
SAM9G45 Microcontroller Schematic Checklist

ARM-based Embedded MPU

Scope

This application note is a schematic review checklist for systems embedding the Atmel® ARM®-based SAM9G45 embedded MPU.

It provides the user with the requirements regarding the different pin connections that must be considered before starting any new board design. The application note also describes the minimum hardware resources required to quickly develop an application with the SAM9G45. It does not consider PCB layout constraints.

It also provides recommendations regarding low-power design constraints to minimize power consumption.

This application note is not intended to be exhaustive. Its objective is to cover as many configurations of use as possible.

The checklist contains a column for use by designers, making it easy to track and verify each line item.

Table of Contents

Scope	1
Table of Contents	2
1. Reference Documentation	3
2. Schematic Checklist	4
3. External Bus Interface (EBI) Hardware Interface	13
4. High-Speed USB: Recommendations for Use	16
4.1 Power Supply	16
4.2 DDR2 Interface	16
4.3 Ground Layout	16
5. Boot Program Hardware Constraints	18
5.1 Boot Program Supported Crystals (MHz)	18
5.2 NAND Flash Boot	18
5.3 SD Card Boot	18
5.4 Serial and DataFlash® Boot	19
5.5 TWI EEPROM Boot	19
5.6 SAM-BA® Boot	19
Revision History	20

1. Reference Documentation

Before starting to work with this application note, it is strongly recommended to check the latest documents available for the SAM9G45 device on the Atmel web site.

[Table 1-1](#) gives the document titles that provide additional information to support this application note.

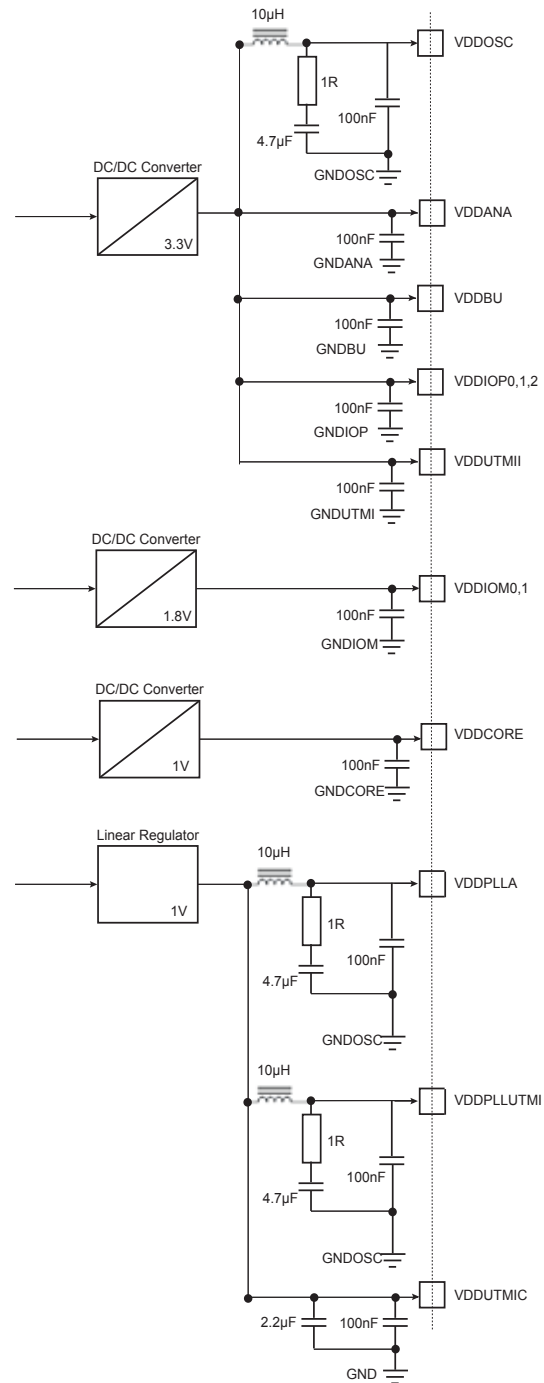
Table 1-1. Reference Documents

Information	Document Title
User Manual Electrical/Mechanical Characteristics Ordering Information Errata	SAM9G45 Datasheet
Internal architecture of processor ARM/Thumb instruction sets Embedded in-circuit-emulator	ARM9EJ-S™ Technical Reference Manual ARM926EJ-S™ Technical Reference Manual
Evaluation Kit User Guide	AT91SAM9M10-G45-EK User Guide
Using SDRAM on AT91SAM9 Microcontrollers	Using SDRAM on AT91SAM9 Microcontrollers Application Note
NAND Flash Support in AT91SAM9 Microcontrollers	NAND Flash Support in AT91SAM9 Microcontrollers Application Note
Implementation of DDR2 on AT91SAM9G45 Devices	Implementation of DDR2 on AT91SAM9G45 Devices Application Note

2. Schematic Checklist

Caution: The SAM9G45 board design must comply with the power-up and power-down sequence guidelines provided in the datasheet to guarantee reliable operation of the device.

