

APPLICATION NOTE

User Guide for ATA5830N 2-way 3-channel Demo

ATAN0007

Features

- Complete bi-directional RF system reference design based on the Atmel ATA5830N transceiver that uses a multi-channel protocol for robust operation
- Included in the kit are:
 - Handheld key fob reference design using PCB loop trace antenna
 - Vehicle side reference design using monopole whip antenna
 - Interface board for STK600 connectivity (STK600 not included)

Reference Documents

- ATA5830N.pdf
- Sigma_STK600EEPROM_Setting_RXTX_demo.xls
- testEEPROM_Setting_RXTX_default.xls

Overview

The Atmel[®] ATA5830N is highly integrated UHF ASK/FSK transceiver with low power consumption available in a small 5x5mm² QFN32 package with 0.5mm pitch. It is developed as a fully integrated low IF double quadrature receiver with an embedded AVR[®] microcontroller including the transmit functionality with a closed loop fractional-N modulator with Gauss-shaping and pre-emphasis for high data rates.

The Atmel ATA5830N can be setup for the following frequency bands:

- 310MHZ to 318MHz
- 418MHZ to 477MHz
- 836MHz to 928MHz

The transceiver combines the functionality of Remote Keyless Entry (RKE) and Tire Pressure Monitoring (TPM) applications in one chip under the control of an embedded AVR microcontroller. The flexibility of this device allows the programming of a wide range of RKE applications, like Passive Entry Go (PEG) and Remote Start (RS) together with the TPM applications.

The Atmel ATAK51002 evaluation kit provides a complete reference design for a bi-directional RF system based upon the Atmel ATA5830N. It provides standalone operation of two Atmel ATA5830N transceivers, one hand-held key fob and one connected to the Vehicle Host Controller. Unencrypted data is exchanged between the two transceivers and is output via an RS232 connection to a PC. The raw data can be viewed with a hyper-terminal application. The kit setup and configuration are described in the following sections. Further information is available in the reference documentation.



1. Getting Started

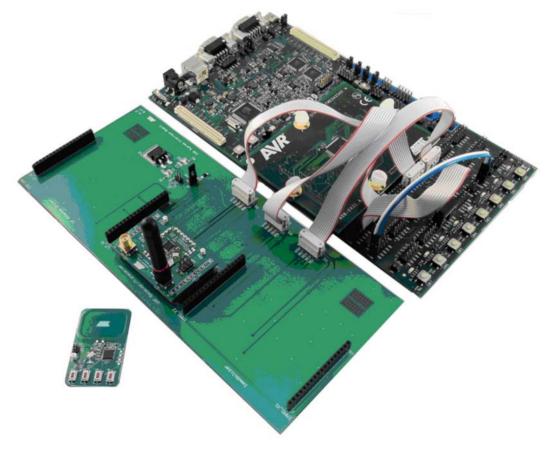
1.1 Kit Contents

This kit contains the following items:

- CAR system interface board
- Atmel ATA5830N transceiver board
- Atmel ATA5830N handheld key fob
- Monopole whip antenna
- RS232 serial cable
- Digitus USB to serial interface converter
- 120/240AC to 12VDC wall transformer
- (3) 10-wire cables for I/O port connections between STK600 and system interface board
- Atmel CD-ROM with datasheets, reference designs, and software

Note: A Atmel STK600 is required, but not included in this kit. Please contact www.atmel.com or you local Atmel Sales office for more info on obtaining one.

Figure 1-1. Atmel ATAK51002 Application Kit





1.1.1 Atmel STK600

The Atmel[®] STK600 along with the Atmel ATmega2560 microcontroller expansion board functions as the Vehicle Host Controller for the Atmel ATAK51002 application evaluation kit.

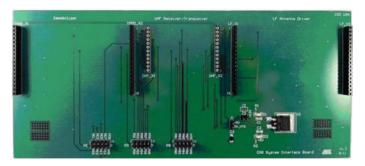
Figure 1-2. Atmel STK600 Host Controller Module



1.1.2 CARS Interface Board

The CARS (Car Access Reference System) Interface Board is the gateway between the Atmel STK600 Vehicle Host Controller and the Atmel ATA5830N Transceiver Board. Additional interface headers are included for future kit expansion to include immobilizer and passive entry functionality.

Figure 1-3. CARS Interface Board



1.1.3 Atmel ATA5830N Transceiver Board

The Atmel[®] ATA5830N Transceiver Board provides the RF link between the Atmel ATA5830N hand-held key fob and the Atmel STK600 Vehicle Host Controller.

Figure 1-4. Atmel ATA5830N Transceiver Board



1.1.4 Atmel ATA5830N Key Fob

The Atmel ATA5830N key fob is a hand-held transceiver used to communicate with the Atmel STK600 Vehicle Host Controller. The key fob contains four buttons, each capable of transmitting unique data over the RF link to the Host Controller.

Figure 1-5. Atmel ATA5830N Transceiver Key Fob





1.2 Connecting the Hardware

Prepare the Atmel[®] STK600 with the Atmel ATmega2560 device board as described in the Atmel STK600 User Guide. Using a 2-wire cable supplied with the Atmel STK600, connect RS232 SPARE pins RXD and TXD to PORTH pins PH0 and PH1 making sure RXD connects to PH0 and TXD connects to PH1. Using the two 10-wire cables supplied with the Atmel STK600, connect PORTA to LEDS. Using the three 10-wire ribbon cables supplied with the CARS evaluation kit, make connections from the Atmel STK600 to the System Interface Boards; PORTB to PB, PORTD to PD, and PORTE to PE.

