

## **KEELOQ<sup>®</sup> Microcontroller-based Code Hopping Encoder**

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#### INTRODUCTION

This application note describes the design of a Microcontroller-based KEELOQ® Hopping Encoder. This encoder is implemented on Microchip PIC16F636 microcontroller. A description of the encoding process, the encoding hardware and description of the software modules are included within this application note. The software was designed to emulate an HCS365 dual encoder. As it is, this design can be used to implement a secure system transmitter that will have the flexibility to be designed into various types of KEELOQ receiver/decoders.

The software used in this implementation makes use of the PIC16F636 internal encryption engine to generate the hopping codes required for transmission.

#### TRANSMITTER OVERVIEW

As this is an emulation of the HCS365, the transmitter has the following key features:

#### Security:

- Two programmable 32-bit serial numbers
- Two programmable 64-bit encryption keys
- Two programmable 60-bit seed values
- · Each transmitter is unique
- 67/69-bit transmission code length
- 32-bit hopping code

#### Operation:

- 2.0-5.5V operation
- Four button inputs
- 15 functions available
- · Four selectable baud rates
- Selectable minimum code word completion
- · Battery low signal transmitted to receiver
- Nonvolatile synchronization data
- PWM, VPWM, PPM, and Manchester modulation
- · Button gueue information transmitted
- · Dual Encoder functionality

#### **DUAL ENCODER OPERATION**

This firmware contains two transmitter configurations with separate serial numbers, encoder keys, discrimination values, counters and seed values. This means that the transmitter can be used as two independent systems. The SHIFT(S3) input pin is used to select between encoder configurations. A low on this pin will select Encoder 1, and a high will select Encoder 2.

#### **FUNCTIONAL INPUTS AND OUTPUTS**

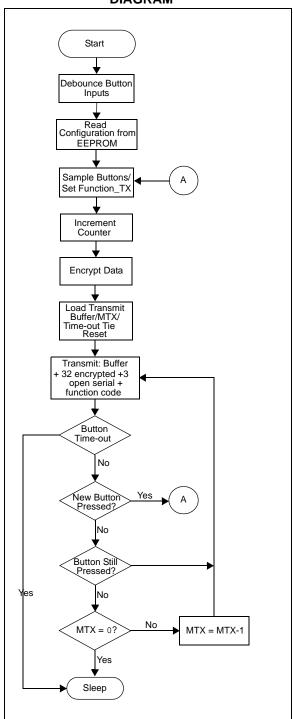
The software implementation makes use of the following pin designations:

TABLE 1: FUNCTIONAL INPUTS AND OUTPUTS

Label	Label Pin Number Input/Output		Function
S0	2 (RA5)	Input	Switch Input S0
S1	3 (RA4)	Input	Switch input S1
S2	4 (RA3)	Input	Switch Input S2
S3	5 (RA2)	Input	Switch Input S3
RF_OUT	6 (RA1)	Output	Encoded transmitter signal output
LED	7(RA0)	Output	LED On/Off

#### OPERATION FLOW DIAGRAM

## FIGURE 1: OPERATION FLOW DIAGRAM



#### **SAMPLE BUTTONS/WAKE-UP**

Upon power-up, the transmitter verifies the state of the buttons inputs and determines if a button is pressed. If no button pressed is detected, the transmitter will go to Sleep mode. The transmitter will wake up whenever a button is pressed. Wake-up is achieved by configuring the input port to generate an interrupt-on-change. After the wake event, the input buttons are debounced for 20 ms to make a determination on which buttons have been pressed. The button input values are then placed in the transmission buffer, in the appropriate section.

#### LOAD SYSTEM CONFIGURATION

After waking up and debouncing the input switches, the firmware will read the system Configuration bytes. These Configuration bytes will determine what data and modulation format will be for the transmission.

All the system Configuration bytes are stored in the EEPROM. Below is the EEPROM mapping for the PIC16F636 transmitter showing the configuration and data bits stored.