1.0V, 1.8V and 3.3V Power Supplies Schematic Example⁽¹⁾

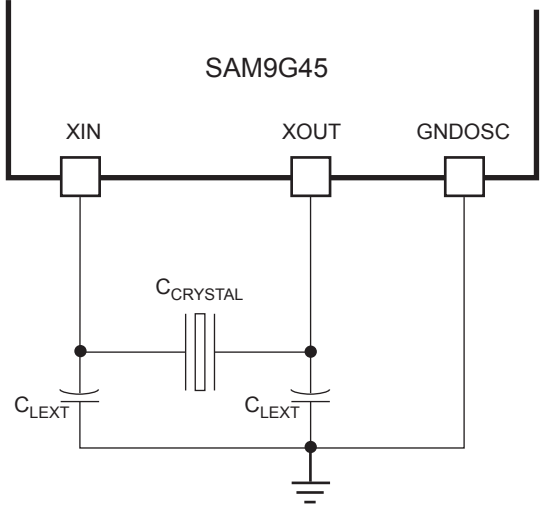


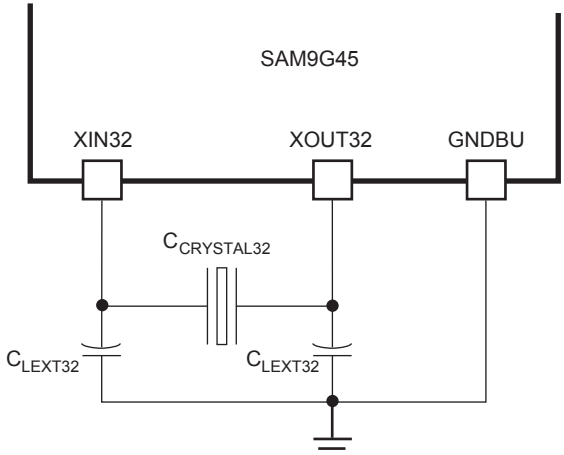
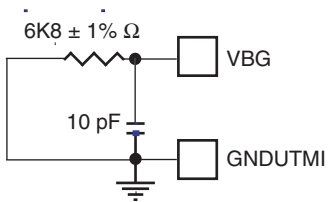
⁽¹⁾ These values are given only as a typical example.

☒	Signal Name	Recommended Pin Connection	Description
	VDDCORE	0.9V to 1.1V Decoupling capacitor (100 nF) ⁽¹⁾⁽²⁾	Powers the device. Decoupling/filtering capacitors must be added to improve startup stability and reduce source voltage drop. Supply ripple must not exceed 20 mVrms.
	VDDPLLA	0.9V to 1.1V Decoupling/filtering RLC circuit ⁽¹⁾	Powers the PLLA cell. The VDDPLLA power supply pin draws small current, but it is noise sensitive. Care must be taken in VDDPLLA power supply routing, decoupling and also on bypass capacitors. Supply ripple must not exceed 10 mVrms.
	VDDPLLUTMI	0.9V to 1.1V Decoupling/filtering RLC circuit ⁽¹⁾	Powers the PLLUTMI cell. The VDDPLLUTMI power supply pin draws small current, but is noise-sensitive. Care must be taken in VDDPLLUTMI power supply routing, decoupling and also on bypass capacitors. Supply ripple must not exceed 10 mVrms.
	VDDBU	1.8V to 3.6V Decoupling capacitor (100 nF) ⁽¹⁾⁽²⁾	Powers the backup unit. (Slow clock oscillator, on-chip RC and a part of the System Controller). Supply ripple must not exceed 30 mVrms.
	VDDOSC	1.65V to 3.6V Decoupling/filtering RLC circuit ⁽¹⁾	Powers the main oscillator cells. The VDDOSC power supply pin draws small current, but is noise-sensitive. Care must be taken in VDDOSC power supply routing, decoupling and also on bypass capacitors. Supply ripple must not exceed 30 mVrms.
	VDDIOM0	1.65V to 1.95V Decoupling capacitor (100 nF) ⁽¹⁾⁽²⁾ If the DDRSDR Controller is not used, VDDIOM0 must be tied to GNDIOM.	Powers the DDR2/LPDDR I/O lines. Decoupling/filtering capacitors must be added to improve start-up stability and reduce source voltage drop.

☑	Signal Name	Recommended Pin Connection	Description
	VDDIOM1	1.65V to 1.95V or 3.0V to 3.6V Decoupling capacitor (100 nF) ⁽¹⁾⁽²⁾	Powers the External Bus Interface I/O lines. Dual voltage range supported. The I/O drives are selected by programming the EBI_DRIVE field in the CCFG_EBICSA register. At power-up, the high drive mode for 3.3V memories is selected. Decoupling/filtering capacitors must be added to improve start-up stability and reduce source voltage drop.
	VDDUTMII	3V to 3.6V Decoupling capacitor (100 nF) ⁽¹⁾⁽²⁾	Powers the USB device and host UTMI+ interface. Must always be connected even if the USB is not used. Decoupling/filtering capacitors must be added to improve startup stability and reduce source voltage drop.
	VDDUTMIC	0.9V to 1.1V Decoupling/filtering capacitors (100 nF and 2.2μF) ⁽¹⁾⁽²⁾	Powers the USB device and host UTMI+ core. Must always be connected even if the USB is not used. Decoupling/filtering capacitors must be added to improve startup stability and reduce source voltage drop.
	VDDIOP0 VDDIOP1 VDDIOP2	1.65V to 3.6V Decoupling/filtering capacitors (100 nF) ⁽¹⁾⁽²⁾	Powers the peripheral I/O lines. Decoupling/filtering capacitors must be added to improve startup stability and reduce source voltage drop.
	VDDANA	3.0V to 3.6V Decoupling/filtering RLC circuit ⁽¹⁾ Application-dependent	Powers the Analog to Digital Converter (ADC) and some PIOD I/O lines.
	GNDCORE	Core chip ground	GNDCORE pins are common to VDDCORE pins. GNDCORE pins should be connected as shortly as possible to the system ground plane.
	GNDBU	Backup ground	GNDBU pin is provided for VDDBU pins. GNDBU pin should be connected as shortly as possible to the system ground plane.
	GNDIOM	DDR2 and EBI I/O lines ground	GNDIOM pins are common to VDDIOM0 and VDDIOM1 pins. GNDIOM pins should be connected as shortly as possible to the system ground plane.
	GNDIOP	Peripherals and ISI I/O lines ground	GNDIOP pins are common to VDDIOP0, VDDIOP1 and VDDIOP2 pins. GNDIOP pins should be connected as shortly as possible to the system ground plane.

