

PIC24FJXXMC Family Flash Programming Specification

1.0 DEVICE OVERVIEW

This document defines the programming specification for the PIC24FJXXMC 16-bit Microcontroller (MCU) family of devices. This programming specification is required only for those developing programming support for the following devices:

- PIC24FJ16MC101
- PIC24FJ16MC102
- PIC24FJ32MC101
- PIC24FJ32MC102
- PIC24FJ32MC104

Customers using only one of these devices should use development tools that already provide support for device programming.

Topics covered include:

- [Section 1.0 “Device Overview”](#)
- [Section 2.0 “Programming Overview”](#)
- [Section 3.0 “Device Programming – ICSP”](#)
- [Section 4.0 “Device Programming – Enhanced ICSP”](#)
- [Section 5.0 “Programming the Programming Executive to Memory”](#)
- [Section 6.0 “The Programming Executive”](#)
- [Section 7.0 “Device ID”](#)
- [Section 8.0 “Checksum Computation”](#)
- [Section 9.0 “AC/DC Characteristics and Timing Requirements”](#)
- [Appendix A: “Hex File Format”](#)
- [Appendix B: “Revision History”](#)

2.0 PROGRAMMING OVERVIEW

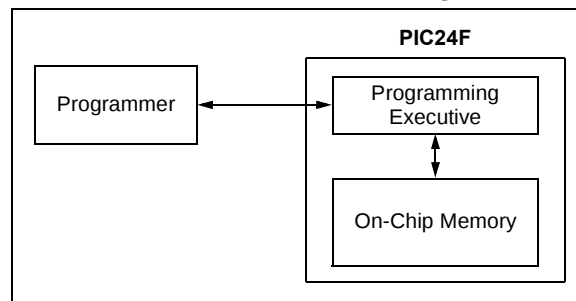
There are two methods for programming the devices discussed in this programming specification:

- In-Circuit Serial Programming™ (ICSP™) Programming Capability
- Enhanced In-Circuit Serial Programming

The ICSP programming method is the most direct method to program the device; however, it is also the slower of the two methods. It provides native, low-level programming capability to erase, program and verify the chip.

The Enhanced ICSP protocol uses a faster method that takes advantage of the Programming Executive, as illustrated in [Figure 2-1](#). The Programming Executive provides all the necessary functionality to erase, program and verify the chip through a small command set. The command set allows the programmer to program a device without having to deal with the low-level programming protocols of the chip.

FIGURE 2-1: PROGRAMMING SYSTEM OVERVIEW FOR ENHANCED ICSP™



This specification is divided into two major sections that describe the programming methods independently:

- [Section 3.0 “Device Programming – ICSP”](#) describes the ICSP method
- [Section 4.0 “Device Programming – Enhanced ICSP”](#) describes the Enhanced ICSP method

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2.1 Required Connections

Devices require specific connections for programming to take place. These connections include power, VCAP, MCLR and one programming pair (PGEDx/PGECx). Table 2-1 describes these connections (refer to the specific device data sheet for pin descriptions and power connection requirements).

Note: Refer to the specific device data sheet for complete pin diagrams.

TABLE 2-1: PINS USED DURING PROGRAMMING

During Programming		
Pin Name	Pin Type	Pin Description
MCLR	I	Programming Enable
VDD and AVDD ⁽¹⁾	P	Power Supply ⁽¹⁾
VSS and AVSS ⁽¹⁾	P	Ground ⁽¹⁾
VCAP	P	CPU Logic Filter Capacitor Connection
PGECx	I	Programming Pin Pair: Serial Clock
PGEDx	I/O	Programming Pin Pair: Serial Data

Legend: I = Input O = Output P = Power

Note 1: All power supply and ground pins must be connected, including AVDD and AVSS.

2.2 Program Memory Write/Erase Requirements

The program Flash memory has a specific write/erase requirement that must be adhered to for proper device operation. The rule is that any given word in memory must not be written without first erasing the page in which it is located. Thus, the easiest way to conform to this rule is to write all the data in a programming block within one write cycle. The programming methods specified in this document comply with this requirement.

Note: A program memory word can be programmed twice before an erase, but only if (a) the same data is used in both program operations or (b) bits containing '1' are set to '0' but no '0' is set to '1'.

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2.3 Memory Map

The program memory map extends from 0x0 to 0xFFFFFE. Code storage is located at the base of the memory map. The last locations of implemented program memory are reserved for the device Configuration bits.

Table 2-2 shows the program memory size, the size of the erase blocks and the number of erase blocks present in each device variant.

Locations, 0x800000 through 0x8007FE, are reserved for executive code memory. This region stores the Programming Executive (PE), which is used for device programming. This region of memory cannot be used to store user code.

Locations, 0xFF0000 and 0xFF0002, are reserved for the Device ID Word registers. These bits can be used by the programmer to identify which device type is being programmed. They are described in Section 7.0 “Device ID”. The Device ID registers read out normally, even after code protection is applied.

Figure 2-2 provides a generic memory map for the devices listed in Table 2-2. See the specific device data sheet for exact memory addresses.

FIGURE 2-2: PROGRAM MEMORY MAP

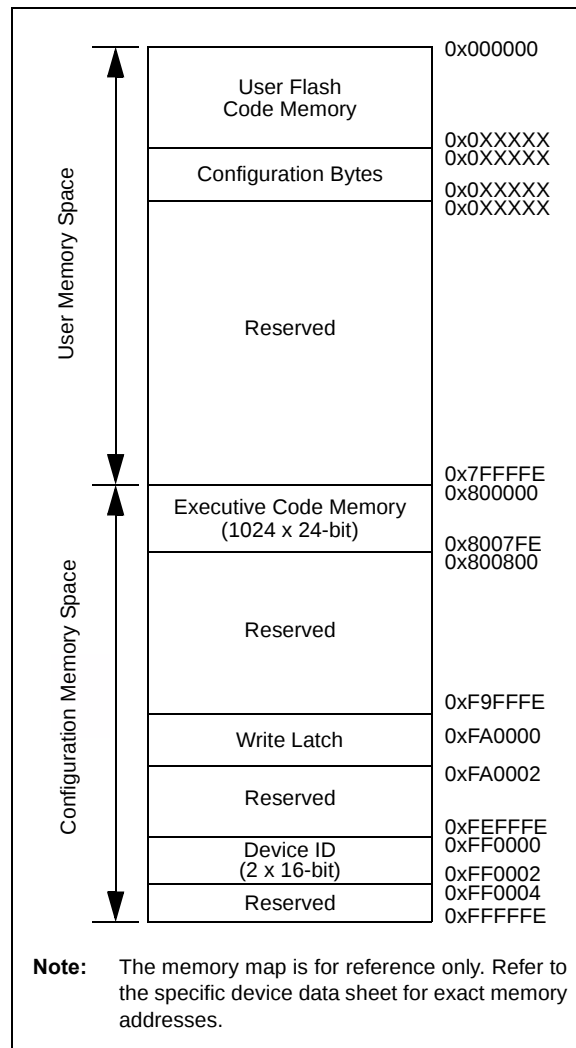


TABLE 2-2: CODE MEMORY SIZE

Device	User Memory Address Limit (Instruction Words)	Erase Page Size (Instruction Words)	Erase Blocks (Pages)	Executive Memory Address Limit (Instruction Words)
PIC24FJ16MC10X ⁽¹⁾	0x002BFA (5.6K)	512	12	0x8007FE (1K)
PIC24FJ32MC10X ⁽¹⁾	0x0057FA (11K)	512	22	0x8007FE (1K)

Note 1: Includes all 20, 28 and 40/44-pin (if applicable) devices.

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2.4 Configuration Bits

2.4.1 OVERVIEW

The Configuration bits are stored in the last locations of implemented program memory of a device. These bits can be set or cleared to select various device configurations. There are two types of Configuration bits: system operation bits and code-protect bits. The system operation bits determine the power-on settings for system level components, such as the Oscillator Start-up Timer and the Watchdog Timer. The code-protect bits prevent program memory from being read and written.

Table 2-3 lists the address and location of the Configuration bits for PIC24FJ16MC10X devices. Table 2-4 lists the address and location of the Configuration bits for PIC24FJ32MC10X devices. See the specific device data sheet for the latest Configuration bit information.

TABLE 2-3: PIC24FJ16MC10X CONFIGURATION BITS⁽¹⁾

File Name	Addr.	Bit Range	Bit 23/15/7	Bit 22/14/6	Bit 21/13/5	Bit 20/12/4	Bit 19/11/3	Bit 18/10/2	Bit 17/9/1	Bit 16/8/0	
CONFIG2	002BFC	23:16	—	—	—	—	—	—	—	—	
		15:8	IESO	PWMLOCK	PWMPIN	WDTWIN<1:0>		FNOSC<2:0>			
		7:0	FCKSM<1:0>		OSCIOFNC	IOL1WAY	LPOL	ALT12C1	POSCMD<1:0>		
CONFIG1	002BFE	23:16	—	—	—	—	—	—	—	—	
		15:8	Reserved ⁽²⁾	Reserved ⁽²⁾	GCP	GWRP	Reserved ⁽³⁾	HPOL	ICS<1:0>		
		7:0	FWDTEN	WINDIS	PLLKEN	WDTPRE	WDTPOST<3:0>				

Legend: — = unimplemented, read as '1'.

Note 1: During a Power-on Reset (POR), the contents of these Flash locations are transferred to the Configuration Shadow registers.

2: This bit is reserved and must be programmed as '0'.

3: This bit is reserved and must be programmed as '1'.

TABLE 2-4: PIC24FJ32MC10X CONFIGURATION BITS⁽¹⁾

File Name	Addr.	Bit Range	Bit 23/15/7	Bit 22/14/6	Bit 21/13/5	Bit 20/12/4	Bit 19/11/3	Bit 18/10/2	Bit 17/9/1	Bit 16/8/0
CONFIG2	0057FC	23:16	—	—	—	—	—	—	—	—
		15:8	IESO	PWMLOCK	PWMPIN	WDTWIN<1:0>		FNOSC<2:0>		
		7:0	FCKSM<1:0>		OSCIOFNC	IOL1WAY	LPOL	ALT12C1	POSCMD<1:0>	
CONFIG1	0057FE	23:16	—	—	—	—	—	—	—	—
		15:8	Reserved ⁽²⁾	Reserved ⁽²⁾	GCP	GWRP	Reserved ⁽³⁾	HPOL	ICS<1:0>	
		7:0	FWDTEN	WINDIS	PLLKEN	WDTPRE	WDTPOST<3:0>			

Legend: — = unimplemented, read as '1'.

Note 1: During a Power-on Reset (POR), the contents of these Flash locations are transferred to the Configuration Shadow registers.

2: This bit is reserved and must be programmed as '0'.

3: This bit is reserved and must be programmed as '1'.

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2.4.2 CODE-PROTECT CONFIGURATION BITS

The Configuration bits control the code protection features, with two forms of code protection being provided. One form prevents code memory from being written (write protection) and the other prevents code memory from being read (i.e., read protection).

The GWRP bit (CONFIG1<12>) controls write protection and the GCP bit (CONFIG1<13>) controls read protection. Protection is enabled when the respective bit is '0'.

Erasing code memory sets GWRP and GCP to '1', which allows the device to be programmed.

When write protection is enabled (GWRP = 0), any programming operation to code memory will fail.

When read protection is enabled (GCP = 0), any read from code memory will cause a 0x0 to be read, regardless of the actual contents of code memory. Since the Programming Executive always verifies what it programs, attempting to program code memory with read protection enabled will also result in failure.

It is imperative that the GWRP and GCP bits are both set to '1' while the device is being programmed and verified. Only after the device is programmed and verified should either the GWRP or GCP bits be programmed to '0' (see [Section 2.4 "Configuration Bits"](#)).

- Note 1:** Bulk Erasing the program memory is the only way to reprogram code-protect bits from an ON state ('0') to an OFF state ('1').
- 2:** Performing a Page Erase operation on the last page of program memory clears the Flash Configuration Words, enabling code protection as a result. Therefore, users should avoid performing Page Erase operations on the last page of program memory.
 - 3:** If the General Segment Code-Protect bit (GCP) is programmed to '0', code memory is code-protected and can not be read. Code memory must be read and verified before enabling read protection. See [Section 2.4.2 "Code-Protect Configuration Bits"](#) for detailed information about code-protect Configuration bits, and [Section 3.10 "Verify Code Memory and Configuration Bits"](#) for details about reading and verifying code memory and Configuration Words and bytes.

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3.0 DEVICE PROGRAMMING – ICSP

ICSP mode is a special programming protocol that allows you to read and write to device memory. The ICSP mode is the most direct method used to program the device, which is accomplished by applying control codes and instructions serially to the device, using the PGECx and PGEDx pins. ICSP mode also has the ability to read executive memory to determine if the Programming Executive is present and to write the Programming Executive to executive memory if Enhanced ICSP (E-ICSP) mode will be used.

In ICSP mode, the system clock is taken from the PGECx pin, regardless of the device's Oscillator Configuration bits. All instructions are shifted serially into an internal buffer, then loaded into the Instruction Register (IR) and executed. No program fetching occurs from internal memory. Instructions are fed in, 24 bits at a time. PGEDx is used to shift data in, and PGECx is used as both the serial shift clock and the CPU execution clock.

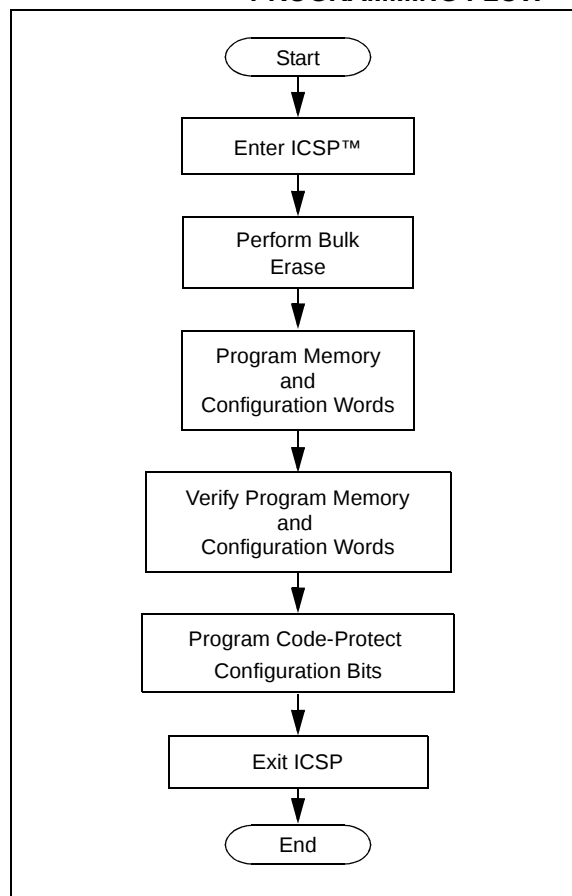
Note 1: During ICSP operation, the operating frequency of PGECx must not exceed 5 MHz.

