## **AN1355**

## A Complete Electronic Watch Based on MCP79410 I<sup>2</sup>C RTCC

Author: Alexandru Valeanu

Microchip Technology Inc.

#### INTRODUCTION

An increasing number of applications that involve time measurement are requiring a Real-Time Clock/ Calendar (RTCC) device. The MCP79410 is a feature-rich RTCC that incorporates EEPROM, SRAM, unique ID and timestamp.

#### FEATURES OF THE RTCC

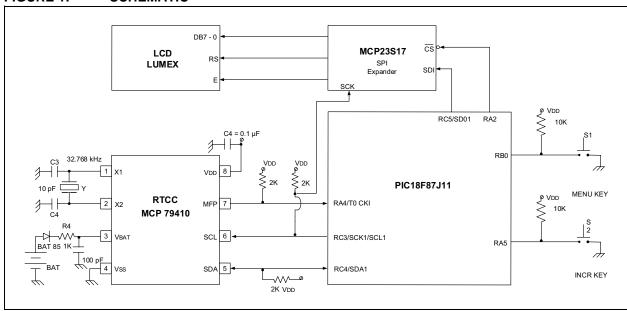
- I<sup>2</sup>C Bus Interface
- RTCC with Time/Date Registers: Year, Month, Date, Day of Week, Hours, Minutes, Seconds
- · Support for Leap Year
- · Low-Power CMOS Technology
- Input for External Battery Backup (maintains SRAM, RTCC and Timekeeping)
- On-Board 32.768 kHz Crystal Oscillator for the RTCC

- On-Chip Digital Trimming/Calibration of the Oscillator
- Operates down to 1.3V VBAT Minimum
- · Operating Temperature Range:
  - Industrial (I): -40°C to +85°C
- · Multifunction Pin:
  - Open-Drain configuration
  - Programmable clock frequency out
  - Programmable alarm output
- Interrupt Capability (based on the two sets of Alarm Registers, ALM0 and ALM1)
- Timestamp Registers for Holding the Time/Date of Crossing:
  - from VDD to VBAT
  - from VBAT to VDD

#### **SCHEMATIC**

The schematic includes a PIC18 Explorer demo board and the I<sup>2</sup>C RTCC PICtail™ daughter board as shown in Figure 1.

#### FIGURE 1: SCHEMATIC



The resources used on the demo board are:

- · LCD module
- · Two push buttons
- AC164140 RTCC PICtail™ daughter board

To access the LCD through a minimum of pins, the SPI on the MSSP1 module is used, in conjunction with a 16-bit I/O expander with SPI interface (MCP23S17). The two on-board push buttons are S1 and S2, connected to RB0, RA5 GPIOs. The I<sup>2</sup>C RTCC is part of the RTCC PICtail evaluation board and is directly connected to the MSSP1 module of the microcontroller. Another necessary connection is between the MFP signal of the RTCC and RA4 (T0CKI), the clock input of TMR0. The RTCC is programmed to offer a square wave of 1 Hz on MFP. TMR0 is programmed as the counter and is initialized at 0xFFFF, in order to give a software interrupt at every second. All connections between the I<sup>2</sup>C RTCC and the microcontroller (SDA, SCL, MFP) are open-drain and use pull-up resistors. The RTCC PICtail daughter board has two other components:

- a 32.768 Hz crystal driving the internal clock of the RTCC
- a 3-volt battery sustaining the RTCC when VDD is not present on the demo board

#### **DETAILS ABOUT IMPLEMENTATION**

The application is designed around a PIC18 Explorer demo board on which is mounted a PIC18F87J11 microcontroller. The code is written in C using the C18 compiler. It implements an electronic watch (based on the MCP79410 RTCC), displaying the six basic time/date variables on the on-board LCD. It includes a setup sequence, which sets the same six time/date variables, using the two push buttons of the evaluation board (S1 = MENU KEY, S2 = INCREMENT KEY).

#### **FUNCTIONAL DESCRIPTION**

The MCP79410 is an  $I^2C$  slave device, working on the related bidirectional 2-wire bus. SDA is a bidirectional pin used to transfer addresses and data in and out of the device. It is an open-drain terminal, therefore, the SDA bus requires a pull-up resistor to VCC (typically 10 k $\Omega$  for 100 kHz and 2 k $\Omega$  for 400 kHz). For normal data transfers, SDA is allowed to change only during SCL low. Changes during SCL high are reserved for indicating the Start and Stop conditions. SCL input is used to synchronize the data transfer from and to the device. The related internal structures have the following device addresses/control bytes (the RTCC is included in the SRAM bank):