☑	Signal Name	Recommended Pin Connection	Description
	GNDOSC	PLLA, PLLUTMI and Oscillator ground	GNDOSC pin is provided for VDDOSC, VDDPLLA and VDDPLLUTMI pins. GNDOSC pin should be connected as shortly as possible to the system ground plane.
	GNDUTMI	UDPHS and UHPHS UTMI+ core and interface ground	GNDUTMI pins are common to VDDUTMII and VDDUTMIC pins. GNDUTMI pins should be connected as shortly as possible to the system ground plane.
	GNDANA	Analog ground	GNDANA pins are common to VDDANA pins. GNDANA pins should be connected as shortly as possible to the system ground plane.

☑	Signal Name	Recommended Pin Connection	Description
Clock, Oscillator and PLL			
	XIN XOUT 12MHz Main Oscillator in Normal Mode	Crystals between 8 and 16 MHz USB high-speed (not full-speed) Host and Device peripherals need a 12 MHz clock. Capacitors on XIN and XOUT (crystal load capacitance dependent)	Crystal load capacitance to check ($C_{CRYSTAL}$).  Example: for a 12 MHz crystal with a load capacitance of $C_{CRYSTAL} = 15$ pF, external capacitors are required: $C_{LEXT} = 22$ pF. Refer to the electrical specifications of the SAM9G45 datasheet
	XIN XOUT 12MHz Main Oscillator in Bypass Mode	XIN: clock source input XOUT: can be left unconnected USB high-speed (not full-speed) Host and Device peripherals need a 12 MHz clock.	VDDOSC square wave signal External clock source up to 50 MHz Duty Cycle: 40 to 60% Refer to the electrical specifications of the SAM9G45 datasheet

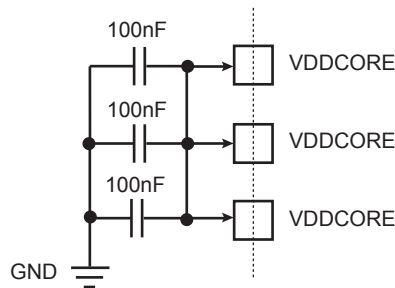
☑	Signal Name	Recommended Pin Connection	Description
	XIN32 XOUT32 Slow Clock Oscillator	32.768 kHz Crystal Capacitors on XIN32 and XOUT32 (crystal load capacitance dependent)	Crystal load capacitance to check ($C_{CRYSTAL32}$).  Example: for a 32.768 kHz crystal with a load capacitance of $C_{CRYSTAL32} = 12.5$ pF, external capacitors are required: $C_{LEXT32} = 19$ pF. Refer to the electrical specifications of the SAM9G45 datasheet
	XIN32 XOUT32 Slow Clock Oscillator in Bypass Mode	XIN32: external clock source XOUT32: can be left unconnected	VDDBU square wave signal External clock source up to 44 kHz Refer to the electrical specifications of the SAM9G45 datasheet
	VBG	0.9 - 1.1V ⁽⁵⁾	Bias Voltage Reference for USB To reduce as much as possible the noise on VBG pin please check the Layout consideration below: - VBG path as short as possible - ground connection to GNDUTMI  VBG can be left unconnected if USB is not used. Refer to the signal description of the SAM9G45 datasheet.

☒	Signal Name	Recommended Pin Connection	Description
ICE and JTAG⁽³⁾			
	TCK	Pull-up (100 kOhm) ⁽¹⁾	This pin is a Schmitt trigger input. No internal pull-up resistor.
	TMS	Pull-up (100 kOhm) ⁽¹⁾	This pin is a Schmitt trigger input. No internal pull-up resistor.
	TDI	Pull-up (100 kOhm) ⁽¹⁾	This pin is a Schmitt trigger input. No internal pull-up resistor.
	TDO	Floating	Output driven at up to V_{DDIOP0}
	RTCK	Floating	Output driven at up to V_{DDIO0P}
	NTRST	Refer to the I/O line considerations and the errata sections of the SAM9G45 datasheet	This pin is a Schmitt trigger input. Internal pull-up resistor to V_{DDIOP0} (100 kOhm).
	JTAGSEL	In harsh environments, ⁽⁴⁾ It is strongly recommended to tie this pin to GNDBU if not used or to add an external low-value resistor (such as 1 kOhm).	Internal pull-down resistor to GNDBU (15 kOhm). Must be tied to V_{VDDBU} to enter JTAG boundary scan.
Reset/Test			
	NRST	Application-dependent. Can be connected to a push button for hardware reset.	NRST is a bidirectional pin (Schmitt trigger input). It is handled by the on-chip reset controller and can be driven low to provide a reset signal to the external components or asserted low externally to reset the microcontroller. By default, the user reset is enabled after a general reset so that it is possible for a component to assert low and reset the microcontroller. An internal pull-up resistor to V_{DDIOP0} (100 kOhm) is available for User Reset and External Reset control.
	TST	In harsh environments,⁽⁴⁾ It is strongly recommended to tie this pin to GNDBU if not used or to add an external low-value resistor (such as 1 kOhm)	This pin is a Schmitt trigger input. Internal pull-down resistor to GNDBU (15 kOhm).
	BMS	Application-dependent.	Must be tied to V_{DDIOP0} to boot from embedded ROM. Must be tied to GNDIOP to boot from external memory (EBI Chip Select 0).
Shutdown/Wakeup Logic			
	SHDN	Application-dependent. A typical application connects the pin SHDN to the shutdown input of the DC/DC Converter providing the main power supplies.	This pin is a push-pull output. SHDN pin is driven low to GNDBU by the Shutdown Controller (SHDWC).