2: ICSP mode is slower than Enhanced ICSP mode for programming.

3.1 Overview of the Programming Process

Figure 3-1 illustrates the high-level overview of the programming process. After entering ICSP mode, the first action is to Bulk Erase program memory. Next, the code memory is programmed, followed by the device Configuration Words. Code memory (including the Configuration Words) is then verified to ensure that programming was successful. Then, program the code-protect Configuration bits, if required.

FIGURE 3-1: HIGH-LEVEL ICSP™ PROGRAMMING FLOW



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3.2 Entering ICSP Mode

As illustrated in Figure 3-2, entering ICSP Program/Verify mode requires three steps:

1. $\overline{\text{MCLR}}$ is briefly driven high then low (P21).⁽¹⁾
2. A 32-bit key sequence is clocked into PGEDx.
3. $\overline{\text{MCLR}}$ is then driven high within a specified period of time, 'P19', and held.

Note 1: If a capacitor is present on the $\overline{\text{MCLR}}$ pin, the high time for entering ICSP mode can vary.

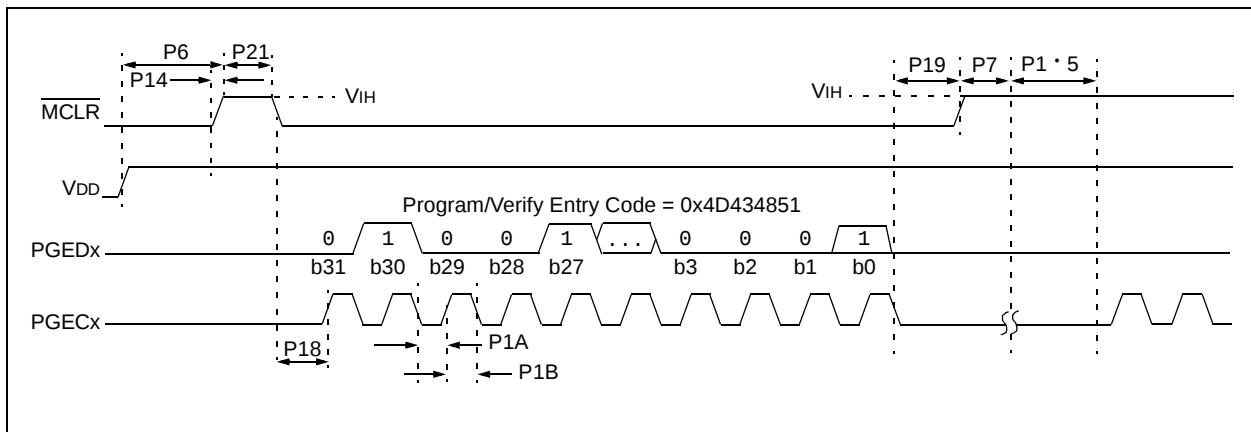
The programming voltage applied to $\overline{\text{MCLR}}$ is V_{IH} , which is essentially V_{DD} . There is no minimum time requirement for holding at V_{IH} . After V_{IH} is removed, an interval of at least P18 must elapse before presenting the key sequence on PGEDx.

The key sequence is a specific 32-bit pattern, '0100 1101 0100 0011 0100 1000 0101 0001' (more easily remembered as 0x4D434851 in hexadecimal). The device will enter Program/Verify mode only if the sequence is valid. The Most Significant bit of the most significant nibble must be shifted in first.

Once the key sequence is complete, V_{IH} must be applied to $\overline{\text{MCLR}}$ and held at that level for as long as Program/Verify mode is to be maintained. An interval of at least time, P19 and $P1 \cdot 5$, must elapse before presenting data on PGEDx. Signals appearing on PGEDx before P7 has elapsed will not be interpreted as valid.

On successful entry, the program memory can be accessed and programmed in serial fashion. While in ICSP mode, all unused I/Os are placed in the high-impedance state.

FIGURE 3-2: ENTERING ICSP™ MODE



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3.3 ICSP Operation

After entering into ICSP mode, the CPU is Idle. Execution of the CPU is governed by an internal state machine. A 4-bit control code is clocked in using PGECx and PGEDx and this control code is used to command the CPU (see [Table 3-1](#)).

The SIX control code is used to send instructions to the CPU for execution and the REGOUT control code is used to read data out of the device via the VISI register.

TABLE 3-1: CPU CONTROL CODES IN ICSP™ MODE

4-Bit Control Code	Mnemonic	Description
0000b	SIX	Shift in 24-bit instruction and execute.
0001b	REGOUT	Shift out the VISI register.
0010b-1111b	N/A	Reserved.

3.3.1 SIX SERIAL INSTRUCTION EXECUTION

The SIX control code allows execution of assembly instructions. When the SIX code is received, the CPU is suspended for 24 clock cycles, as the instruction is then clocked into the internal buffer. Once the instruction is shifted in, the state machine allows it to be executed over the next four clock cycles. While the received instruction is executed, the state machine simultaneously shifts in the next 4-bit command (see [Figure 3-3](#)).

Note 1: Coming out of the ICSP entry sequence, the first 4-bit control code is always forced to SIX and a forced NOP instruction is executed by the CPU. Five additional PGECx clocks are needed on start-up, thereby resulting in a 9-bit SIX command instead of the normal 4-bit SIX command. After the forced SIX is clocked in, ICSP operation resumes as normal (the next 24 clock cycles load the first instruction word to the CPU). See [Figure 3-4](#) for details.

FIGURE 3-3: SIX SERIAL EXECUTION

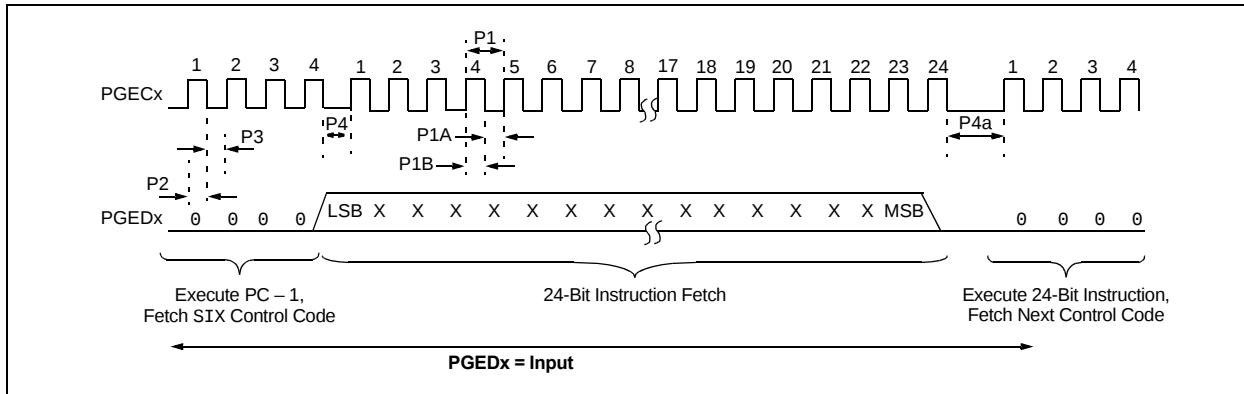
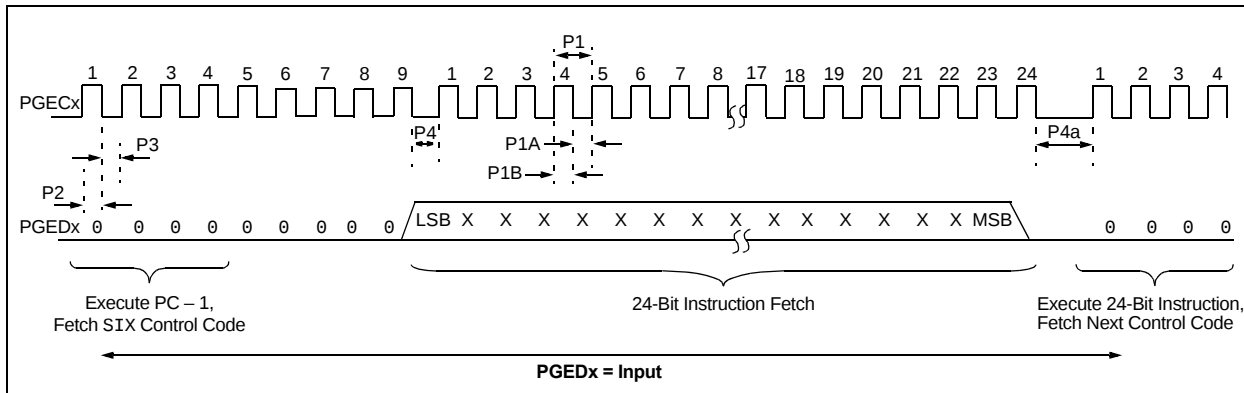


FIGURE 3-4: PROGRAM ENTRY AFTER RESET



PIC24FJXXMC PROGRAMMING SPECIFICATION

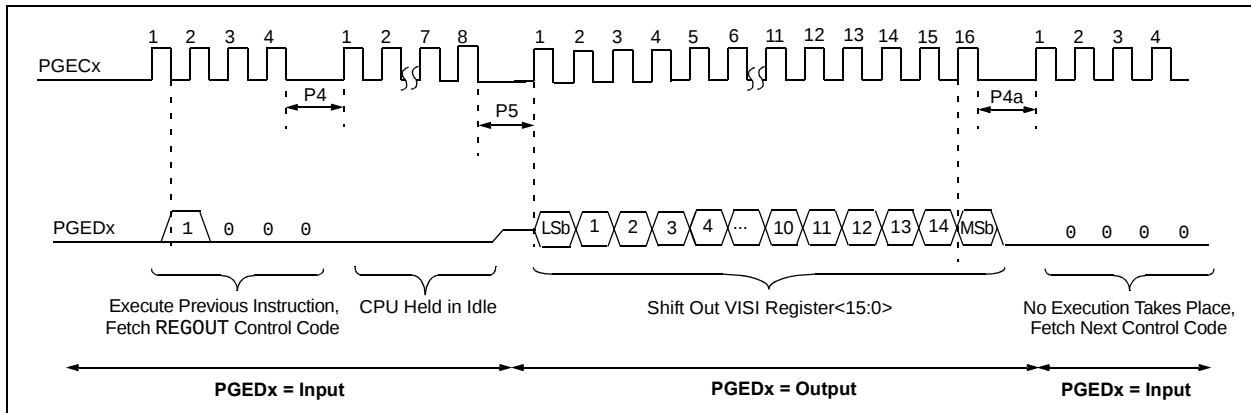
3.3.2 REGOUT SERIAL INSTRUCTION EXECUTION

The REGOUT control code allows for data to be extracted from the device in ICSP mode. It is used to clock the contents of the VISI register out of the device over the PGEDx pin. After the REGOUT control code is received, the CPU is held Idle for eight cycles. After these eight cycles, an additional 16 cycles are required to clock the data out (see [Figure 3-5](#)).

The REGOUT code is unique because the PGEDx pin is an input when the control code is transmitted to the device. However, after the control code is processed, the PGEDx pin becomes an output as the VISI register is shifted out.

Note: The device will latch input PGEDx data on the rising edge of PGECx and will output data on the PGEDx line on the rising edge of PGECx. For all data transmissions, the Least Significant bit (LSb) is transmitted first.

FIGURE 3-5: REGOUT SERIAL EXECUTION



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3.4 Flash Memory Programming in ICSP Mode

3.4.1 PROGRAMMING OPERATIONS

Flash memory write and erase operations are controlled by the NVMCON register. Programming is performed by setting the NVMCON register to select the type of erase operation (Table 3-2) or write operation (Table 3-3) and initiating the programming by setting the WR control bit (NVMCON<15>).

In ICSP mode, all programming operations are self-timed. There is an internal delay between the user setting the WR control bit and the automatic clearing of the WR control bit when the programming operation is complete. Please refer to [Section 9.0 “AC/DC Characteristics and Timing Requirements”](#) for detailed information about the delays associated with various programming operations.

TABLE 3-2: NVMCON ERASE OPERATIONS

NVMCON Value	Erase Operation
0x404F	Erase code memory or executive memory (does not erase Device ID registers).
0x404D	Erase General Segment memory.
0x4042	Erase a page of program memory.

TABLE 3-3: NVMCON WRITE OPERATIONS

NVMCON Value	Write Operation
0x4003	Program a code memory word.

3.4.2 STARTING AND STOPPING A PROGRAMMING CYCLE

The WR bit (NVMCON<15>) is used to start an erase or write cycle. Setting the WR bit initiates the programming cycle.

All erase and write cycles are self-timed. The WR bit should be polled to determine if the erase or write cycle has been completed. Starting a programming cycle is performed as follows:

BSET NVMCON, #WR

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REGISTER 3-1: NVMCON: FLASH MEMORY CONTROL REGISTER

R/SO-0 ⁽¹⁾	R/W-0 ⁽¹⁾	R/W-0 ⁽¹⁾	U-0	U-0	U-0	U-0	U-0
WR	WREN	WRERR	—	—	—	—	—
bit 15							bit 8
U-0	R/W-0 ⁽¹⁾	U-0	U-0	R/W-0 ⁽¹⁾	R/W-0 ⁽¹⁾	R/W-0 ⁽¹⁾	R/W-0 ⁽¹⁾
—	ERASE	—	—	NVMOP<3:0> ⁽²⁾			
bit 7							bit 0

Legend:	SO = Satiabile only bit
R = Readable bit	W = Writable bit
-n = Value at POR	'1' = Bit is set
	'0' = Bit is cleared
	x = Bit is unknown

bit 15	WR: Write Control bit ⁽¹⁾ 1 = Initiates a Flash memory program or erase operation. The operation is self-timed and the bit is cleared by hardware once operation is complete 0 = Program or erase operation is complete and inactive
bit 14	WREN: Write Enable bit ⁽¹⁾ 1 = Enable Flash program/erase operations 0 = Inhibit Flash program/erase operations
bit 13	WRERR: Write Sequence Error Flag bit ⁽¹⁾ 1 = An improper program or erase sequence attempt or termination has occurred (bit is set automatically on any set attempt of the WR bit) 0 = The program or erase operation completed normally
bit 12-7	Unimplemented: Read as '0'
bit 6	ERASE: Erase/Program Enable bit ⁽¹⁾ 1 = Perform the erase operation specified by NVMOP<3:0> on the next WR command 0 = Perform the program operation specified by NVMOP<3:0> on the next WR command
bit 5-4	Unimplemented: Read as '0'
bit 3-0	NVMOP<3:0>: NVM Operation Select bits ^(1,2) If ERASE = 1: 1111 = Memory Bulk Erase ⁽³⁾ 1101 = Erase General Segment 0010 = Program Memory Page Erase If ERASE = 0: 0011 = Memory word program

- Note 1:** These bits can only be reset on a Power-on Reset (POR).
Note 2: All other combinations of NVMOP<3:0> are unimplemented.
Note 3: This command will erase, either all of program memory or all of executive memory, but not both.