TABLE 2: EEPROM MAPPING FOR THE PIC16F636 TRANSMITTER

Offset	Bits								
Bytes	7 6 5 4 3 2 1 0								MNEMONIC
0x00	Sync Counter Transmitter #0, stored in Pseudo-Gray Code								EE_CNT0
0x01		Sync Counter Transmitter #0, stored in Pseudo-Gray Code							
0x02		Syr	nc Counter Trans	smitter #0, sto	red in Pseu	do-Gray Cod	е		
0x03			Sync Count	er Transmitter	#0 Checks	um AB			
0x04			Sync Count	er Transmitter	#0 Checks	um BC			
0x05			Sync Count	er Transmitter	#0 Checks	um AC			
0x06				_					
0x07	_	_	_	_	_	_		_	EE_VLOWL
0x08		Syr	nc Counter Trans	smitter #1, sto	red in Pseu	do-Gray Cod	е		EE_CNT1
0x09		Syr	nc Counter Trans	smitter #1, sto	red in Pseu	do-Gray Cod	е		
0x0A		Syr	nc Counter Trans	smitter #1, sto	red in Pseu	do-Gray Code	Э		
0x0B			Sync Count	er Transmitter	#1 Checks	um AB			
0x0C			Sync Count	er Transmitter	#1 Checks	um BC			
0x0D			Sync Count	er Transmitter	#1 Checks	um AC			
0x0E				_					
0x0F	_	_	_	_	SD_FLG	_	TST	_FLG	
0x10	32-BIT SERIAL NUMBER for TX#0 (MSB)							EE_SER	
0x11	32-BIT SERIAL NUMBER for TX#0								
0x12	32-BIT SERIAL NUMBER for TX#0								
0x13	32-BIT SERIAL NUMBER for TX#0 (LSB)								
0x14	4-BIT SEED CODE TX#0 60-BIT SEED_0 VALUE (MS-NIBBLE)						EE_SEED		
0x15	60-BIT SEED VALUE (MSB) for TX #0								
0x16	60-BIT SEED VALUE for TX #0								
0x17	60-BIT SEED VALUE for TX #0								
0x18			60-Bl	T SEED VALU	JE for TX #0	)			
0x19			60-Bl	T SEED VALU	JE for TX #0	)			
0x1A			60-Bl	T SEED VALU	JE for TX #0	)			
0x1B			60-BIT S	EED VALUE (	(LSB) for TX	( #0			
0x1C	STRTSEL_0	QUEN_0	XSER_0	HEADER_0	TN	MOD_0	DISC_0	(MS-BITS)	EE_DISC
0x1D	DISC_0 (Lower 8 bits)								
0x1E	64-BIT KEY (MSB) for TX #0						EE_KEY		
0x1F			6	64-BIT KEY fo	r TX #0				
0x20				64-BIT KEY fo					
0x21			6	64-BIT KEY fo	r TX #0				
0x22			6	64-BIT KEY fo	r TX #0				
0x23			6	64-BIT KEY fo	r TX #0				
0x24			6	64-BIT KEY fo	r TX #0				