☑	Signal Name	Recommended Pin Connection	Description
	WKUP	0V to V _{VDDBU}	This pin is an input-only. WKUP behavior can be configured through the Shutdown Controller (SHDWC).
PIO			
	PAx PBx PCx	Application-dependent	All PIOs are pulled-up inputs (100 kOhms) at reset except those which are multiplexed with the address bus signals that require to be enabled as peripherals: Refer to the column "Reset State" of the PIO Controller multiplexing tables in the product datasheet. Schmitt trigger on all inputs To reduce power consumption if not used, the concerned PIO can be configured as an output, driven at '0' with internal pull-up disabled.
ADC			
	TSADVREF	2.4V to VDDANA Decoupling/filtering capacitors. Application-dependent	ADVREF is a pure analog input. To reduce power consumption, if ADC is not used: connect ADVREF to GNDANA.
EBI			
	D0-D31	Application-dependent	Data Bus (D0 to D31) All data bus lines are pulled-up inputs to V _{VDDIOM1} at reset. Note: D16 to D31 are multiplexed with the PIOC controller.
	A0-A25	Application-dependent	Address Bus (A0 to A25) All address lines are driven to '0' at reset. Note: A19 to A25 are multiplexed with the PIOC controller.
DDR Memory Interface- DDR2/SDRAM/LPDDR Controller			
	DDR_D0-DDR_D15	Application-dependent If the DDRSDR Controller is not used, DDR_D0-DDR_D15 pins can be left unconnected.	Data Bus Data bus lines are pulled-up inputs to V _{VDDIOM0} at reset.
	DDR_A0-DDR_A13	Application-dependent If the DDRSDR Controller is not used, DDR_A0-DDR_A13 pins can be left unconnected.	Address Bus All address lines are driven to '0' at reset.

☑	Signal Name	Recommended Pin Connection	Description
	DDR_VREF	If the DDR2 Controller is used with LPDDR or DDR2 memory, DDR_VREF is connected to VDDIOM0/2 (i.e. 0.9V) If the DDR2 Controller is used with an SDRAM memory, DDR_VREF is connected to GND or VDDIOM0/2.	Reference voltage for DDR2 Controller. If the DDR2 Controller is not used, DDR_VREF is connected to GND.
SMC - SDRAM Controller - CompactFlash® Support - NAND Flash Support			
See "External Bus Interface (EBI) Hardware Interface" on page 13.			
USB High Speed Host (UHPHS)			
	HFSDPA/HFSDPB HHSDPA/HHSDPB	Application-dependent ⁽⁵⁾	Integrated pull-down resistor to prevent over consumption when the host is disconnected.
	HFSDMA/HFSDMB HHSDMA/HHSDMB	Application-dependent ⁽⁵⁾	Integrated pull-down resistor to prevent over consumption when the host is disconnected.
USB High Speed Device (UDPHS)			
	DHSDM/DFSDP	Application-dependent ⁽⁶⁾	Integrated programmable pull-up resistor. Integrated programmable pull-down resistor to prevent over consumption when the host is disconnected. To reduce power consumption if USB Device is not used, connect the embedded pull-up.
	DHSDP/DFSDM	Application-dependent ⁽⁶⁾	Integrated programmable pull-down resistor to prevent over consumption when the host is disconnected. To reduce power consumption if USB Device is not used, connect the embedded pull-down.

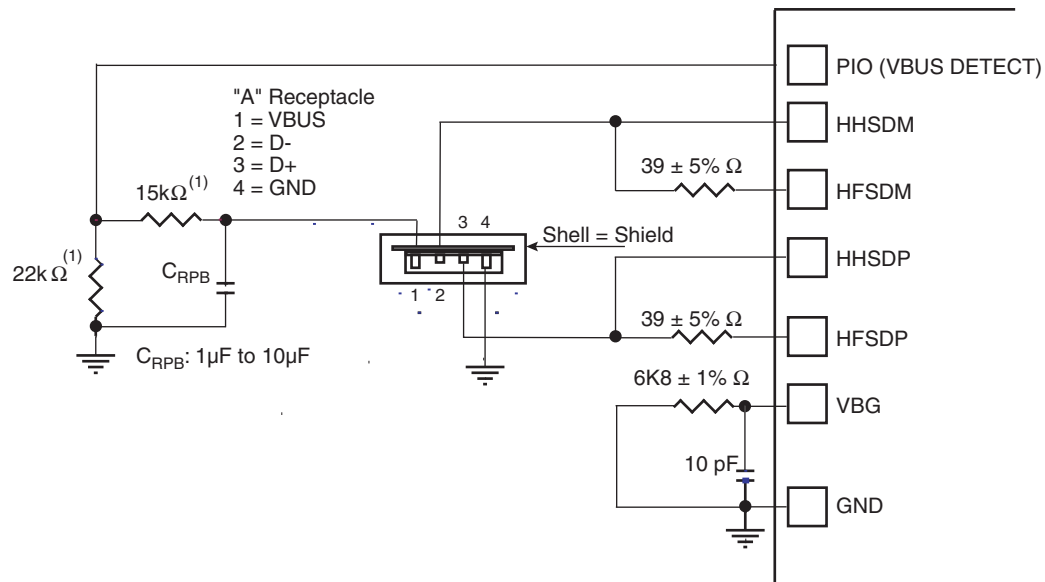
- Notes:
1. These values are given only as a typical example.
 2. Decoupling capacitors must be connected as close as possible to the microcontroller and on each concerned pin.