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3.5 Erasing Program Memory

The procedure for erasing program memory (including code-protect bits) is shown in [Figure 3-6](#). It consists of setting the NVMCON register to 0x404F, initializing the TBLPAG register to 0x00, and then executing the programming cycle. For Page Erase operations, the NVMCON value should be modified suitably, according to [Table 3-2](#).

[Table 3-4](#) illustrates the ICSP programming process for erasing program memory.

FIGURE 3-6: PROGRAM MEMORY ERASE FLOW

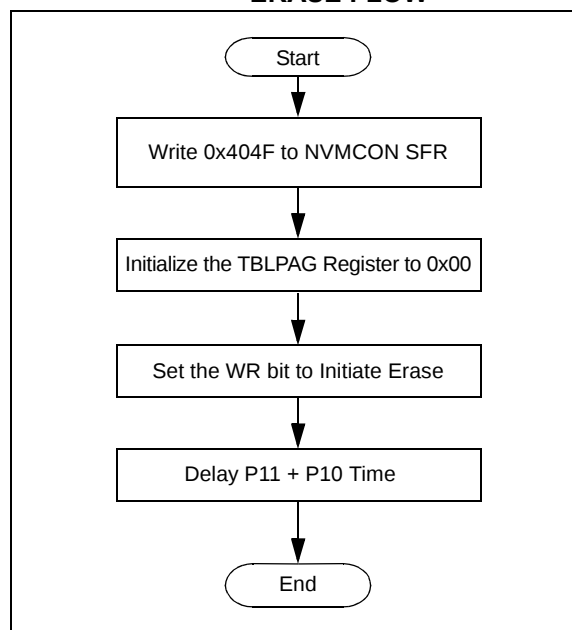


TABLE 3-4: SERIAL INSTRUCTION EXECUTION FOR ERASING PROGRAM MEMORY

4-Bit Control Code	Data (Hex)	Description
Step 1: Exit the Reset vector.		
0000	040200	GOTO 0x200
0000	040200	GOTO 0x200
0000	000000	NOP
Step 2: Set the NVMCON to erase all program memory.		
0000	2404FA	MOV #0x404F, W10
0000	883B0A	MOV W10, NVMCON
Step 3: Initiate the TBLPAG register for program memory.		
0000	200001	MOV #0x00, W1
0000	880191	MOV W1, TBLPAG
Step 4: Initiate the erase cycle.		
0000	A8E761	BSET NVMCON, #WR
0000	000000	NOP
0000	000000	NOP
0000	000000	NOP
0000	000000	NOP
Step 5: Wait for Bulk Erase operation to complete to ensure that the WR bit is clear.		
—	—	Externally time, 'P11' + 'P10' ms (see Section 9.0 “AC/DC Characteristics and Timing Requirements”), to allow sufficient time for the Bulk Erase operation to complete.

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3.6 Writing Code Memory

Figure 3-7 provides a high-level description of how to write to code memory. First, the device is configured for writes, one instruction word is loaded into the write latch and the write point is incremented. Next, the write sequence is initiated and finally, the WR bit is checked for the sequence to be complete. This process continues for all words to be programmed.

Table 3-5 describes the ICSP programming process for writing program memory.

FIGURE 3-7: PROGRAM CODE MEMORY FLOW

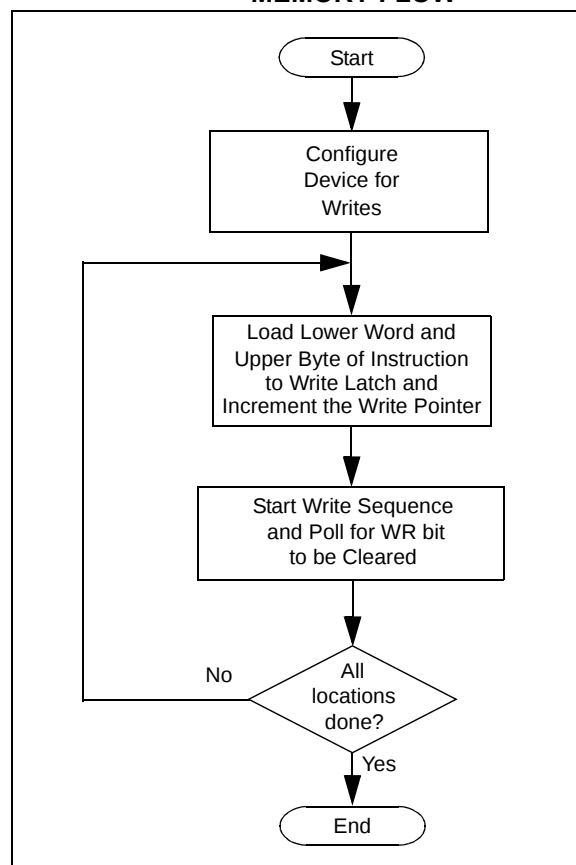


TABLE 3-5: SERIAL INSTRUCTION EXECUTION FOR WRITING CODE MEMORY

4-Bit Control Code	Data (Hex)	Description
Step 1: Exit the Reset vector.		
0000	040200	GOTO 0x200
0000	040200	GOTO 0x200
0000	000000	NOP
Step 2: Set the NVMCON register to program one program memory word.		
0000	240030	MOV #0x4003, W0
0000	000000	NOP
0000	883B00	MOV W0, NVMCON
Step 3: Initialize the TBLPAG register to the first page of program memory.		
0000	200001	MOV #0x00, W1
0000	000000	NOP
0000	880191	MOV W1, TBLPAG
Step 4: Initialize the Write Pointer (W2) for the TBLWT instruction.		
0000	2xxxx2	MOV #<DestinationAddress15:0>, W2
Step 5: Load the lower instruction word to the W5 register and the upper instruction byte to the W6 register.		
0000	2xxxx5	MOV #<LOW_WORD>, W5
0000	200xx6	MOV #<HIGH_BYTE>, W6

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TABLE 3-5: SERIAL INSTRUCTION EXECUTION FOR WRITING CODE MEMORY (CONTINUED)

4-Bit Control Code	Data (Hex)	Description
Step 6: Write the program memory low word and the program memory upper byte into the write latch and increment the Write Pointer.		
0000	000000	NOP
0000	BB0905	TBLWTL W5, [W2]
0000	000000	NOP
0000	000000	NOP
0000	BB9906	TBLWTH.B W6, [W2++]
0000	000000	NOP
0000	000000	NOP
0000	000000	NOP
Step 7: Initiate the write cycle.		
0000	A8E761	BSET NVMCON, #WR
0000	000000	NOP
0000	000000	NOP
0000	000000	NOP
0000	000000	NOP
Step 8: Wait for the word write operation to complete and make sure the WR bit is clear.		
—	—	Externally time, 'P13' ms (see Section 9.0 “AC/DC Characteristics and Timing Requirements”), to allow sufficient time for the Configuration Word write operation to complete.
0000	803B00	MOV NVMCON, W0
0000	883C20	MOV W0, VISI
0000	000000	NOP
0001	<VISI>	Clock out contents of VISI register.
0000	040200	GOTO 0x200
0000	000000	NOP
—	—	Repeat until the WR bit is clear.
Step 9: Repeat Steps 5-8 to write the remaining program words.		

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3.7 Writing Configuration Words

The procedure for writing Configuration Words is similar to the procedure for writing code memory, except that 16-bit data words are written (with the upper bytes read being all '0's) instead of 24-bit words. Since there are multiple Configuration Words, they are written one word at a time.

To change the values of the Configuration Words once they have been programmed, the device must be Chip Erased, as described in [Section 3.5 "Erasing Program Memory"](#), and reprogrammed to the desired value. It is not possible to program a '0' to '1', but they may be programmed from a '1' to '0' to enable code protection.

[Table 3-6](#) shows the ICSP programming details for writing the Configuration Words.

In order to verify the data by reading the Configuration Words after performing the write, the code protection bits should initially be programmed to '1' to ensure that the verification can be performed properly. After verification is finished, the code protection bits can be programmed to '0' by using a word write to the appropriate Configuration Word.

TABLE 3-6: SERIAL INSTRUCTION EXECUTION FOR WRITING CONFIGURATION WORDS

4-Bit Control Code	Data (Hex)	Description
Step 1: Exit the Reset vector.		
0000	040200	GOTO 0x200
0000	040200	GOTO 0x200
0000	000000	NOP
Step 2: Set the NVMCON register to program one Configuration Word.		
0000	24003A	MOV #0x4003, W10
0000	883B0A	MOV W10, NVMCON
Step 3: Initialize the TBLPAG register to the first page of program memory.		
0000	200xx0	MOV <Address7:0>, W0
0000	880190	MOV W0, TBLPAG
Step 4: Initialize the Write Pointer (W7) for the TBLWT instruction.		
0000	2xxxx7	MOV <Address15:0>, W7
Step 5: Load the Configuration Word data to W6.		
0000	2xxxx6	MOV #<VALUE>, W6
Step 6: Write the Configuration Word data to the write latch and increment the Write Pointer.		
0000	000000	NOP
0000	BB1B86	TBLWTL W6, [W7++]
0000	000000	NOP
0000	000000	NOP
0000	000000	NOP
Step 7: Initiate the write cycle.		
0000	A8E761	BSET NVMCON, #WR
0000	000000	NOP
0000	000000	NOP
0000	000000	NOP
0000	000000	NOP

PIC24FJXXMC PROGRAMMING SPECIFICATION

TABLE 3-6: SERIAL INSTRUCTION EXECUTION FOR WRITING CONFIGURATION WORDS

4-Bit Control Code	Data (Hex)	Description
Step 8: Wait for the Configuration Word write operation to complete and make sure the WR bit is clear.		
—	—	Externally time, 'P13' ms (see Section 9.0 “AC/DC Characteristics and Timing Requirements”), to allow sufficient time for the Configuration Word write operation to complete.
0000	803B00	MOV NVMCON, W0
0000	883C20	MOV W0, VISI
0000	000000	NOP
0001	<VISI>	Clock out contents of VISI register.
0000	040200	GOTO 0x200
0000	000000	NOP
—	—	Repeat until the WR bit is clear.
Step 9: Repeat Steps 5-8 to write the remaining Configuration Words.		

PIC24FJXXMC PROGRAMMING SPECIFICATION

3.8 Reading Code Memory

Reading from code memory is performed by executing a series of TBLRD instructions and clocking out the data using the REGOUT command.

Table 3-7 shows the ICSP programming details for reading code memory.

To minimize programming time, the same packed data format that the Programming Executive uses is utilized.

See [Section 6.2 “Programming Executive Commands”](#) for more details on the packed data format.

TABLE 3-7: SERIAL INSTRUCTION EXECUTION FOR READING CODE MEMORY

4-Bit Control Code	Data (Hex)	Description
Step 1: Exit the Reset vector.		
0000	040200	GOTO 0x200
0000	040200	GOTO 0x200
0000	000000	NOP
Step 2: Initialize TBLPAG and the Read Pointer (W6) for TBLRD instruction.		
0000	200000	MOV <Address7:0>, W0
0000	880190	MOV W0, TBLPAG
0000	2xxxx6	MOV #<Address15:0>, W6
Step 3: Initialize the Write Pointer (W7) and store the next four locations of code memory to W0:W5.		
0000	EB0380	CLR W7
0000	BA1B96	TBLRDL [W6], [W7++]
0000	000000	NOP
0000	000000	NOP
0000	BADBB6	TBLRDH.B [W6++], [W7++]
0000	000000	NOP
0000	000000	NOP
0000	BADBD6	TBLRDH.B [++W6], [W7++]
0000	000000	NOP
0000	000000	NOP
0000	BA1BB6	TBLRDL [W6++], [W7++]
0000	000000	NOP
0000	000000	NOP
0000	BA1B96	TBLRDL [W6], [W7++]
0000	000000	NOP
0000	000000	NOP
0000	BADBB6	TBLRDH.B [W6++], [W7++]
0000	000000	NOP
0000	000000	NOP
0000	BADBD6	TBLRDH.B [++W6], [W7++]
0000	000000	NOP
0000	000000	NOP
0000	BA1BB6	TBLRDL [W6++], [W7++]
0000	000000	NOP
0000	000000	NOP

PIC24FJXXMC PROGRAMMING SPECIFICATION

TABLE 3-7: SERIAL INSTRUCTION EXECUTION FOR READING CODE MEMORY (CONTINUED)

4-Bit Control Code	Data (Hex)	Description
Step 4: Output W0:W5 using the VISI register and REGOUT command.		
0000	883C20	MOV W0, VISI
0000	000000	NOP
0001	<VISI>	Clock out contents of VISI register.
0000	000000	NOP
0000	883C21	MOV W1, VISI
0000	000000	NOP
0001	<VISI>	Clock out contents of VISI register.
0000	000000	NOP
0000	883C22	MOV W2, VISI
0000	000000	NOP
0001	<VISI>	Clock out contents of VISI register.
0000	000000	NOP
0000	883C23	MOV W3, VISI
0000	000000	NOP
0001	<VISI>	Clock out contents of VISI register.
0000	000000	NOP
0000	883C24	MOV W4, VISI
0000	000000	NOP
0001	<VISI>	Clock out contents of VISI register.
0000	000000	NOP
0000	883C25	MOV W5, VISI
0000	000000	NOP
0001	<VISI>	Clock out contents of VISI register.
0000	000000	NOP
Step 5: Reset device internal PC.		
0000	040200	GOTO 0x200
0000	000000	NOP
Step 6: Repeat Steps 3-5 until all desired code memory is read.		

