          |
| 73              | TdiV2scH<br>TdiV2scL |  |             | 50              | _    | _               | 100                               | _    | _                               | ns          |
| 73A<br>(Note 2) | Тв2в                 | Last clock edge of Byte1 to the 1st clock edge of Byte2        |             | _               | _    | _               | 1.5Tcy + 40                       |      | _                               | ns          |
| 74              | TscH2diL<br>TscL2diL | Hold time of SDI data input to SCK edge                        |             | 50              | _    | _               | 100                               | _    | _                               | ns          |
| 75              | TdoR                 | SDO data output  | PIC16CXX    | _               | 10   | 25              | _                                 | 10   | 25                              | ns          |
|                 |                      | rise time  | PIC16LCXX   |                 |      |                 | _                                 | 20   | 45                              | ns          |
| 78              | TscR                 | SCK output rise  | PIC16CXX    | _               | 10   | 25              | _                                 | 10   | 25                              | ns          |
|                 |                      | time (Master mode)   | PIC16LCXX   |                 |      |                 | _                                 | 20   | 45                              | ns          |
| 80              | TscH2doV             | SDO data output  | PIC16CXX    | _               |      | 50              | _                                 | _    | 50                              | ns          |
|                 | TscL2doV             | valid after SCK edge   | PIC16LCXX   |                 |      |                 | _                                 | _    | 100                             | ns          |
| 83              | TscH2ssH<br>TscL2ssH |  |             | _               | _    | _               | 1.5Tcy + 40                       |      | _                               | ns          |

<sup>†</sup> Data in "Typ" column is at 5V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: When BOR is enabled, the device will operate until VDD drops below VBOR.

**<sup>2:</sup>** Specification 73A is only required if specifications 71A and 72A are used.

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