3. It is recommended to establish accessibility to a JTAG connector for debug in any case.
4. In a well-shielded environment subject to low magnetic and electric field interference, the pin may be left unconnected. In noisy environments, a connection to ground is recommended.

5. Example of USB high-speed host connection:

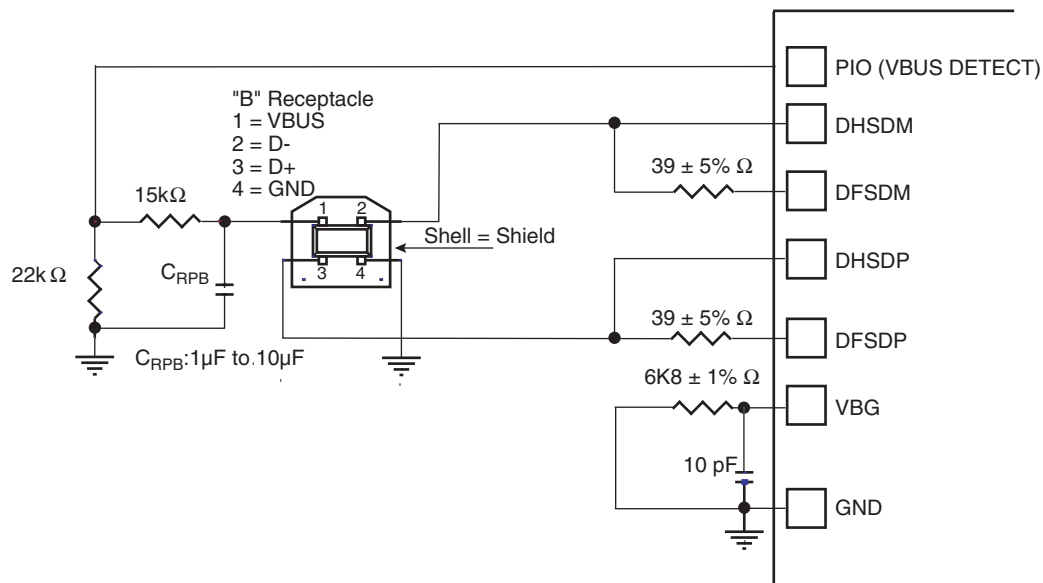
A 39 Ohm termination serial resistor must be connected to HFSDPx and HFSDMx. For more details, refer to the USB High-speed Host Port section (UHPHS) section of the SAM9G45 datasheet.



6. Typical USB high-speed device connection:

As there is an embedded pull-up, no external circuitry is necessary to enable and disable the 1.5 k Ohm pull-up.

A 39 Ohm termination serial resistor must be connected to DFSDP and DFSDM. For more details, refer to the USB High-speed Device Port section (UDPHS) section of the SAM9G45 datasheet.



3. External Bus Interface (EBI) Hardware Interface

Table 3-1 and Table 3-2 detail the connections to be applied between the EBI pins and the external devices for each Memory Controller.

Table 3-1. EBI Pins and External Static Devices Connections

Signals: EBI_	Pins of the Interfaced Device					
	8-bit Static Device	2 x 8-bit Static Devices	16-bit Static Device	4 x 8-bit Static Devices	2 x 16-bit Static Devices	32-bit Static Device
Controller	SMC					
D0 - D7	D0 - D7	D0 - D7	D0 - D7	D0 - D7	D0 - D7	D0 - D7
D8 - D15	–	D8 - D15	D8 - D15	D8 - D15	D8 - 15	D8 - 15
D16 - D23	–	–	–	D16 - D23	D16 - D23	D16 - D23
D24 - D31	–	–	–	D24 - D31	D24 - D31	D24 - D31
A0/NBS0	A0	–	NLB	–	NLB ⁽³⁾	BE0
A1/NWR2/NBS2	A1	A0	A0	WE ⁽³⁾	NLB ⁽³⁾	BE2
A2 - A22	A[2:22]	A[1:21]	A[1:21]	A[0:20]	A[0:20]	A[0:20]
A23 - A25 ⁽⁵⁾	A[23:25]	A[22:24]	A[22:24]	A[21:23]	A[21:23]	A[21:23]
NCS0	CS	CS	CS	CS	CS	CS
NCS1/DDRSDCS	CS	CS	CS	CS	CS	CS
NCS2	CS	CS	CS	CS	CS	CS
NCS3/NANDCS	CS	CS	CS	CS	CS	CS
NCS4/CFCS0	CS	CS	CS	CS	CS	CS
NCS5/CFCS1	CS	CS	CS	CS	CS	CS
NRD/CFOE	OE	OE	OE	OE	OE	OE
NWR0/NWE	WE	WE ⁽¹⁾	WE	WE ⁽³⁾	WE	WE
NWR1/NBS1	–	WE ⁽¹⁾	NUB	WE ⁽²⁾	NUB ⁽³⁾	BE1
NWR3/NBS3	–	–	–	WE ⁽²⁾	NUB ⁽³⁾	BE3

Notes: 1. NWR0 enables lower byte writes. NWR1 enables upper byte writes.