PIC24FJXXMC PROGRAMMING SPECIFICATION

3.9 Reading Configuration Bits

The procedure for reading Configuration bits is similar to the procedure for reading code memory, except that 16-bit data words are read instead of 24-bit instructions. Since there are multiple Configuration bits, they are read one word at a time.

Table 3-8 shows the ICSP programming details for reading the Configuration bits.

TABLE 3-8: SERIAL INSTRUCTION EXECUTION FOR READING ALL CONFIGURATION BITS

4-Bit Control Code	Data (Hex)	Description
Step 1: Exit the Reset vector.		
0000	040200	GOTO 0x200
0000	040200	GOTO 0x200
0000	000000	NOP
Step 2: Initialize TBLPAG, the Read Pointer (W6) and the Write Pointer (W7) for the TBLRD instruction.		
0000	200000	MOV <Address7:0>, W0
0000	880190	MOV W0, TBLPAG
0000	2xxxx6	MOV <Address15:0>, W6
0000	EB0380	CLR W7
0000	000000	NOP
Step 3: Read the Configuration Word, write it to the VISI register and clock out the VISI register using the REGOUT command.		
0000	BA0036	TBLRDL [W6++], W0
0000	000000	NOP
0000	000000	NOP
0000	883C20	MOV W0, VISI
0000	000000	NOP
0001	<VISI>	Clock out contents of VISI register.
0000	000000	NOP
Step 4: Reset device internal PC.		
0000	040200	GOTO 0x200
0000	000000	NOP
Step 5: Repeat Steps 3-4 to read remaining Configuration bits.		

PIC24FJXXMC PROGRAMMING SPECIFICATION

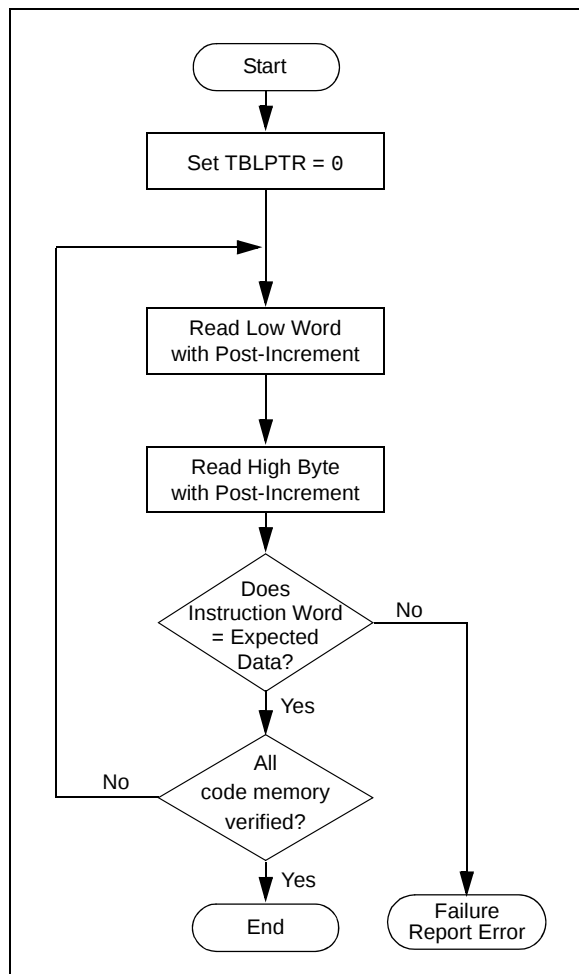
3.10 Verify Code Memory and Configuration Bits

The verify step involves reading back the code memory space and comparing it against the copy held in the programmer's buffer. The Configuration Words are verified with the rest of the code.

The verify process is illustrated in Figure 3-8. The lower word of the instruction is read, and then the lower byte of the upper word is read and compared against the instruction stored in the programmer's buffer. Refer to Section 3.8 "Reading Code Memory" for implementation details of reading code memory.

Note: Because the configuration bytes include the device code protection bit, code memory should be verified immediately after writing if the code protection is to be enabled. This is because the device will not be readable or verifiable if a device Reset occurs after the code-protect bit has been cleared.

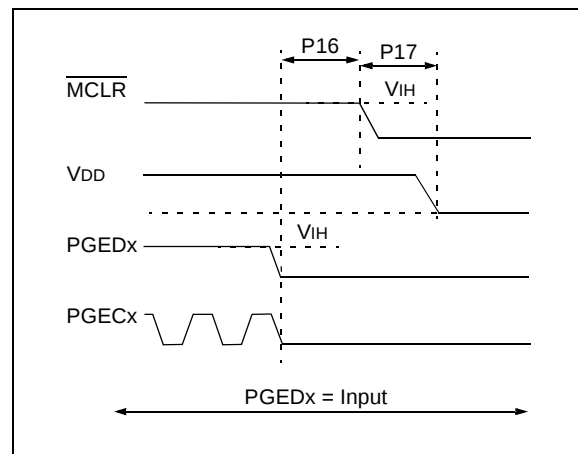
FIGURE 3-8: VERIFY CODE MEMORY FLOW



3.11 Exiting ICSP Mode

Exiting Program/Verify mode is done by removing V_{IH} from MCLR, as illustrated in Figure 3-9. The only requirement for exit is that an interval P16 should elapse between the last clock and program signals on PGECx and PGEDx before removing V_{IH} .

FIGURE 3-9: EXITING ICSP™ MODE



PIC24FJXXMC PROGRAMMING SPECIFICATION

4.0 DEVICE PROGRAMMING – ENHANCED ICSP

This section discusses programming the device through Enhanced ICSP and the Programming Executive. The Programming Executive resides in executive memory (separate from code memory) and is executed when Enhanced ICSP Programming mode is entered. The Programming Executive provides the mechanism for the programmer (host device) to program and verify a device, using a simple command set and communication protocol. There are several basic functions provided by the Programming Executive:

- Read Memory
- Erase Memory
- Program Memory
- Blank Check

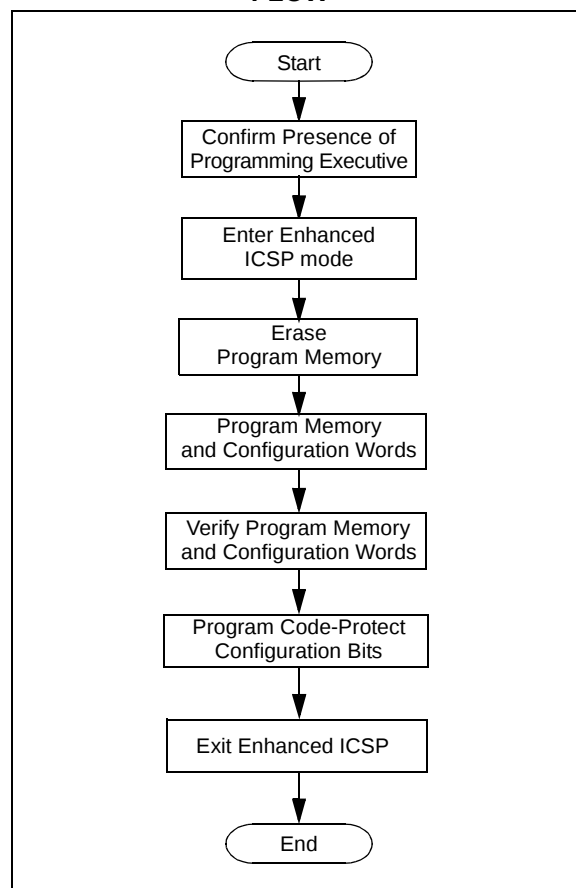
The Programming Executive performs the low-level tasks required for erasing, programming and verifying a device. This allows the programmer to program the device by issuing the appropriate commands and data. A detailed description for each command is provided in [Section 6.2 “Programming Executive Commands”](#).

Note: The Programming Executive uses the device's data RAM for variable storage and program execution. After running the Programming Executive, no assumptions should be made about the contents of data RAM.

4.1 Overview of the Programming Process

[Figure 4-1](#) shows the high-level overview of the programming process. First, it must be determined if the Programming Executive is present in executive memory and then, Enhanced ICSP mode is entered. The program memory is then erased, and the program memory and Configuration Words are programmed and verified. Last, the code-protect Configuration bits are programmed (if required) and Enhanced ICSP mode is exited.

FIGURE 4-1: HIGH-LEVEL ENHANCED ICSP™ PROGRAMMING FLOW



PIC24FJXXMC PROGRAMMING SPECIFICATION

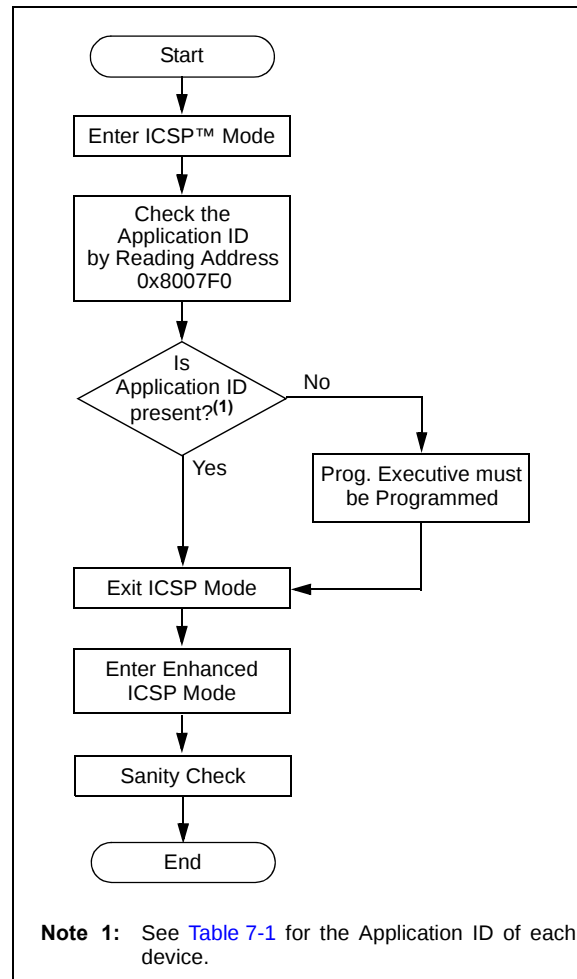
4.2 Confirming the Presence of the Programming Executive

Before programming, the programmer must confirm that the Programming Executive is stored in executive memory. The procedure for this task is illustrated in Figure 4-2.

First, ICSP mode is entered. Then, the unique Application ID Word, stored in executive memory, is read. If the Programming Executive is resident, the correct Application ID Word is read and programming can resume as normal. However, if the Application ID Word is not present, the Programming Executive must be programmed to executive code memory, using the method described in Section 5.0 “Programming the Programming Executive to Memory”. See Table 7-1 for the Application ID of each device.

Section 3.0 “Device Programming – ICSP” describes the ICSP programming method. Section 4.3 “Reading the Application ID Word” describes the procedure for reading the Application ID Word in ICSP mode.

FIGURE 4-2: CONFIRMING PRESENCE OF PROGRAMMING EXECUTIVE



PIC24FJXXMC PROGRAMMING SPECIFICATION

4.3 Reading the Application ID Word

The Application ID Word is stored at address, 0x8007F0, in executive code memory. To read this memory location, you must use the SIX control code to move this program memory location to the VISI register. Then, the REGOUT control code must be used to clock the contents of the VISI register out of the device. The corresponding control and instruction codes, that must be serially transmitted to the device to perform this operation, are shown in [Table 3-8](#).

After the programmer has clocked out the Application ID Word, it must be inspected. If the Application ID has the value listed in [Table 7-1](#), the Programming Executive is resident in memory and the device can be programmed using the mechanism described in [Section 4.0 “Device Programming – Enhanced ICSP”](#). However, if the Application ID has any other value, the Programming Executive is not resident in memory; it must be loaded to memory before the device can be programmed. The procedure for loading the Programming Executive to memory is described in [Section 5.0 “Programming the Programming Executive to Memory”](#).

TABLE 4-1: SERIAL INSTRUCTION EXECUTION FOR READING THE APPLICATION ID WORD

4-bit Control Code	Data (Hex)	Description
Step 1: Exit the Reset vector.		
0000	040200	GOTO 0x200
0000	040200	GOTO 0x200
0000	000000	NOP
Step 2: Initialize TBLPAG and the Read Pointer (W0) for the TBLRD instruction.		
0000	200800	MOV #0x80, W0
0000	880190	MOV W0, TBLPAG
0000	207F00	MOV #0x7F0, W0
0000	207841	MOV #VISI, W1
0000	000000	NOP
0000	BA0890	TBLRDL [W0], [W1]
0000	000000	NOP
0000	000000	NOP
Step 3: Output the VISI register using the REGOUT command.		
0001	<VISI>	Clock out contents of the VISI register.

PIC24FJXXMC PROGRAMMING SPECIFICATION

4.4 Entering Enhanced ICSP Mode

As illustrated in Figure 4-3, entering Enhanced ICSP Program/Verify mode requires three steps:

1. The $\overline{\text{MCLR}}$ pin is briefly driven high, then low.
2. A 32-bit key sequence is clocked into PGEDx.
3. $\overline{\text{MCLR}}$ is then driven high within a specified period of time and held.

The programming voltage applied to $\overline{\text{MCLR}}$ is V_{IH} , which is essentially V_{DD} . There is no minimum time requirement for holding at V_{IH} . After V_{IH} is removed, an interval of at least P18 must elapse before presenting the key sequence on PGEDx.

The key sequence is a specific 32-bit pattern, '0100 1101 0100 0011 0100 1000 0101 0000' (more easily remembered as 0x4D434850 in hexadecimal format). The device will enter Program/Verify mode only if the key sequence is valid. The Most Significant bit (MSb) of the most significant nibble must be shifted in first.

Once the key sequence is complete, V_{IH} must be applied to $\overline{\text{MCLR}}$ and held at that level for as long as Program/Verify mode is to be maintained. An interval time of at least P19, and $P1 \cdot 5$, must elapse before presenting data on PGEDx. Signals appearing on PGEDx before P7 has elapsed will not be interpreted as valid.