- RTCC + SRAM: 0xDE for writes, 0xDF for reads
- · EEPROM: 0xAE for writes, 0xAF for reads

The chip can support speeds up to:

- 400 kHz at 2.5 to 5V
- 100 kHz at 1.8 to 2.5V

#### APPLICATION DESCRIPTION

The application performs an electronic watch that has two main functions:

- display of the six time/date variables (year, month, date, hour, minutes, seconds) using the interrupts of the microcontroller (this operation is performed on the on-board LCD; the format is 24 hours)
- setup of the above variables using the two onboard push buttons: S1 = MENU KEY, S2 = INCREMENT KEY. The real-time display of the time/date variables is performed as long as the MENU KEY (S1) is not pressed (the action of the INCREMENT KEY (S2) has no effect on the watch continuously displaying the time and the date)

Pressing the MENU KEY will start the setup menu, disabling the interrupts. The menu is covered once in the following order: year, month, date, hour, minutes, and seconds. Going from one variable to another is performed through the MENU KEY, and incrementing a variable is performed through the INCREMENT KEY. The last action of the MENU KEY exits the setup menu. Accordingly, to correct a possible setup error, the setup menu must be re-entered. The upper limits of every variable are:

- year = (20) 99
- month = 12
- date = (always) 31
- hour = 23 (24 hours format)
- minutes = 59
- seconds = 59

Entering the setup menu will not stop the oscillator of the RTCC. At the end of the setup, the time/date variables are updated and entering the menu will stop the counting. If the user enters the Time Setup mode, all changes are written to the RTCC, even if no variables are changed. When entering the menu, the watch will resume counting from the point where it was stopped.

#### FIRMWARE DESCRIPTION

#### **Drivers**

Drivers are divided into 4 classes:

- · LCD drivers
- · RTCC register access drivers
- Drivers related to the operating system (setup menu): keyboard drivers
- Interrupt system drivers (the interrupt function based on TMR0's overflow and the related functions (interrupt initialization, start/stop interrupts))

#### **LCD Drivers**

The application is specifically implemented on the PIC18 Explorer demo board. On this board, it was important to reduce the number of GPIO pins used to access the LCD. Accessing the LCD is performed on a SPI bus (included in the MSSP1 module) through an auxiliary chip, the MCP23S17 SPI expander. The related drivers are:

- Write command to LCD: wrcmnd\_lcd (unsigned char cmnd\_lcd)
- Write data byte/character to LCD: wrdata\_lcd (unsigned char data\_lcd)
- Write to LCD a string stored in the flash: wrstr\_lcd (const rom unsigned char \*str\_lcd)

#### **Drivers to Access RTCC Register**

Since the MCP79410 is an  $I^2C$  RTCC, it will use the  $I^2C$  bus of the microcontroller (the MSSP1 module). Accordingly, the related drivers will be divided into two categories:

- basic I<sup>2</sup>C drivers
- · RTCC drivers

They use as a control method the SPP1IF bit (flag) in the PIR1 register (interrupt flag of the MSSP1 module). They read through polling and not through interrupts, since interrupts are allocated to display the time/date using TMR0's overflow, once per second. Keep in mind that TMR0 acts as a counter, and its input is activated by the MFP signal coming from the RTCC (programmed as an one-second square wave). The method represents an alternative to the classical "i2c.h" library, included in the C18 compiler.

FIGURE 2: FLOWCHART FOR A
TYPICAL WRITE
OPERATION (FOR A
RANDOM BYTE ACCESS):

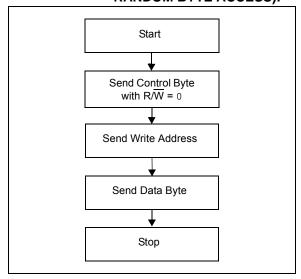
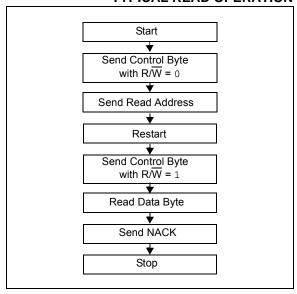


FIGURE 3: FLOWCHART FOR A
TYPICAL READ OPERATION



The two related functions are:

- void rtcc\_wr (unsigned char time\_var, unsigned char rtcc\_req)
- unsigned char rtcc\_rd (unsigned char rtcc\_reg)

#### **Keyboard Drivers (2 keys O.S.)**

The set of keyboard drivers has only one function: keyb\_press(). The keyb\_press() function awaits the selection of one of the two on-board switches: S1 (MENU KEY) or S2 (INCREMENT KEY). After the selection is made, the firmware updates the code of the pressed key. Upon exiting the function, a value is returned in either KEYB\_MENU or KEYB\_INCR. The function performs a key debounce of (2 x 100 msec). The function will exit only after the pressed key is released (deactivated). For more details about the operating system based on the two on-board switches, refer to the "Application Description" paragraph.