2. NWRx enables corresponding byte x writes (x = 0,1,2 or 3).

3. NBS0 and NBS1 enable respectively lower and upper bytes of the lower 16-bit word.

4. NBS2 and NBS3 enable respectively lower and upper bytes of the upper 16-bit word.

Table 3-2. EBI Pins and External Device Connections

Signals: EBI_	Pins of the Interfaced Device				
	DDR2/LPDDR	SDRAM	CompactFlash	CompactFlash True IDE Mode	NAND Flash
Controller	DDRC	SDRAMC	SMC		
D0 - D7	D0 - D7	D0 - D7	D0 - D7	D0 - D7	I/O0-I/O7
D8 - D15	D8 - D15	D8 - D15	D8 - 15	D8 - 15	I/O8-I/O15 ⁽⁴⁾
D16 - D31	–	D16 - D31	–	–	–
A0/NBS0	–	–	A0	A0	–
A1/NWR2/NBS2	–	–	A1	A1	–
DQM0-DQM3	DQM0-DQM3	DQM0-DQM3	–	–	–
DQS0-DQM1	DQS0-DQS1	–	–	–	–
A2 - A10	A[0:8]	A[0:8]	A[2:10]	A[2:10]	–
A11	A9	A9	–	–	–
SDA10	–	A10	–	–	–
A12	–	–	–	–	–
A13 - A14	A[11:12]	A[11:12]	–	–	–
A15	A13	A13	–	–	–
A16/BA0	BA0	BA0	–	–	–
A17/BA1	BA1	BA1	–	–	–
A18 - A20	–	–	–	–	–
A21/NANDALE	–	–	–	–	ALE
A22/NANDCLE	–	–	REG	REG	CLE
A23 - A24	–	–	–	–	–
A25	–	–	CFRNW ⁽¹⁾	CFRNW ⁽¹⁾	–
NCS0	–	–	–	–	–
NCS1/DDRSDCS	DDRC	SDCS	–	–	–
NCS2	–	–	–	–	–
NCS3/NANDCS	–	–	–	–	CE ⁽³⁾
NCS4/CFCS0	–	–	CFCS0 ⁽¹⁾	CFCS0 ⁽¹⁾	–
NCS5/CFCS1	–	–	CFCS1 ⁽¹⁾	CFCS1 ⁽¹⁾	–
NANDOE	–	–	–	–	OE
NANDWE	–	–	–	–	WE
NRD/CFOE	–	–	OE	–	–
NWR0/NWE/CFWE	–	–	WE	WE	–
NWR1/NBS1/CFIOR	–	–	IOR	IOR	–
NWR3/NBS3/CFIOW	–	–	IOW	IOW	–
CFCE1	–	–	CE1	CS0	–
CFCE2	–	–	CE2	CS1	–
SDCK	CK	CLK	–	–	–
SDCK#	CK#	–	–	–	–
SDCKE	CKE	CKE	–	–	–
RAS	RAS	RAS	–	–	–
CAS	CAS	CAS	–	–	–
SDWE	WE	WE	–	–	–

Table 3-2. EBI Pins and External Device Connections (Continued)

Signals: EBI_	Pins of the Interfaced Device				
	DDR2/LPDDR	SDRAM	CompactFlash	CompactFlash True IDE Mode	NAND Flash
Controller	DDRC	SDRAMC	SMC		
NWAIT ⁽⁵⁾	–	–	WAIT	WAIT	–
Pxx ⁽²⁾	–	–	CD1 or CD2	CD1 or CD2	–
Pxx ⁽²⁾	–	–	–	–	CE ⁽³⁾
Pxx ⁽²⁾	–	–	–	–	RDY

- Notes:
1. Not directly connected to the CompactFlash slot. Permits the control of the bidirectional buffer between the EBI data bus and the CompactFlash slot.
 2. Any PIO line.
 3. CE connection depends on the NAND Flash.
For standard NAND Flash devices, it must be connected to any free PIO line.
For “CE don't care” NAND Flash devices, it can be either connected to NCS3/NANDCS or to any free PIO line.
 4. I/O8 - I/O15 pins used only for 16-bit NAND Flash device.
 5. EBI_NWAIT signal is multiplexed with PC15.

4. High-Speed USB: Recommendations for Use

High-speed signal transitions on the I/O pins of SAM9G45 can affect high-speed USB communication.

To avoid USB communication problems, the following recommendations are strongly recommended:

- Filter the power supplies to reduce system noise.
- Match the impedance of DDR2 signal lines to reduce the signal reflection and configure the DDR2 I/O drives to lower the switching noise.
- Reduce the effects of ground bounce.

4.1 Power Supply

The USB power supplies are sensitive to switching noise. It is strongly recommended to use an LDO to power VDDUTMI and VDDPLLUTMI.

4.2 DDR2 Interface

The DDR2 interface contributes to switching noise and ground bounce. The impedance matching of DDR2 lines can be achieved with termination resistors, which are computed using IBIS models and a tool for signal integrity analysis.

Both the DDR2 controller of the SAM9G45 and the DDR2 device feature I/O drive control.

- For the SAM9G45, the DDR2 I/O drive is configured to high by default. It can be configured to low in the EBI Chip Select Assignment Register.
- For the DDR2 device, the drive is configured to high by default, which leads to an increase in switching noise. The drive can be configured to low during the DDR2 initialization phase only.

For detailed information on the drive selection of the DDR2 controller of the SAM9G45, refer to the EBI Chip Select Assignment Register in the External Memories section of the product datasheet.