On successful entry, the program memory can be accessed and programmed in serial fashion. While in the Program/Verify mode, all unused I/Os are placed in the high-impedance state.

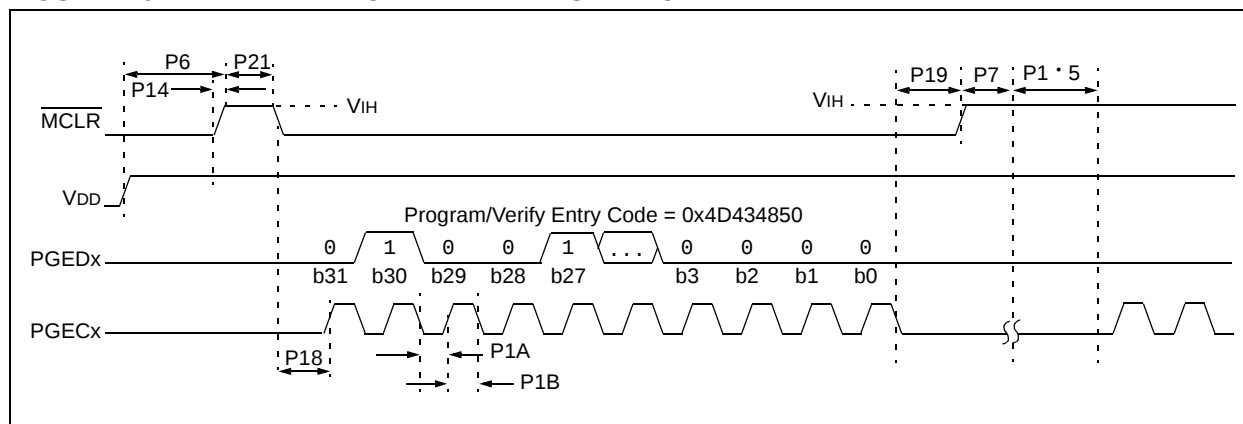
4.5 Blank Check

The term, "Blank Check", implies verifying that the device has been successfully erased and has no programmed memory locations. A blank or erased memory location is always read as '1'.

The Device ID registers (0xFF0000:0xFF0002) can be ignored by the Blank Check, since this region stores device information that cannot be erased. Additionally, all unimplemented memory space should be ignored from the Blank Check.

The QBLANK command is used for the Blank Check. It determines if the code memory is erased by testing these memory regions. A 'BLANK' or 'NOT BLANK' response is returned. If it is determined that the device is not blank, it must be erased before attempting to program the chip.

FIGURE 4-3: ENTERING ENHANCED ICSP™ MODE



PIC24FJXXMC PROGRAMMING SPECIFICATION

4.6 Code Memory Programming

4.6.1 PROGRAMMING METHODOLOGY

There are two commands that can be used for programming code memory when utilizing the Programming Executive: PROGW and PROGP. The PROGW command programs and verifies a single 24-bit instruction word into the specified program memory address. The second and faster command, PROGP, allows up to sixty-four 24-bit instruction words to be programmed and verified into program memory starting at the specified address. See [Section 6.0 “The Programming Executive”](#) for a full description for each of these commands.

[Figure 4-4](#) and [Figure 4-5](#) illustrate the programming methodology for both of these commands. In both cases, 5.6K instruction words of the devices are programmed.

Note: If a bootloader needs to be programmed, the bootloader code must not be programmed into the first page of code memory. For example, if a bootloader, located at address 0x200, attempts to erase the first page, it would inadvertently erase itself. Instead, program the bootloader into the second page (e.g., 0x400).

FIGURE 4-4: FLOWCHART FOR SINGLE WORD PROGRAMMING

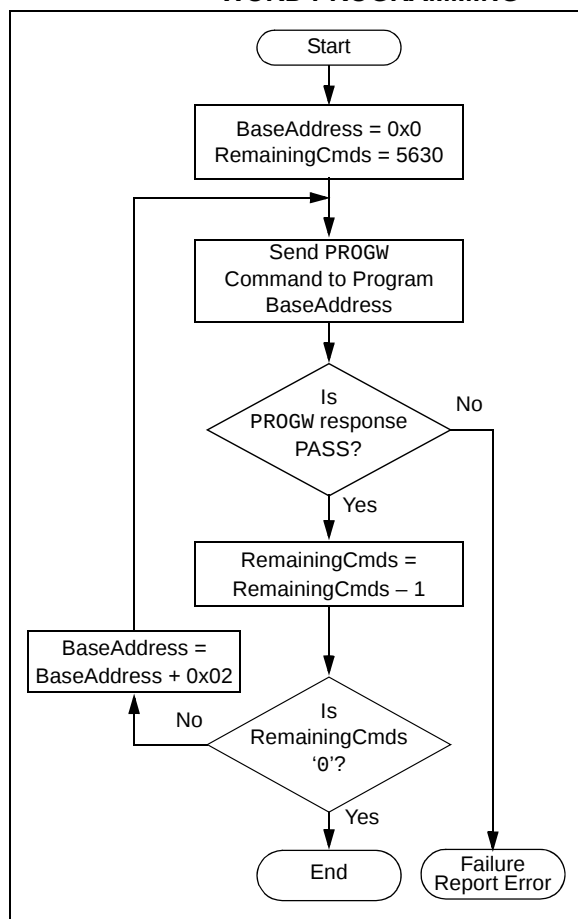
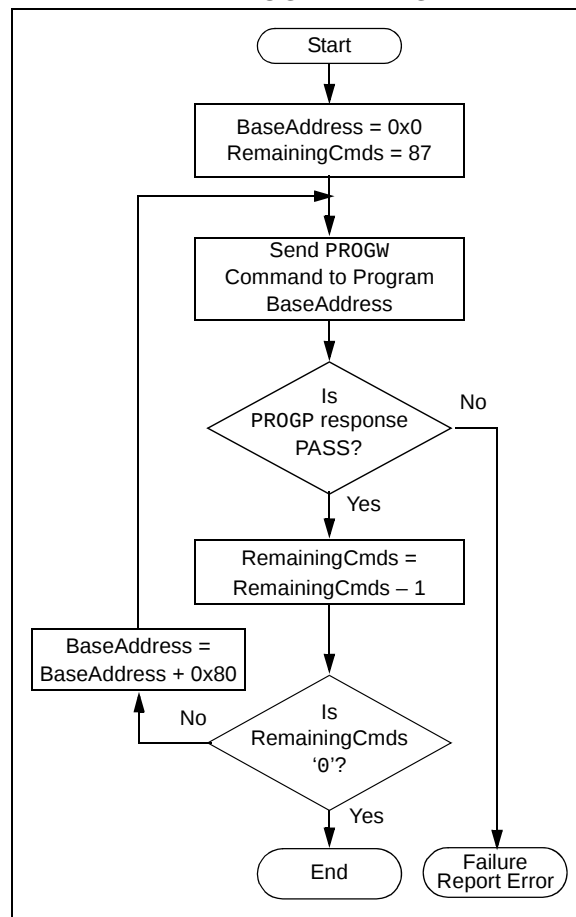


FIGURE 4-5: FLOWCHART FOR MULTIPLE WORD PROGRAMMING



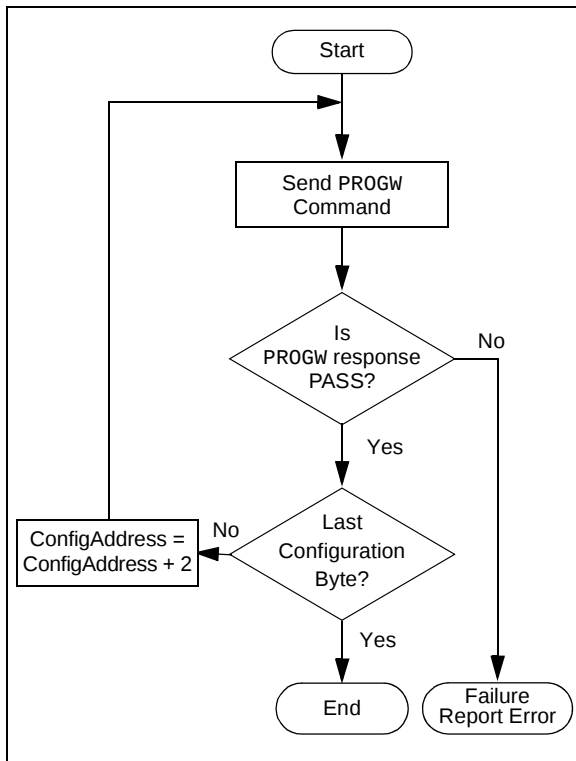
PIC24FJXXMC PROGRAMMING SPECIFICATION

4.7 Configuration Bit Programming

Configuration bits are programmed one at a time using the PROGW command. This command specifies the configuration data and address. When Configuration bits are programmed, any unimplemented bits must be programmed with a '1'.

Multiple PROGW commands are required to program all Configuration bits. A flowchart for the Configuration bit programming is shown in [Figure 4-6](#).

FIGURE 4-6: CONFIGURATION BIT PROGRAMMING FLOW



4.8 Programming Verification

After code memory is programmed, the contents of memory can be verified to ensure that programming was successful. Verification requires code memory to be read back and compared against the copy held in the programmer's buffer.

The READP command can be used to read back all the programmed code memory and Configuration Words.

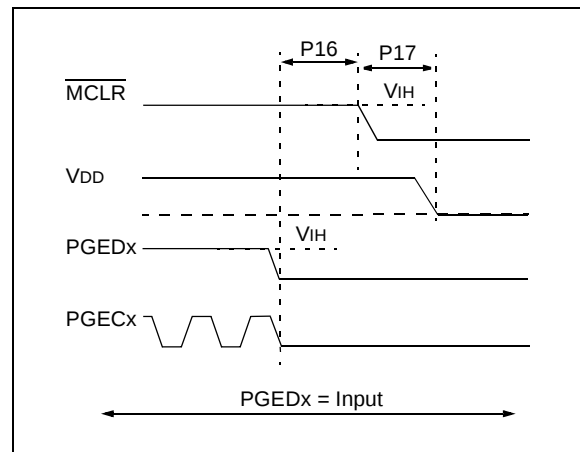
Alternatively, you can have the programmer perform the verification after the entire device is programmed, using a checksum computation.

See [Section 8.0 "Checksum Computation"](#) for more information on calculating the checksum.

4.9 Exiting Enhanced ICSP Mode

Exiting Program/Verify mode is done by removing V_{IH} from MCLR, as illustrated in [Figure 4-7](#). The only requirement for exit is that an interval P16 should elapse between the last clock and program signals on PGECx and PGEDx before removing V_{IH} .

FIGURE 4-7: EXITING ENHANCED ICSP™ MODE



PIC24FJXXMC PROGRAMMING SPECIFICATION

5.0 PROGRAMMING THE PROGRAMMING EXECUTIVE TO MEMORY

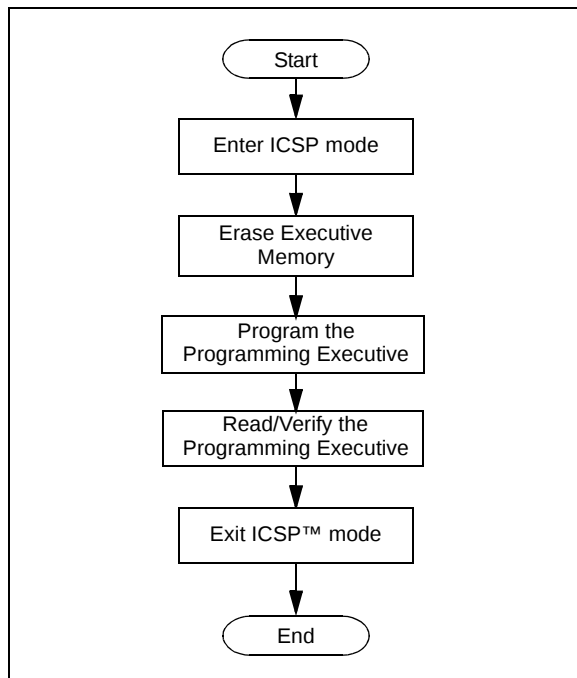
Note: The Programming Executive (PE) can be located within the following folder within your installation of MPLAB® IDE:
...\\Microchip\\MPLAB IDE\\REAL ICE
and then selecting the Hex PE file,
RIPE_01d_XXXXXX.hex.

5.1 Overview

If it is determined that the Programming Executive is not present in executive memory (as described in [Section 4.2 “Confirming the Presence of the Programming Executive”](#)), the Programming Executive must be programmed to executive memory.

[Figure 5-1](#) shows the high-level process of programming the Programming Executive into executive memory. First, ICSP mode must be entered and executive memory is erased, then, the Programming Executive is programmed and verified. Finally, ICSP mode is exited.

FIGURE 5-1: HIGH-LEVEL PROGRAMMING EXECUTIVE PROGRAMMING FLOW



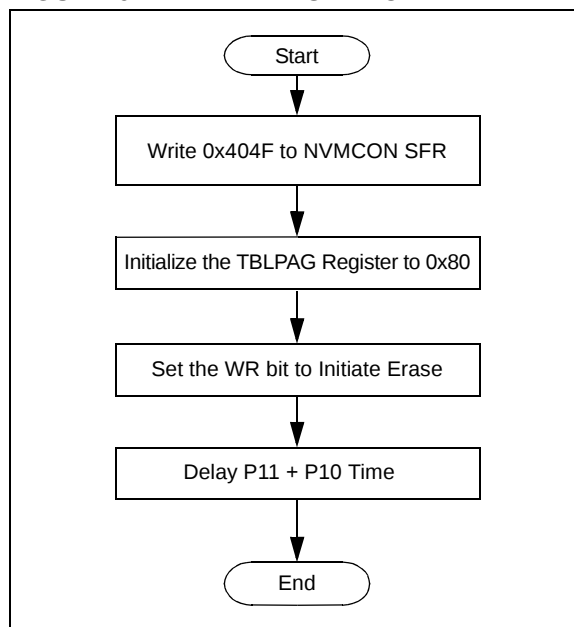
5.2 Erasing Executive Memory

The procedure for erasing executive memory is similar to that of erasing program memory and is shown in [Figure 5-2](#). It consists of setting NVMCON to 0x404F, initializing the TBLPAG register to the beginning of executive memory, 0x80, and then executing the programming cycle.

[Table 5-1](#) illustrates the ICSP programming process for erasing executive memory.