### TABLE 2: EEPROM MAPPING FOR THE PIC16F636 TRANSMITTER (CONTINUED)

IADEL 2		OIN MAI			000 1117	VIACIAII I I EI	1 (0011)	1110LD)	
0x25	64-BIT KEY-0 (LSB) for TX #0								
0x26	32-BIT SERIAL NUMBER for TX#1 (MSB)							B_EE_SER	
0x27			32-BIT \$	SERIAL NUME	BER for TX#	<b>#1</b>			
0x28			32-BIT 9	SERIAL NUME	BER for TX#	<b>#1</b>			
0x29			32-BIT SEF	RIAL NUMBER	R for TX#1 (	LSB)			
0x2A		4-BIT SEED	CODE TX#1		60-BIT	SEED_1 VAL	UE (MS-NI	BBLE)	B_EE_SEED
0x2B			60-BIT SI	EED VALUE (N	MSB) for TX	<b>&lt;#1</b>			
0x2C			60-BI	T SEED VALU	E for TX#1				
0x2D			60-BI	T SEED VALU	E for TX#1				
0x2E			60-BI	T SEED VALU	E for TX#1				
0x2F			60-BI	T SEED VALU	E for TX#1				
0x30	60-BIT SEED VALUE for TX#1								
0x31	60-BIT SEED VALUE (LSB) for TX#1								
0x32	DISC_1 (M	S-BITS)	STRTSEL_1	QUEN_1	XSER_1	HEADER_1	TMC	D_1	B_EE_DISC
0x33	DISC_1 (Lower 8 bits)								
0x34	64-BIT KEY (MSB) for TX#1						B_EE_KEY		
0x35	64-BIT KEY for TX#1								
0x36	64-BIT KEY for TX#1								
0x37	64-BIT KEY for TX#1								
0x38			6	64-BIT KEY for	TX#1				
0x39	64-BIT KEY for TX#1								
0x3A	64-BIT KEY for TX#1								
0x3B	64-BIT KEY (LSB) for TX#1								
0x3C	GSEL	0	BSE	L_0	SE	DTM_0	SDMD_0	SDLM_0	EE_CFG3
0x3D	LEDOS_1	LEDBL_1	TS	EL	RFENO	INDESEL	M <sup>-</sup>	TX	EE_CFG2
0x3E	GSEL	_1	BSE	L_1	SE	TM_1	SDMD_1	SDLM_1	EE_CFG1
0x3F	LEDOS_0	LEDBL_0	PLLSEL	VLOWSEL	VLOWL	CNTSEL	WA	KE	EE_CFG0

#### **CONFIGURATION WORDS DESCRIPTION**

TABLE 3: TX0\_CFG0 (FOR TRANSMITTER 0, FOR TRANSMITTER 1 USE TX1\_CFG0)

BIT	Field	Description	Values
0	DISC:8	Upper two bits of Discrimination	Discrimination bits 9:8
1	DISC:9		
2	TMOD:0	Transmission Modulation Format	00 = PWM 01 = Manchester
3	TMOD:1		10 = VPWM 11 = PPM
4	HEADER	Time Length of Transmission Header	0 = 4*Te 1 = 10*Te
5	XSER	Extended Serial Number Select	0 = 28 bits 1 = 32 bits
6	QUEN	Queue Counter Enable	0 = Disable 1 = Enable
7	STRTSEL	Start/Stop Pulse Enable	0 = Disable 1 = Enable

### TABLE 4: TX0\_CFG1 (FOR TRANSMITTER 0, FOR TRANSMITTER 1 USE TX1\_CFG1)

BIT	Field	Description	Values
0	SDLM	Limited Seed Enable	0 = Disable 1 = Enable
1	SDMD	Seed Mode	0 = User 1 = Production
2	SDTM <3:2>	Time Before Seed Code Word	00 = 0.0 sec 01 = 0.8 sec 10 = 1.6 sec
3			11 = 3.2 sec
4	BSEL <5:4>	Transmission Baud Rate Select	00 = 100 μs 01 = 200 μs
5			10 = 400 μs 11 = 800 μs
6	GSEL <7:6>	Guard Time Select	00 = 0.0 ms 01 = 6.4 ms
7			10 = 51.2 ms 11 = 102.4 ms

#### TABLE 5: SYSCFG0

BIT	Field	Description	Values
0	WAKE <1:0>	Wake-up	00 = No wake-up 01 = 75ms 50%
1			10 = 50ms 33% 11 = 100ms 16.6%
2	CNTSEL	Counter Select	0 = 16 bits 1 = 20 bits
3	VLOWL	Low-Voltage Latch Enable	0 = Disable 1 = Enable
4	VLOWSEL	Low-Voltage Trip Level	0 = 2.2V 1 = 3.2V
5	PLLSEL	PLL interface Select	0 = ASK 1 = FSK
6	LEDBL_0	Low-Voltage LED Blink	0 = Continuous 1 = Once
7	LEDOS_0	LED On Time Select	0 = 50 ms 1 = 100 ms