For detailed information on the drive selection of the DDR2 device, refer to the DDRSDRC Configuration Register in the DDR/SDR SDRAM Controller (DDRSDRC) section of the product datasheet.

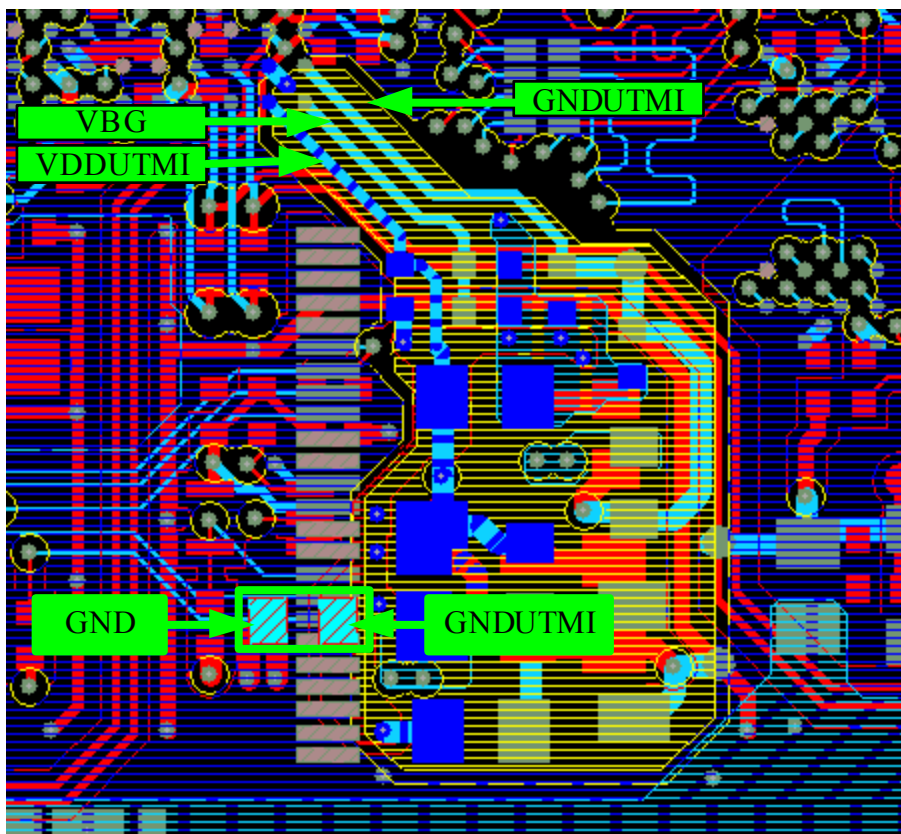
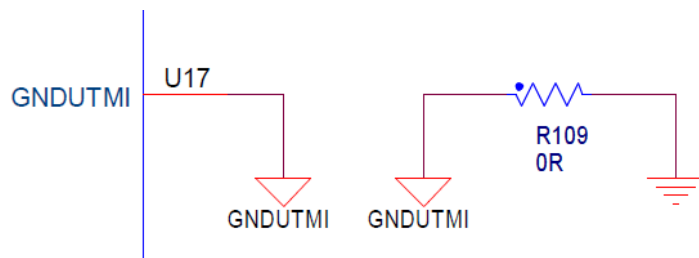
4.3 Ground Layout

The USB transceivers are sensitive to switching noise and ground bounce.

Figure 4-1 illustrates how to separate the USB transceiver ground (GNDUTMI) from the system ground (GND).

VDDUTMI and VBG refer to GNDUTMI, a ground island that is connected to GND plane by a single point.

Figure 4-1. Separation of GNDUTMI and System Ground



5. Boot Program Hardware Constraints

See the Boot Strategies section of the SAM9G45 datasheet for more details on the boot program.

5.1 Boot Program Supported Crystals (MHz)

A 12 MHz crystal or external clock (in bypass mode) is mandatory in order to generate USB and PLL clocks correctly for the following boots.

5.2 NAND Flash Boot

The first block must be guaranteed by the manufacturer. There is no ECC check.

The supported SLC small block NAND Flash devices are described in the Boot Strategies section of the SAM9G45 datasheet.

The NAND Flash boot also supports all SLC large block NAND Flash devices.

Table 5-1. Pins Driven during NAND Flash Boot Program Execution

Peripheral	Pin	PIO Line
EBI CS3 SMC	NANDCS	PC14
EBI CS3 SMC	NAND ALE	A21
EBI CS3 SMC	NAND CLE	A22
EBI CS3 SMC	Cmd//Addr/Data	D[16:0]

5.3 SD Card Boot

SD Card Boot supports all SD Card memories compliant with SD Memory Card Specification V2.0, including SDHC cards.

Table 5-2. Pins Driven during SD Card Boot Program Execution

Peripheral	Pin	PIO Line
MCIO	MCIO_CK	PA0
MCIO	MCIO_CD	PA1
MCIO	MCIO_D0	PA2
MCIO	MCIO_D1	PA3
MCIO	MCIO_D2	PA4
MCIO	MCIO_D3	PA5

5.4 Serial and DataFlash® Boot

Two kinds of SPI Flash are supported: SPI Serial Flash and SPI DataFlash.

The SPI Flash bootloader tries to boot on SPI0 Chip Select 0, first looking for SPI Serial Flash, and then for SPI DataFlash.

The SPI Flash Boot program supports:

- all Serial Flash devices
- all Atmel DataFlash devices.