Note: The Programming Executive must always be erased before it is programmed, as described in [Figure 5-1](#).

FIGURE 5-2: ERASE FLOW



PIC24FJXXMC PROGRAMMING SPECIFICATION

TABLE 5-1: SERIAL INSTRUCTION EXECUTION FOR ERASING EXECUTIVE MEMORY

4-Bit Control Code	Data (Hex)	Description
Step 1: Exit the Reset vector.		
0000	040200	GOTO 0x200
0000	040200	GOTO 0x200
0000	000000	NOP
Step 2: Set the NVMCON to erase all executive memory.		
0000	2404FA	MOV #0x404F, W10
0000	883B0A	MOV W10, NVMCON
Step 3: Initiate the TBLPAG register for executive memory.		
0000	200800	MOV #0x80, W1
0000	880191	MOV W1, TBLPAG
Step 4: Initiate the erase cycle.		
0000	A8E761	BSET NVMCON, #WR
0000	000000	NOP
0000	000000	NOP
0000	000000	NOP
0000	000000	NOP
Step 5: Wait for Bulk Erase operation to complete and make sure WR bit is clear.		
—	—	Externally time, 'P11' ms (see Section 9.0 “AC/DC Characteristics and Timing Requirements”), to allow sufficient time for the Bulk Erase operation to complete.

PIC24FJXXMC PROGRAMMING SPECIFICATION

5.3 Program the Programming Executive

Storing the Programming Executive to executive memory is similar to normal programming of code memory. Namely, the executive memory must first be erased and then the Programming Executive must be programmed one word at a time. This control flow is summarized in [Figure 5-3](#).

[Table 5-2](#) illustrates the ICSP programming process for Programming Executive memory.

FIGURE 5-3: PROGRAM CODE MEMORY FLOW

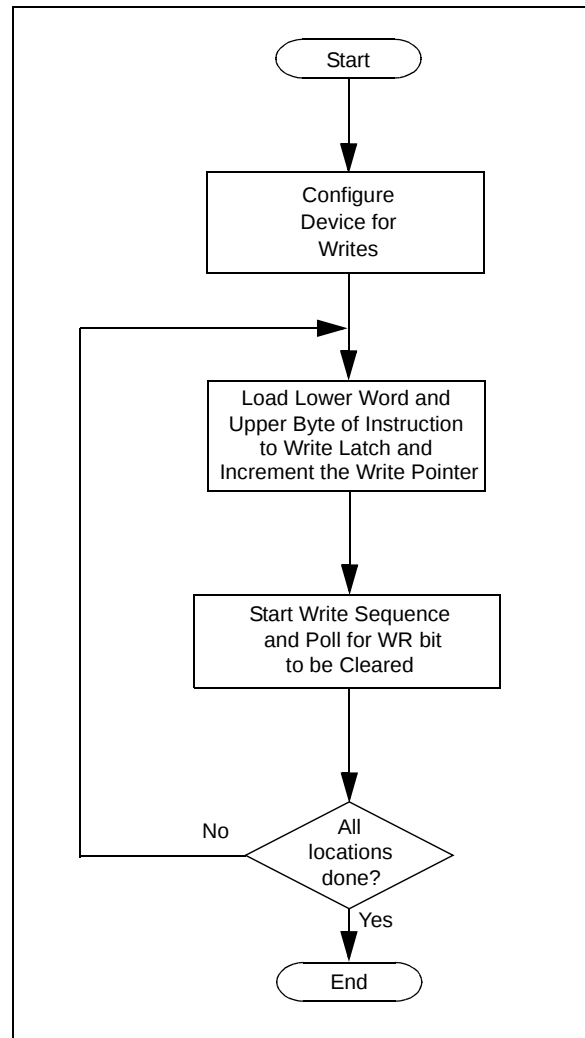


TABLE 5-2: PROGRAMMING THE PROGRAMMING EXECUTIVE

4-Bit Control Code	Data (Hex)	Description
Step 1: Exit the Reset vector.		
0000	040200	GOTO 0x200
0000	040200	GOTO 0x200
0000	000000	NOP
Step 2: Set the NVMCON register to program one executive memory word.		
0000	240030	MOV #0x4003, W0
0000	000000	NOP
0000	883B00	MOV W0, NVMCON
Step 3: Initialize the TBLPAG register to the first page of executive memory.		
0000	200801	MOV #0x80, W1
0000	000000	NOP
0000	880191	MOV W1, TBLPAG
Step 4: Initialize the Write Pointer (W2) for the TBLWT instruction.		
0000	2xxxx2	MOV #<DestinationAddress15:0>, W2

PIC24FJXXMC PROGRAMMING SPECIFICATION

TABLE 5-2: PROGRAMMING THE PROGRAMMING EXECUTIVE (CONTINUED)

4-Bit Control Code	Data (Hex)	Description
Step 5: Load the lower instruction word to the W5 register and the upper instruction byte to the W6 register.		
0000	2xxxx5	MOV #<LOW_WORD>, W5
0000	200xx6	MOV #<HIGH_BYTE>, W6
Step 6: Write the program memory low word and the executive memory upper byte into the write latch, and increment the Write Pointer.		
0000	000000	NOP
0000	BB0905	TBLWTL.W W5, [W2]
0000	000000	NOP
0000	000000	NOP
0000	BBD906	TBLWTH.B W6, [W2++]
0000	000000	NOP
0000	000000	NOP
0000	000000	NOP
Step 7: Initiate the write cycle.		
0000	A8E761	BSET NVMCON, #WR
0000	000000	NOP
0000	000000	NOP
0000	000000	NOP
0000	000000	NOP
Step 8: Wait for the word write operation to complete and make sure the WR bit is clear.		
—	—	Externally time 'P13' ms (see Section 9.0 “AC/DC Characteristics and Timing Requirements”) to allow sufficient time for the Configuration Word write operation to complete.
0000	803B00	MOV NVMCON, W0
0000	883C20	MOV W0, VISI
0000	000000	NOP
0001	<VISI>	Clock out contents of VISI register.
0000	040200	GOTO 0x200
0000	000000	NOP
—	—	Repeat until the WR bit is clear.
Step 9: Repeat Steps 5-8 to write the remaining executive memory words.		

PIC24FJXXMC PROGRAMMING SPECIFICATION

5.4 Reading Executive Memory

Reading from executive memory is performed by executing a series of TBLRD instructions and clocking out the data using the REGOUT command.

Table 5-3 shows the ICSP programming details for reading executive memory.

To minimize programming time, the same packed data format that the Programming Executive uses is utilized. See [Section 6.2 “Programming Executive Commands”](#) for more details on the packed data format.

TABLE 5-3: SERIAL INSTRUCTION EXECUTION FOR READING EXECUTIVE MEMORY

4-Bit Control Code	Data (Hex)	Description
Step 1: Exit the Reset vector.		
0000	040200	GOTO 0x200
0000	040200	GOTO 0x200
0000	000000	NOP
Step 2: Initialize TBLPAG and the Read Pointer (W6) for TBLRD instruction.		
0000	200800	MOV #0x80, W0
0000	880190	MOV W0, TBLPAG
0000	2xxxx6	MOV #<SourceAddress15:0>, W6
Step 3: Initialize the Write Pointer (W7) and store the next four locations of executive memory to W0:W5.		
0000	EB0380	CLR W7
0000	BA1B96	TBLRDL [W6], [W7++]
0000	000000	NOP
0000	000000	NOP
0000	BADBB6	TBLRDH.B [W6++], [W7++]
0000	000000	NOP
0000	000000	NOP
0000	BADBD6	TBLRDH.B [++W6], [W7++]
0000	000000	NOP
0000	000000	NOP
0000	BA1BB6	TBLRDL [W6++], [W7++]
0000	000000	NOP
0000	000000	NOP
0000	BA1B96	TBLRDL [W6], [W7++]
0000	000000	NOP
0000	000000	NOP
0000	BADBB6	TBLRDH.B [W6++], [W7++]
0000	000000	NOP
0000	000000	NOP
0000	BADBD6	TBLRDH.B [++W6], [W7++]
0000	000000	NOP
0000	000000	NOP
0000	BA1BB6	TBLRDL [W6++], [W7++]
0000	000000	NOP
0000	000000	NOP

PIC24FJXXMC PROGRAMMING SPECIFICATION

TABLE 5-3: SERIAL INSTRUCTION EXECUTION FOR READING EXECUTIVE MEMORY

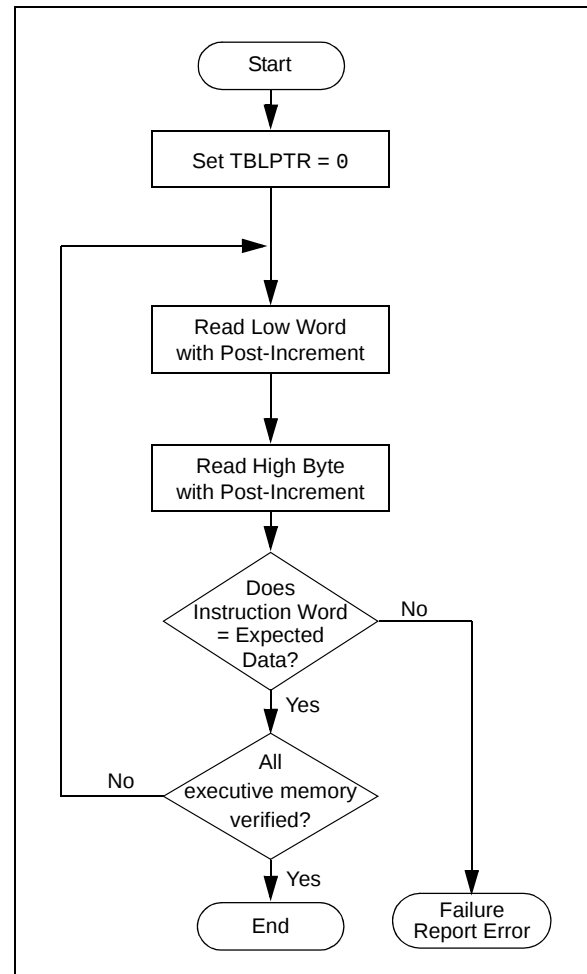
4-Bit Control Code	Data (Hex)	Description
Step 4: Output W0:W5 using the VISI register and REGOUT command.		
0000	883C20	MOV W0, VISI
0000	000000	NOP
0001	<VISI>	Clock out contents of VISI register.
0000	000000	NOP
0000	883C21	MOV W1, VISI
0000	000000	NOP
0001	<VISI>	Clock out contents of VISI register.
0000	000000	NOP
0000	883C22	MOV W2, VISI
0000	000000	NOP
0001	<VISI>	Clock out contents of VISI register.
0000	000000	NOP
0000	883C23	MOV W3, VISI
0000	000000	NOP
0001	<VISI>	Clock out contents of VISI register.
0000	000000	NOP
0000	883C24	MOV W4, VISI
0000	000000	NOP
0001	<VISI>	Clock out contents of VISI register.
0000	000000	NOP
0000	883C25	MOV W5, VISI
0000	000000	NOP
0001	<VISI>	Clock out contents of VISI register.
0000	000000	NOP
Step 5: Reset device internal PC.		
0000	040200	GOTO 0x200
0000	000000	NOP
Step 6: Repeat Steps 3-5 until all desired executive memory is read.		

5.5 Verify Programming Executive

The verify step involves reading back the executive memory space and comparing it against the copy held in the programmer's buffer.

The verify process is illustrated in [Figure 5-4](#). The lower word of the instruction is read, and then the lower byte of the upper word is read and compared against the instruction stored in the programmer's buffer. Refer to [Section 5.4 "Reading Executive Memory"](#) for implementation details of reading executive memory.

FIGURE 5-4: VERIFY EXECUTIVE MEMORY FLOW



PIC24FJXXMC PROGRAMMING SPECIFICATION

6.0 THE PROGRAMMING EXECUTIVE

6.1 Programming Executive Communication

The programmer and Programming Executive have a master-slave relationship, where the programmer is the master programming device and the Programming Executive is the slave.

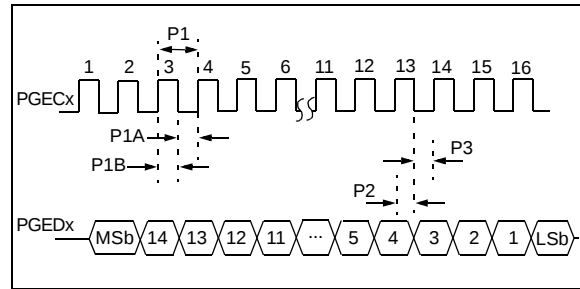
All communication is initiated by the programmer in the form of a command. Only one command at a time can be sent to the Programming Executive. In turn, the programming Executive only sends one response to the programmer after receiving and processing a command. The Programming Executive command set is described in [Section 6.2 “Programming Executive Commands”](#). The response set is described in [Section 6.3 “Programming Executive Responses”](#).

6.1.1 COMMUNICATION INTERFACE AND PROTOCOL

The Enhanced ICSP interface is a 2-wire SPI, implemented using the PGECx and PGEDx pins. The PGECx pin is used as a clock input pin and the clock source must be provided by the programmer. The PGEDx pin is used for sending command data to and receiving response data from the Programming Executive.

Note: For Enhanced ICSP, all serial data is transmitted on the falling edge of PGECx and latched on the rising edge of PGECx. All data transmissions are sent to the Most Significant bit first, using 16-bit mode (see [Figure 6-1](#)).

FIGURE 6-1: PROGRAMMING EXECUTIVE SERIAL TIMING



Since a 2-wire SPI is used, and data transmissions are bidirectional, a simple protocol is used to control the direction of PGEDx. When the programmer completes a command transmission, it releases the PGEDx line and allows the Programming Executive to drive this line high. The Programming Executive keeps the PGEDx line high to indicate that it is processing the command.