#### TABLE 6: SYSCFG1

BIT	Field	Description	Values
0	MTX <1:0>	Maximum Code Words	00 = 1
			01 = 2
1			10 = 4
			11 = 8
2	INDESEL	Dual Encoder Enable	0 = Disable
			1 = Enable
3	RFEN0	RF Enable Output Select	0 = Disable
		·	1 = Enable
4	TSEL	Time-out Select	00 = Disabled
			01 = 0.8 sec
5			10 = 3.2 sec
			11 = 25.6 sec
6	LEDBL_1	Low-Voltage LED Blink	0 = Continuous
			1 = Once
7	LEDOS_1	LED On-Time Select	0 = 50 ms
			1 = 100 ms

#### SER\_0 AND SER\_1

SER\_0 stores the 4 bytes of the 32-bit serial number for transmitter 1 (SER\_1 for transmitter 2). There are 32 bits allocated for the serial number and a selectable Configuration bit determines whether 32 or 28 bits will be transmitted. The serial number is meant to be unique for every transmitter.

#### SEED 0 AND SEED 1

This is the 60-bit seed code that will be transmitted when seed transmission is selected. SEED\_0 for transmitter 0 and SEED\_1 for transmitter 1. This allows for the implementation of the secure learning scheme.

## KEY\_0 (TRANSMITTER 0 64-BIT ENCRYPTION KEY)

The 64-bit encryption key is used by the transmitter to create the encrypted message transmitted to the receiver. This key is created using a key generation algorithm. The inputs to the key generation algorithm are the secret manufacturer's code, the serial number, and/or the SEED value. The user may elect to use the algorithm supplied by Microchip or to create their own method of key generation.

#### **COUNTER-CODE DESCRIPTION**

The following addresses save the counter checksum values. The counter value is converted to Pseudo-Gray code and stored in the Counter locations (COUNTA, COUNTB, COUNTC) described on the EEPROM table. These checksum values are used to validate the current value of the counter and allows recovery from any brown-out events. This code is contained in module CounterCode.inc.

#### **ENCRYPTION ENGINE**

The encryption portion of the firmware makes use of the encryption engine internal to the PIC16F636. In essence, the data to be encrypted is loaded into the module, the number of cycles through the engine is set and, after running, the encryption module places the encrypted data into the registers CSRDATA<3:0>. Please read technical Brief TB076, "Using the KEELOQ Cryptographical Module" for more information on the use of this module.

#### **BUTTON PRESS DURING TRANSMIT**

If the device is in the process of transmitting and detects that a new button is pressed, the current transmission will be aborted, a new code word will be generated based on the new button information and transmitted. If all the buttons are released, a minimum number of code words will be completed. If the time for transmitting the minimum code words is longer than the time-out time, or the button is pressed for that long, the device will time-out.

#### **CODE TRANSMISSION FORMAT**

The following is the data stream format transmitted:

TABLE 7: DATA STREAM FORMAT TRANSMITTED

Unencrypted (bits)/Fixed Code					Encrypted (32 bits)		
CRC (2 bits)	VLOW (1 bit)	Repeat (1 bit)	Function Code (4 bits)	Serial Number (28 bits)	Function Code (4 bits)	Discrimination (12 bits)	Counter (16 bits)

Data transmitted LSb-first

A KEELOQ transmission consists of 32 bits of hopping code data, 32 bits of fixed code data and 3 to 5 bits of status information.

#### HOPPING CODE PORTION

The hopping code portion is calculated by encrypting the counter, discrimination value, and function code with the Encoder Key (KEY). A new hopping code is calculated every time a button press is pressed.

The synchronization counter can be either a 16- or a 10-bit counter as selected by the Counter Select option (CNTSEL).

The discrimination value can be programmed with any fixed value to serve as a post decryption check on the receiver end.

#### **FIXED CODE PORTION**

The 32 bits of fixed code consist of 28 bits of serial number and a copy of the 4-bit function code.

Each code word contains a preamble, header and data, and is separated from another code by guard time. The Guard Time Select (GSEL) configuration option can select a time period of 0ms, 6.4ms, 51.2ms or 102.4ms.

All other timing specifications are based on the timing element (Te). This Te can be set to 100  $\mu$ s, 200  $\mu$ s, 400  $\mu$ s or 800  $\mu$ s with the Baud Rate select (BSEL) configuration. The calibration header time can be set to 4\*Te or 10\*Te with the Header Select (HEADER) configuration option.