Table 5-3. Pins Driven during Serial or DataFlash Boot Program Execution

Peripheral	Pin	PIO Line
SPI0	MOSI	PB1
SPI0	MISO	PB0
SPI0	SPCK	PB2
SPI0	NPCS0	PB3

5.5 TWI EEPROM Boot

The TWI EEPROM Flash boot program searches for a valid application in an EEPROM memory.

TWI EEPROM Boot supports all I²C-compatible EEPROM memories using 7-bit device (Address 0x50).

Table 5-4. Pins Driven during TWI EEPROM Boot Program Execution

Peripheral	Pin	PIO Line
TWI0	TWD0	PA20
TWI0	TWCK0	PA21

5.6 SAM-BA® Boot

The SAM-BA boot assistant supports serial communication via the DBGU or the USB Device Port.

Table 5-5. Pins Driven during SAM-BA Boot Program Execution

Peripheral	Pin	PIO Line
DBGU	DRXD	PB12
DBGU	DTXD	PB13

Revision History

Doc. Rev	Comments	Change Request Ref.
6494E	"VDDUTMII" : updated description with USB information.	8523
	"VDDUTMIC" : updated description with USB information.	8523
	Added "VBG" signal description.	rfo
	Added Section 4. "High-Speed USB: Recommendations for Use" .	rfo
6494D	'XIN XOUT 12MHz Main Oscillator in Normal Mode' edited: text removed and figure updated.	7064
	Row A15 edited in Table 3-2, "EBI Pins and External Device Connections" .	7028
	"DDR_VREF" contents edited.	6982
6494C	Supply ripple unit 'mV' changed into 'mVrms'	6831
	Only 1 capacitor value in front of VDDIOP in Section 2. "Schematic Checklist" table	6868
6494B	A new reference at the bottom of Table 1-1, "Associated Documentation"	6775
	Note added to "VDDIOM0" signal in table.	
	Note added to "DDR_D0-DDR_D15" and "DDR_A0-DDR_A13" signals in " DDR Memory Interface- DDR2/SDRAM/LPDDR Controller " table part	6736
	DDR_VREF signal added to " DDR Memory Interface- DDR2/SDRAM/LPDDR Controller " table part	6734
	EBI CS0 changed into EBI CS3 in Table 5-1 TWI, TWD, TWCK changed into TWI0, TWD0, TWCK0 in Table 5-4 In Section 3.1 "AT91SAM Boot Program Supported Crystals (MHz)" , 'NAND Flash memory' changed into 'EEPROM memory', and 'TWI EEPROM memories' changed into 'EEPROM memories'.	rfo
	In Section 2. "Schematic Checklist" , Supply Voltage Ripple information added to "VDDCORE", "VDDPLLA", "VDDPLLUTMI", "VDDBU" and "VDDOSC".	6691
6494A	First issue	



Enabling Unlimited Possibilities®

Atmel Corporation

1600 Technology Drive
San Jose, CA 95110
USA

Tel: (+1) (408) 441-0311

Fax: (+1) (408) 487-2600

www.atmel.com

Atmel Asia Limited

Unit 01-5 & 16, 19F
BEA Tower, Millennium City 5
418 Kwun Tong Road
Kwun Tong, Kowloon
HONG KONG

Tel: (+852) 2245-6100

Fax: (+852) 2722-1369

Atmel Munich GmbH

Business Campus
Parking 4
D-85748 Garching b. Munich
GERMANY

Tel: (+49) 89-31970-0

Fax: (+49) 89-3194621

Atmel Japan G.K.

16F Shin-Osaki Kangyo Bldg
1-6-4 Osaki, Shinagawa-ku
Tokyo 141-0032
JAPAN

Tel: (+81) (3) 6417-0300

Fax: (+81) (3) 6417-0370

© 2013 Atmel Corporation. All rights reserved. / Rev.: 6494E-ATARM-07-Nov-13

Atmel®, Atmel logo and combinations thereof, Enabling Unlimited Possibilities®, SAM-BA® and others are registered trademarks or trademarks of Atmel Corporation or its subsidiaries. ARM® and others are registered trademarks or trademarks of ARM Ltd. Other terms and product names may be the trademarks of others.

Disclaimer: The information in this document is provided in connection with Atmel products. No license, express or implied, by estoppel or otherwise, to any intellectual property right is granted by this document or in connection with the sale of Atmel products. EXCEPT AS SET FORTH IN THE ATMEL TERMS AND CONDITIONS OF SALES LOCATED ON THE ATMEL WEBSITE, ATMEL ASSUMES NO LIABILITY WHATSOEVER AND DISCLAIMS ANY EXPRESS, IMPLIED OR STATUTORY WARRANTY RELATING TO ITS PRODUCTS INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTY OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE, OR NON-INFRINGEMENT. IN NO EVENT SHALL ATMEL BE LIABLE FOR ANY DIRECT, INDIRECT, CONSEQUENTIAL, PUNITIVE, SPECIAL OR INCIDENTAL DAMAGES (INCLUDING, WITHOUT LIMITATION, DAMAGES FOR LOSS AND PROFITS, BUSINESS INTERRUPTION, OR LOSS OF INFORMATION) ARISING OUT OF THE USE OR INABILITY TO USE THIS DOCUMENT, EVEN IF ATMEL HAS BEEN ADVISED OF THE POSSIBILITY OF SUCH DAMAGES. Atmel makes no representations or warranties with respect to the accuracy or completeness of the contents of this document and reserves the right to make changes to specifications and products descriptions at any time without notice. Atmel does not make any commitment to update the information contained herein. Unless specifically provided otherwise, Atmel products are not suitable for, and shall not be used in, automotive applications. Atmel products are not intended, authorized, or warranted for use as components in applications intended to support or sustain life.