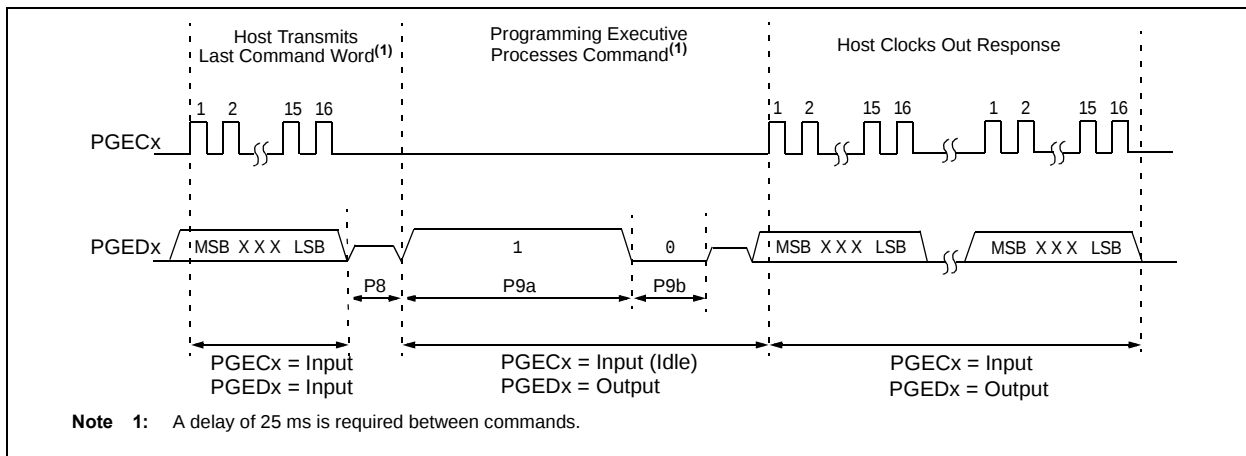
After the Programming Executive has processed the command, it brings PGEDx low (P9b) to indicate to the programmer that the response is available to be clocked out. The programmer can begin to clock out the response after a maximum Wait (P9b) and it must provide the necessary amount of clock pulses to receive the entire response from the Programming Executive.

After the entire response is clocked out, the programmer should terminate the clock on PGECx until it is time to send another command to the Programming Executive. This protocol is illustrated in [Figure 6-2](#).

6.1.2 SPI RATE

In Enhanced ICSP mode, devices operate from the Fast Internal RC oscillator, which has a nominal frequency of 7.3728 MHz. This oscillator frequency yields an effective system clock frequency of 1.8432 MHz. To ensure that the programmer does not clock too fast, it is recommended that a 1.85 MHz clock be provided by the programmer.

FIGURE 6-2: PROGRAMMING EXECUTIVE – PROGRAMMER COMMUNICATION PROTOCOL



PIC24FJXXMC PROGRAMMING SPECIFICATION

6.1.3 TIME-OUTS

The Programming Executive uses no Watchdog Timer or time-out for transmitting responses to the programmer. If the programmer does not follow the flow control mechanism using PGECx, as described in [Section 6.1.1 “Communication Interface and Protocol”](#), it is possible that the Programming Executive will behave unexpectedly while trying to send a response to the programmer. Since the Programming Executive has no time-out, it is imperative that the programmer correctly follow the described communication protocol.

As a safety measure, the programmer should use the command time-outs identified in [Table 6-1](#). If the command time-out expires, the programmer should reset the Programming Executive and start programming the device again.

TABLE 6-1: PROGRAMMING EXECUTIVE COMMAND SET

Opcode	Mnemonic	Length (16-bit words)	Time-Out	Description
0x0	SCHECK	1	1 ms	Sanity check.
0x1	READC	3	1 ms	Read an 8-bit word from the specified Device ID register.
0x2	READP	4	1 ms/word	Read 'N' 24-bit instruction words of code memory, starting from the specified address.
0x3	Reserved	N/A	N/A	This command is reserved; it will return a NACK.
0x4	Reserved	N/A	N/A	This command is reserved; it will return a NACK.
0x5	PROGP	99	5 ms	Program 64 instruction words of program memory at the specified starting address and verify.
0x6	Reserved	N/A	N/A	This command is reserved; it will return a NACK.
0x7	Reserved	N/A	N/A	This command is reserved; it will return a NACK.
0x8	Reserved	N/A	N/A	This command is reserved; it will return a NACK.
0x9	ERASEP	3	20 ms	Command to erase a page.
0xA	Reserved	N/A	N/A	This command is reserved; it will return a NACK.
0xB	QVER	1	1 ms	Query the Programming Executive software version.
0xC	CRCP	5	1s	Perform a CRC-16 on the specified range of program memory.
0xD	PROGW	4	5 ms	Program one instruction word of code memory at the specified address and then verify.
0xE	QBLANK	5	700 ms	Query to check whether the code memory is blank.

PIC24FJXXMC PROGRAMMING SPECIFICATION

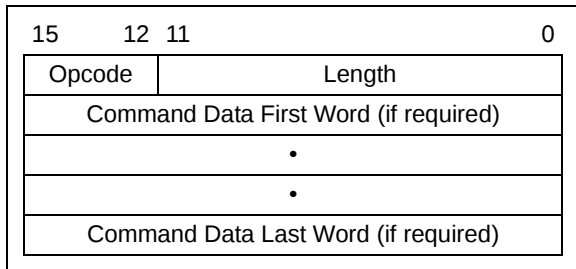
6.2 Programming Executive Commands

The Programming Executive command set is shown in [Table 6-1](#). This table contains the opcode, mnemonic, length, time-out and description for each command. Functional details on each command are provided in the command descriptions ([Section 6.2.4 “Command Descriptions”](#)).

6.2.1 COMMAND FORMAT

All Programming Executive commands have a general format, consisting of a 16-bit header and any required data for the command (see [Figure 6-3](#)). The 16-bit header consists of a 4-bit opcode field, which is used to identify the command, followed by a 12-bit command length field.

FIGURE 6-3: COMMAND FORMAT



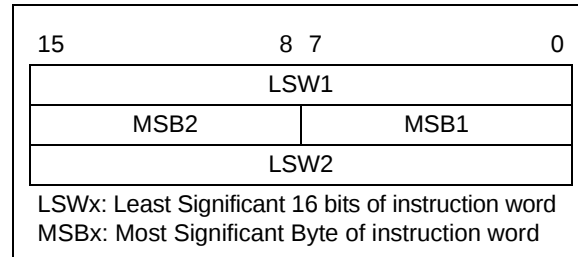
The command opcode must match one of those in the command set. Any command that is received, which does not match the list in [Table 6-1](#) will return a “NACK” response (see [Section 6.3.1.1 “Opcode Field”](#)).

The command length is represented in 16-bit words, since the SPI operates in 16-bit mode. The Programming Executive uses the command length field to determine the number of words to read from the SPI port. If the value of this field is incorrect, the command will not be properly received by the Programming Executive.

6.2.2 PACKED DATA FORMAT

When 24-bit instruction words are transferred across the 16-bit SPI interface, they are packed to conserve space using the format illustrated in [Figure 6-4](#). This format minimizes traffic over the SPI and provides the Programming Executive with data that is properly aligned for performing table write operations.

FIGURE 6-4: PACKED INSTRUCTION WORD FORMAT



Note: When the number of instruction words transferred is odd, MSB2 is zero and LSW2 cannot be transmitted.

6.2.3 PROGRAMMING EXECUTIVE ERROR HANDLING

The Programming Executive will “NACK” all unsupported commands. Additionally, due to the memory constraints of the Programming Executive, no checking is performed on the data contained in the programmer command. It is the responsibility of the programmer to command the Programming Executive with valid command arguments or the programming operation may fail. Additional information on error handling is provided in [Section 6.3.1.3 “QE_Code Field”](#).

PIC24FJXXMC PROGRAMMING SPECIFICATION

6.2.4 COMMAND DESCRIPTIONS

All commands supported by the Programming executive are described in [Section 6.2.4.1 “SCHECK Command”](#) through [Section 6.2.4.6 “QVER Command”](#).

6.2.4.1 SCHECK Command

15	12	11	0
Opcode	Length		

Field	Description
Opcode	0x0
Length	0x1

The SCHECK command instructs the Programming Executive to do nothing but generate a response. This command is used as a “Sanity Check” to verify that the Programming Executive is operational.

Expected Response (2 words):

0x1000
0x0002

Note: This instruction is not required for programming, but is provided for development purposes only.

6.2.4.2 READC Command

15	12	11	8	7	0
Opcode		Length			
N			Addr_MSB		
Addr_LS					

Field	Description
Opcode	0x1
Length	0x3
N	Number of 16-bit Device ID registers to read (maximum of 256).
Addr_MSB	MSB of 24-bit source address.
Addr_LS	Least Significant 16 bits of 24-bit source address.

The READC command instructs the Programming Executive to read N Device ID registers, starting from the 24-bit address specified by Addr_MSB and Addr_LS. This command can only be used to read 8-bit or 16-bit data.

When this command is used to read Device ID registers, the upper byte in every data word returned by the Programming Executive is 0x00 and the lower byte contains the Device ID register value.

Expected Response ($4 + 3 * (N - 1)/2$ words for N odd):

0x1100
2 + N
Device ID Register 1
...
Device ID Register N

Note: Reading unimplemented memory will cause the Programming Executive to reset. Please ensure that only memory locations present on a particular device are accessed.

PIC24FJXXMC PROGRAMMING SPECIFICATION

6.2.4.3 READP Command

15	12	11	8	7	0
Opcode		Length			
N					
Reserved			Addr_MSB		
Addr_LS					

Field	Description
Opcode	0x2
Length	0x4
N	Number of 24-bit instructions to read (maximum of 32768).
Reserved	0x0
Addr_MSB	MSB of 24-bit source address.
Addr_LS	Least Significant 16 bits of 24-bit source address.

The READP command instructs the Programming Executive to read N 24-bit words of code memory, starting from the 24-bit address specified by Addr_MSB and Addr_LS. This command can only be used to read 24-bit data. All data returned in the response to this command uses the packed data format described in [Section 6.2.2 “Packed Data Format”](#).

Expected Response (2 + 3 * N/2 words for N even):

0x1200

2 + 3 * N/2

Least Significant Program Memory Word 1

...

Least significant data word N

Expected Response (4 + 3 * (N – 1)/2 words for N odd):

0x1200

4 + 3 * (N – 1)/2

Least Significant Program Memory Word 1

...

MSB of Program Memory Word N (zero padded)

Note: Reading unimplemented memory will cause the Programming Executive to reset. Please ensure that only memory locations present on a particular device are accessed.

6.2.4.4 PROGP Command

15	12	11	8	7	0
Opcode		Length			
Reserved			Addr_MSB		
Addr_LS					
D_1					
D_2					
...					
D N					

Field	Description
Opcode	0x5
Length	0x63
Reserved	0x0
Addr_MSB	MSB of 24-bit destination address.
Addr_LS	Least Significant 16 bits of 24-bit destination address.
D_1	16-Bit Data Word 1.
D_2	16-Bit Data Word 2.
...	16-Bit Data Word 3 through 95.
D_96	16-Bit Data Word 96.

The PROGP command instructs the Programming Executive to program 64 instruction words, starting at the specified memory address.

The data to program the memory, located in command words, D_1 through D_96, must be arranged using the packed instruction word format illustrated in [Figure 6-4](#).

After all data has been programmed to code memory, the Programming Executive verifies the programmed data against the data in the command.

Expected Response (2 words):

0x1500

0x0002

Note: Refer to [Table 2-2](#) for code memory size information.

PIC24FJXXMC PROGRAMMING SPECIFICATION

6.2.4.5 ERASEP Command

15 12 11 8 7 0

Opcode	Length
NUM_PAGES	Addr_MSB
Addr_LS	

Field	Description
Opcode	0x9
Length	0x3
NUM_PAGES	Up to 255.
Addr_MSB	Most Significant Byte of the 24-bit address.
Addr_LS	Least Significant 16 bits of the 24-bit address.

The ERASEP command instructs the Programming Executive to Page Erase [NUM_PAGES] of code memory. The code memory must be erased at an “even” 512 instruction word address boundary

Expected Response (2 words):

0x1900

0x0002

6.2.4.6 QVER Command

15 12 11 0

Opcode	Length
--------	--------

Field	Description
Opcode	0xB
Length	0x1

The QVER command queries the version of the Programming Executive software stored in test memory. The “version.revision” information is returned in the response’s QE_Code using a single byte with the following format: main version in upper nibble and revision in the lower nibble (i.e., 0x23 means Version 2.3 of Programming Executive software).

Expected Response (2 words):

0x1BMN (where “MN” stands for version M.N)

0x0002

6.2.4.7 CRCP Command

15 12 11 8 7 0

Opcode	Length
Reserved	Addr_MSB
Addr_LSW	
Reserved	Size_MSB
Size_LSW	

Field	Description
Opcode	0xC
Length	0x5
Reserved	0x0
Addr_MSB	Most Significant Byte of 24-bit address.
Addr_LSW	Least Significant 16 bits of 24-bit address.
Size	Number of 24-bit locations (address range divided by 2).

The CRCP command performs a CRC-16 on the range of memory specified. This command can substitute for a full chip verify. Data is shifted in a packed method, as demonstrated in [Figure 6-4](#), byte-wise Least Significant Byte first.

Example:

CRC-CCITT-16 with test data of “123456789” becomes 0x29B1

Expected Response (3 words):

QE_Code: 0x1C00

Length: 0x0003

CRC Value: 0XXXXX

PIC24FJXXMC PROGRAMMING SPECIFICATION

6.2.4.8 PROGW Command

15	12	11	8	7	0
Opcode		Length			
Data_MSB			Addr_MSB		
Addr_LS					
Data_LS					

Field	Description
Opcode	0xD
Length	0x4
Data_MSB	MSB of 24-bit data.
Addr_MSB	MSB of 24-bit destination address.
Addr_LS	Least Significant 16 bits of 24-bit destination address.
Data_LS	Least Significant 16 bits of 24-bit data.

The PROGW command instructs the Programming Executive to program one instruction word of code memory (3 bytes) to the specified memory address.

After the word has been programmed to code memory, the Programming Executive verifies the programmed data against the data in the command.

Expected Response (2 words):

0x1D00
0x0002

6.2.4.9 QBLANK Command

15	12	11	0
Opcode		Length	
Reserved		Size_MSB	
Size_LSW			
Reserved		Addr_MSB	
Addr_LSW			

Field	Description
Opcode	0xE
Length	0x5
Size	Length of program memory to check (in 24-bit words) + Addr_MS.
Addr_MSB	Most Significant Byte of the 24-bit address.
Addr_LSW	Least Significant 16 bits of the 24-bit address.

The QBLANK command queries the Programming Executive to determine if the contents of code memory are blank (contains all '1's). The size of code memory to check must be specified in the command.