#### The Interrupt Function

Interrupts are generated by the TMR0 overflow, which is initialized at 0xFFFF as a counter. TIMER0 is incremented once per second by the MFP signal coming from the RTCC. The interrupt function calls one function: display\_time(), which reads the six related registers of the RTCC and puts them in the six global variables (year, month, date, hour, minute, seconds). The Random Byte Access mode is used, as some versions of the application can use only a subset of these six variables.

In the end, the interrupt function (through the display\_time() driver) displays these six variables on the on-board LCD, according to the format below:

ROW1: "date" string year month date
ROW2: "time" string hour minutes seconds

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#### ACCESSING THE RTCC REGISTERS

There are two basic functions for accessing the RTCC register: one for writes and one for reads. They can be defined as:

- void rtcc\_wr (unsigned char time\_var, unsigned char rtcc\_reg)
- unsigned char rtcc\_rd (unsigned char rtcc\_reg)

Each of these two functions include error messages displayed on LEDs, which could signal when an operation is not acknowledged by the slave (RTCC).

#### **EXAMPLE 1: WRITES TO THE RTCC**

#### **EXAMPLE 2: READS FROM THE RTCC**

```
start I<sup>2</sup>C communication: SDA goes down while SCL remains high
i2c_start()
                        ; //
                                send the RTCC's address for write = 0xde
i2c_wr(ADDR_RTCC_WRITE); //
i2c_wr(rtcc_reg)
                        ; //
                                send the register's address
i2c_restart()
                        ; //
                                switch to reads
i2c_wr(ADDR_RTCC_READ); //
                                send the RTCC's address for read = 0xdf
i2c_rd()
                        ; //
                                read the byte from the RTCC (register's content)
i2c nack
                        ; //
                                NoACK from MCU to the RTCC (no more bytes to read)
i2c_stop()
                        ; //
                                stop I<sup>2</sup>C communication: SDA goes high while SCL remains high
```

As described in the data sheet, the addresses of the RTCC register are shown in Table 1.

TABLE 1: RTCC REGISTER ADDRESSES

Address	Register Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
00h	RTCSEC	ST	SECTEN2	SECTEN1	SECTEN0	SECONE3	SECONE2	SECONE1	SECONE0
01h	RTCMIN	-	MINTEN2	MINTEN1	MINTEN0	MINONE3	MINONE2	MINONE1	MINONE0
02h	RTCHOUR	_	12/24	AM/PM HRTEN1	HRTEN0	HRONE3	HRONE2	HRONE1	HRONE0
03h	RTCWKDAY	_	_	OSCRUN	PWRFAIL	VBATEN	WKDAY2	WKDAY1	WKDAY0
04h	RTCDATE	-	-	DATETEN1	DATETEN0	DATEONE3	DATEONE2	DATEONE1	DATEONE0
05h	RTCMTH	1	1	LPYR	MTHTEN0	MTHONE3	MTHONE2	MTHONE1	MTHONE0
06h	RTCYEAR	YRTEN3	YRTEN2	YRTEN1	YRTEN0	YRONE3	YRONE2	YRONE1	YRONE0
07h	CONTROL	OUT	SQWEN	ALM1EN	ALM0EN	EXTOSC	CRSTRIM	SQWFS1	SQWFS0
08h	OSCTRIM	SIGN	TRIMVAL6	TRIMVAL5	TRIMVAL4	TRIMVAL3	TRIMVAL2	TRIMVAL1	TRIMVAL0
09h	EEUNLOCK	Protected EEPROM Unlock Register (not a physical register)							

According to these addresses, in the basic read/write functions, only the register's address will differ. Reads are used in the interrupt function (once/second).

Writes are used in the initialization function and in the setup sequence (the main function).

#### CONCLUSION

This application note presents how to control (display and setup) an electronic watch, based on Microchip's I<sup>2</sup>C RTCC, MCP79410. The project is performed on a PIC18 Explorer demo board, using the on-board resources: LCD (accessed through the SPI bus) and push buttons. The code (drivers and main function) is written in C, using the C18 compiler. The preferred microcontroller is the PIC18F87J11.

### **AN1355**

#### APPENDIX A: REVISION HISTORY

#### **Revision A (October 2010)**

Initial release of this document.

#### Revision B (June 2016)

Updated overall content for improved clarity; Updated bit and register names to match new data sheet format; Minor typographical corrections.

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