The firmware has four different transmission modulation formats available. The Modulation select (TMOD) configuration option is used to select between:

- · Pulse-Width Modulation (PWM)
- Manchester (MAN)
- Variable Pulse-Width Modulation (VPWM)
- · Pulse Position Modulation (PPM)

FIGURE 2: PULSE-WIDTH MODULATION (PWM)

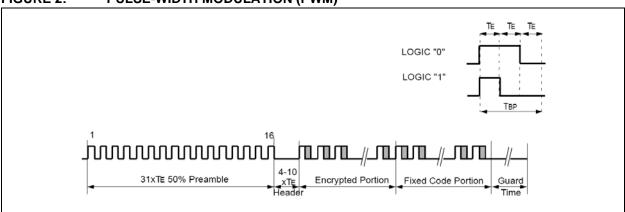
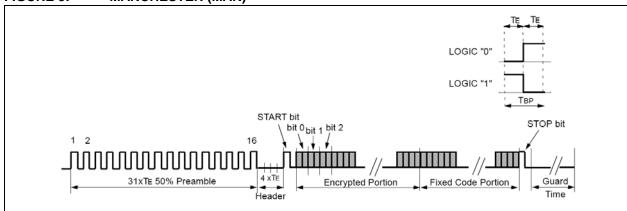


FIGURE 3: MANCHESTER (MAN)





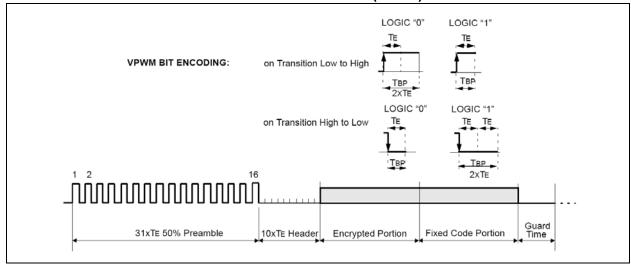
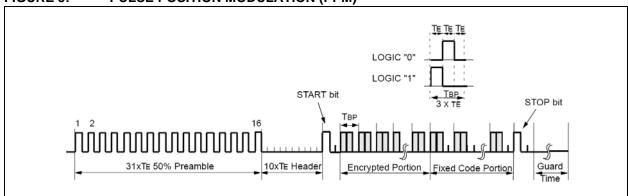


FIGURE 5: PULSE POSITION MODULATION (PPM)



If the Start/Stop Pulse Enable (STEN) configuration option is enabled, the software will place a leading and trailing '1' on each code word. This bit is necessary for modulation formats such as Manchester and PPM to interpret the first and last data bit.

A receiver wake-up sequence can be transmitted before the transmission starts. The wake-up sequence is configured with the Wake-up (WAKE) configuration option and can be disabled or set to 50 ms, 75 ms, or 100 ms of pulses of Te width.

#### FIRMWARE MODULES

The following files make up the KEELOQ transmitter firmware:

- TX 16F636.asm: this file contains the main loop routine as well as the wake-up, debounce, read configuration, load transmit buffer and transmit routines.
- <u>Encrypt636.inc:</u> this file runs the KEELOQ encryption engine.
- TX eeprom.inc: this file contains the EEPROM data as specified on the EEPROM data map.
- CounterCode.inc: Calculates the checksums and confirms the validity of the counter.

#### CONCLUSION

This KEELOQ transmitter firmware has all the features of a standard hardware encoder. What makes this firmware implementation useful to the designer is that it gives the designer the power and flexibility of modifying the encoding and/or transmission formats and parameters to suit their security system.

#### **ADDITIONAL INFORMATION**

Microchip's Secure Data Products are covered by some or all of the following:

Code hopping encoder patents issued in European countries and U.S.A.

Secure learning patents issued in European countries, U.S.A. and R.S.A.  $\,$ 

#### **REVISION HISTORY**

### **Revision B (June 2011)**

- Added new section Additional Information
- Minor formatting and text changes were incorporated throughout the document

#### Note the following details of the code protection feature on Microchip devices:

- Microchip products meet the specification contained in their particular Microchip Data Sheet.
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