The Blank Check for code memory begins at [Addr] and advances toward larger addresses for the specified number of instruction words.

QBLANK returns a QE_Code of 0xF0 if the specified code memory is blank; otherwise, QBLANK returns a QE_Code of 0x0F.

Expected Response (2 words for blank device):

0x1EF0
0x0002

Expected Response (2 words for non-blank device):

0x1E0F
0x0002

Note: Ensure that the address range selected excludes the configuration bytes at the top of memory when using the QBLANK command; otherwise, a non-blank response will be generated.

PIC24FJXXMC PROGRAMMING SPECIFICATION

6.3 Programming Executive Responses

The Programming Executive sends a response to the programmer for each command that it receives. The response indicates if the command was processed correctly. It includes any required response data or error data.

The Programming Executive response set is shown in [Table 6-2](#). This table contains the opcode, mnemonic and description for each response. The response format is described in [Section 6.3.1 “Response Format”](#).

TABLE 6-2: PROGRAMMING EXECUTIVE RESPONSE OPCODES

Opcode	Mnemonic	Description
0x1	PASS	Command successfully processed.
0x2	FAIL	Command unsuccessfully processed.
0x3	NACK	Command not known.

6.3.1 RESPONSE FORMAT

All Programming Executive responses have a general format consisting of a two-word header and any required data for the command.

15	12	11	8	7	0
Opcode		Last_Cmd		QE_Code	
Length					
D_1 (if applicable)					
...					
D_N (if applicable)					

Field	Description
Opcode	Response opcode.
Last_Cmd	Programmer command that generated the response.
QE_Code	Query code or error code.
Length	Response length in 16-bit words (includes 2 header words).
D_1	First 16-bit data word (if applicable).
D_N	Last 16-bit data word (if applicable).

6.3.1.1 Opcode Field

The opcode is a 4-bit field in the first word of the response. The opcode indicates how the command was processed (see [Table 6-2](#)). If the command was processed successfully, the response opcode is PASS. If there was an error in processing the command, the response opcode is FAIL and the QE_Code indicates the reason for the failure. If the command sent to the Programming Executive is not identified, the Programming Executive returns a NACK response.

PIC24FJXXMC PROGRAMMING SPECIFICATION

6.3.1.2 Last_Cmd Field

The Last_Cmd is a 4-bit field in the first word of the response and indicates the command that the Programming Executive processed. Since the Programming Executive can only process one command at a time, this field is technically not required. However, it can be used to verify that the Programming Executive correctly received the command that the programmer transmitted.

6.3.1.3 QE_Code Field

The QE_Code is a byte in the first word of the response. This byte is used to return data for query commands and error codes for all other commands.

When the Programming Executive processes one of the two query commands (QBLANK or QVER), the returned opcode is always PASS and the QE_Code holds the query response data. The format of the QE_Code for both queries is shown in Table 6-3.

TABLE 6-3: QE_Code FOR QUERIES

Query	QE_Code
QBLANK	0x0F = Code memory is NOT blank 0xF0 = Code memory is blank
QVER	0xMN, where Programming Executive software version = M.N (i.e., 0x32 means Software Version 3.2).

When the Programming Executive processes any command other than a Query, the QE_Code represents an error code. Supported error codes are shown in Table 6-4. If a command is successfully processed, the returned QE_Code is set to 0x0, which indicates that there is no error in the command processing. If the verify of the programming for the PROGW command fails, the QE_Code is set to 0x1. For all other Programming Executive errors, the QE_Code is 0x2.

TABLE 6-4: QE_Code FOR NON-QUERY COMMANDS

QE_Code	Description
0x0	No error.
0x1	Verify failed.
0x2	Other error.

6.3.1.4 Response Length

The response length indicates the length of the Programming Executive's response in 16-bit words. This field includes the 2 words of the response header.

With the exception of the response for the read commands, the length of each response is only 2 words.

The response to the read commands uses the packed instruction word format, described in Section 6.2.2 "Packed Data Format". When reading an odd number of program memory words (N odd), the response to the READP command is $(3 * (N + 1) / 2 + 2)$ words. When reading an even number of program memory words (N even), the response to the READP command is $(3 * N / 2 + 2)$ words.

PIC24FJXXMC PROGRAMMING SPECIFICATION

7.0 DEVICE ID

The Device ID region of memory can be used to determine variant and manufacturing information about the chip. This region of memory is read-only and can be read when code protection is enabled.

[Table 7-1](#) lists the identification information for the PIC24FJXXMC10X devices. [Table 7-2](#) shows the Device ID registers.

TABLE 7-1: DEVICE IDs AND REVISION

Device	DEVID Register Value	Application ID	DEVREV Register Value and Silicon Revision
PIC24FJ16MC101	0x0206	0xCD	0x3001 – A1 Revision
PIC24FJ16MC102	0x0207	0xCD	
PIC24FJ32MC101	0x0A0C	0xCD	0x3000 – A0 Revision
PIC24FJ32MC102	0x0A0D	0xCD	
PIC24FJ32MC104	0x0A0F	0xCD	

TABLE 7-2: DEVICE ID REGISTERS

Address	Name	Bit															
		15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0xFF0000	DEVID	DEVID Value															
0xFF0002	DEVREV	DEVREV Value															

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8.0 CHECKSUM COMPUTATION

Checksums for the devices listed below are 16 bits in size. The checksum is calculated by summing the following:

- Contents of code memory locations
- Contents of Configuration Words

All memory locations are summed, one byte at a time, using only their native data size. Configuration bytes are summed by adding the lower two bytes of these locations (the upper byte is ignored), while code memory is summed by adding all three bytes of code memory.

Table 8-1 is an example of the checksum calculation for the PIC24FJ16MC10X device. Table 8-2 describes the Configuration bit masks for the PIC24FJXXMC10X devices.

TABLE 8-1: CHECKSUM COMPUTATION EXAMPLE

Device	Read Code Protection	Checksum Computation	Erased Value	Value with 0xAAAAAA at 0x0 and Last Code Address
PIC24FJ16MC10X	Disabled	CFGB + SUM(0:0x002BFA)	0xF804	0xF606
	Enabled	Reads of program memory return 0x00	0x0000	0x0000

Item Description:

SUM(a:b) = Byte sum of locations, a to b inclusive (all 3 bytes of code memory)

CFGB = Configuration block (masked) = Byte sum of (CONFIG1 & 0x3FFF + CONFIG2 & 0xFFFF)

CFGB = Configuration block (masked) = Byte sum of ((0x7FFF & 0x3FFF) + (0xFFFF & 0xFFFF))

TABLE 8-2: PIC24FJXXMC10X CONFIGURATION BIT MASKS

Device	CONFIG2	CONFIG1
PIC24FJ16MC10X ⁽¹⁾	0xFFFF	0x3FFF
PIC24FJ32MC10X ⁽¹⁾	0xFFFF	0x3FFF

Note 1: Includes all 20, 28 and 40/44-pin (if applicable) devices.

PIC24FJXXMC PROGRAMMING SPECIFICATION

9.0 AC/DC CHARACTERISTICS AND TIMING REQUIREMENTS

Table 9-1 lists the AC/DC characteristics and timing requirements.

TABLE 9-1: AC/DC CHARACTERISTICS AND TIMING REQUIREMENTS

Standard Operating Conditions Operating Temperature: -40°C to +85°C. Programming at +25°C is recommended.						
Param No.	Symbol	Characteristic	Min.	Max.	Units	Conditions
D111	VDD	Supply Voltage During Programming	3.0	3.60	V	Normal programming, see Note 1
D112	IPP	Programming Current on $\overline{\text{MCLR}}$	—	5	μA	
D113	IDDP	Supply Current During Programming	—	10	mA	
D114	IPEAK	Instantaneous Peak Current During Start-up	—	45	mA	
D031	VIL	Input Low Voltage	VSS	0.2 VDD	V	
D041	VIH	Input High Voltage	0.8 VDD	VDD	V	
D080	VOL	Output Low Voltage	—	0.6	V	IOL = 8.5 mA @ 3.6V
D090	VOH	Output High Voltage	VDD – 0.7	—	V	IOH = -3.0 mA @ 3.6V
D012	CIO	Capacitive Loading on I/O pin (PGEDx)	—	50	pF	To meet AC specifications
P1	TPGC	Serial Clock (PGECx) Period (ICSP™)	200	—	ns	
P1	TPGC	Serial Clock (PGECx) Period (Enhanced ICSP)	500	—	ns	
P1A	TPGCL	Serial Clock (PGECx) Low Time (ICSP)	80	—	ns	
P1A	TPGCL	Serial Clock (PGECx) Low Time (Enhanced ICSP)	200	—	ns	
P1B	TPGCH	Serial Clock (PGECx) High Time (ICSP)	80	—	ns	
P1B	TPGCH	Serial Clock (PGECx) High Time (Enhanced ICSP)	200	—	ns	
P2	TSET1	Input Data Setup Time to Serial Clock ↓	15	—	ns	
P3	THLD1	Input Data Hold Time from PGECx ↓	15	—	ns	
P4	TDLY1	Delay between 4-bit Command and Command Operand	40	—	ns	
P4A	TDLY1A	Delay between Command Operand and Next 4-bit Command	40	—	ns	
P5	TDLY2	Delay between Last PGECx ↓ of Command to First PGECx ↑ of Read of Data Word	20	—	ns	
P6	TSET2	VDD ↑ Setup Time to $\overline{\text{MCLR}}$ ↑	100	—	ns	
P7	THLD2	Input Data Hold Time from $\overline{\text{MCLR}}$ ↑	25	—	ms	
P8	TDLY3	Delay between Last PGECx ↓ of Command Byte to PGEDx ↑ by Programming Executive	12	—	μs	
P9a	TDLY4	Programming Executive Command Processing Time	10	—	μs	

Note 1: VDD must also be supplied to the AVDD pins during programming. AVDD and AVSS should always be within ±0.3V of VDD and VSS, respectively.

2: Time depends on the FRC accuracy and the value of the FRC Oscillator Tuning register. Refer to the “**Electrical Characteristics**” chapter in the specific device data sheet.

3: This time applies to both Program Memory Words and Configuration Words.

PIC24FJXXMC PROGRAMMING SPECIFICATION

TABLE 9-1: AC/DC CHARACTERISTICS AND TIMING REQUIREMENTS (CONTINUED)

Standard Operating Conditions						
Operating Temperature: -40°C to +85°C. Programming at +25°C is recommended.						
Param No.	Symbol	Characteristic	Min.	Max.	Units	Conditions
P9b	TDLY5	Delay between PGEDx ↓ by Programming Executive to PGEDx Released by Programming Executive	15	23	μs	
P10	TDLY6	PGECx Low Time After Programming	400	—	ns	
P11	TDLY7	Bulk Erase Time	200	240	ms	See Note 2
P12	TDLY8	Page Erase Time	20.1	26.5	ms	See Note 2
P13	TDLY9	Word Programming Time	47.9	—	μs	See Note 2 and Note 3
P14	TR	MCLR Rise Time to Enter ICSP mode	—	1.0	μs	
P15	TVALID	Data Out Valid from PGECx ↑	10	—	ns	
P16	TDLY10	Delay between Last PGECx ↓ and MCLR ↓	0	—	s	
P17	THLD3	MCLR ↓ to VDD ↓	100	—	ns	
P18	TKEY1	Delay from First MCLR ↓ to First PGECx ↑ for Key Sequence on PGEDx	1	—	ms	
P19	TKEY2	Delay from Last PGECx ↓ for Key Sequence on PGEDx to Second MCLR ↑	25	—	ns	
P21	TMCLRH	MCLR High Time	—	500	μs	

Note 1: VDD must also be supplied to the AVDD pins during programming. AVDD and AVSS should always be within ±0.3V of VDD and VSS, respectively.

2: Time depends on the FRC accuracy and the value of the FRC Oscillator Tuning register. Refer to the “**Electrical Characteristics**” chapter in the specific device data sheet.

3: This time applies to both Program Memory Words and Configuration Words.

PIC24FJXXMC PROGRAMMING SPECIFICATION

APPENDIX A: HEX FILE FORMAT

Flash programmers process the standard Hex format used by the Microchip development tools. The format supported is the Intel® HEX32 Format (INHX32). Please refer to Appendix A in the “*MPASM™ Assembler, MPLINK™ Object Linker, MPLIB™ Object Librarian User's Guide*” (DS33014) for more information about Hex file formats.

The basic format of the Hex file is:

:BBAATTHHHH...HHHCC

Each data record begins with a 9-character prefix and always ends with a 2-character checksum. All records begin with ':' regardless of the format. The individual elements are described below.

- BB – is a two-digit hexadecimal byte count, representing the number of data bytes that appear on the line. Divide this number by two to get the number of words per line.
- AAAA – is a four-digit hexadecimal address, representing the starting address of the data record. Format is high byte first, followed by low byte. The address is doubled because this format only supports 8 bits. Divide the value by two to find the real device address.
- TT – is a two-digit record type that will be '00' for data records, '01' for end-of-file records and '04' for extended address records.
- HHHH – is a four-digit hexadecimal data word. Format is low byte followed by high byte. There will be BB/2 data words following TT.
- CC – is a two-digit hexadecimal checksum that is the two's complement of the sum of all the preceding bytes in the line record.

Because the Intel Hex file format is byte-oriented, and the 16-bit Program Counter (PC) is not, program memory sections require special treatment. Each 24-bit program word is extended to 32 bits by inserting a so-called “phantom byte”. Each program memory address is multiplied by 2 to yield a byte address.

As an example, a section that is located at 0x100 in program memory will be represented in the Hex file as 0x200.

The Hex file will be produced with the following contents:

:020000040000fa

:040200003322110096

:00000001FF

Notice that the data record (line 2) has a load address of 0200, while the source code specified address, 0x100. Note also that the data is represented in “little-endian” format, meaning the Least Significant Byte (LSB) appears first. The phantom byte appears last, just before the checksum.

PIC24FJXXMC PROGRAMMING SPECIFICATION

APPENDIX B: REVISION HISTORY

Revision A (May 2011)

This is the initial released version of this document.

Revision B (June 2012)

Added three new devices (PIC24FJ32MC101/102/104) to the specification. This addition includes the following changes:

- Additions to [Table 2-2](#)
- Addition of new [Table 2-4](#) for all new devices
- Additions to [Table 7-1](#)
- Changes to [Table 8-2](#) to accommodate new devices

Note the following details of the code protection feature on Microchip devices:

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