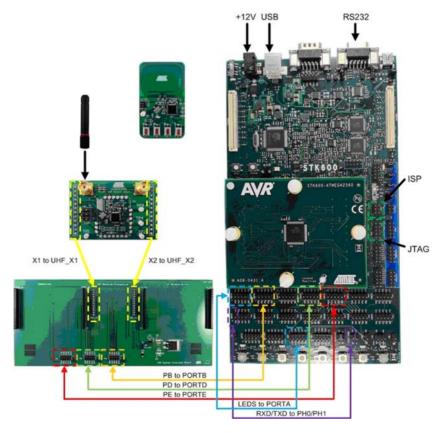
Note: Be sure to properly match header alignment to pin 1 on both ends of the cable when making these connections.

Mount the Atmel ATA5830N Transceiver Application Board to the System Interface Board taking care to align the X1 and X2 pin headers on the Transceiver Application Board to the

UHF_X1 and UHF_X2 pin sockets on the System Interface Board. Connect monopole RF whip antenna to the Transceiver Application Board and ensure that a jumper is installed onto J1.

Complete the set-up by connecting supplemental 12VDC power from the wall transformer to the mating receptacle on the Atmel STK600 and connect the USB and RS232 ports to the PC with the supplied cables. Also install a CR2032 Li-ion coin cell battery (not included with the kit due to governmental shipping regulations) into the hand-held key fob. Please ensure that the "+" side of the battery is correctly aligned with the "+" on the metal battery clip on the key fob.

Figure 1-6. Atmel ATAK51002 Hardware Interconnection



Note: Use the USB to Serial converter dongle included with the kit if your PC does not have an RS232 port.



1.3 **Device Programming**

1.3.1 **Atmel ATmega2560 Host Controller**

Since the Atmel® STK600 hardware is not included with the Atmel ATAK51002 kit, the Atmel ATmega2560 Host Controller must be flashed with the Atmel ATA5830N application firmware to operate. In-System Programming of the Atmel ATmega2560 can be done using the AVR® internal SPI (Serial Peripheral Interface) to download code into the flash and EEPROM memory. ISP programming requires only VCC, GND, RESET and 3 signal lines for programming. No high voltage signals are required. The ISP programmer can program both the internal flash and EEPROM, fuses, lock bits and calibration bytes. The ISP frequency (SCK) must be less than 1/4 of the target clock. The ISP frequency is set by the Atmel STK600 programming dialog in AVR Studio. Refer to the Atmel STK600 User Guide for additional information.

To program the Atmel ATmega2560 on the device card installed in the Atmel STK600, connect a 6-wire cable between the two 6-pins ISP headers on the Atmel STK600. See Figure 1-7 and Figure 1-8 below. Ensure that the VTARGET jumper is mounted, and that the voltage is the within the operating range for the target device.

Figure 1-7. Atmel STK600 ISP Headers

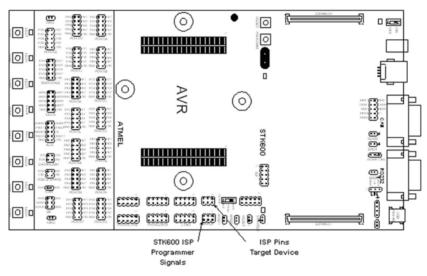


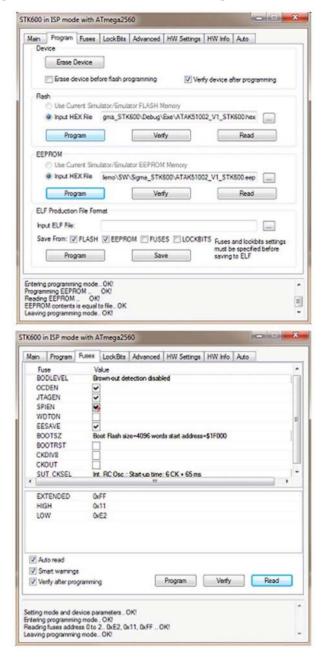
Figure 1-8. ISP 6-Wire Ribbon Cable Connection





Using AVR Studio[®]4, program the Atmel[®] ATmega2560 on the Atmel STK600 by selecting Tools/AVR Programming to bring up the ISP menus. Select and specify the Tool, Device, Interface, and Target Voltage as shown below and browse to locate files titled "ATAK51002_V1_STK600.hex" and "ATAK51002_V1_STK600.eep". The files can be found in the CD-ROM supplied with the CARS kit. Be sure to set the target voltage for 5.0V when programming the Atmel ATmega2560. Refer to Figure 1-9 for a screen shot of the properly completed ISP programming menu along with a view of proper fuse settings.

Figure 1-9. ISP Programming and Fuse Menus for the Atmel ATmega2560



1.3.2 Atmel ATA5830N Transceiver Board

Standalone programming of the Atmel[®] ATA5830N Transceiver Board is not required. The Atmel ATA5830N Transceiver Board is automatically configured whenever power is first applied to the Vehicle Host Controller.

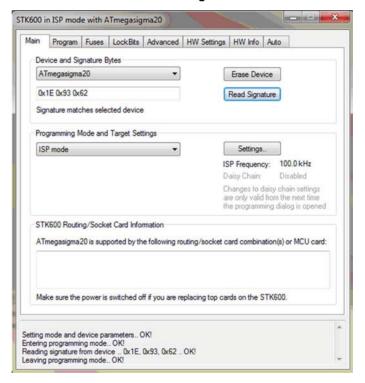
1.3.3 Atmel ATA5830N Key Fob

AVR Studio[®]4 must be updated with the Atmel ATA5830N hardware profile in order to program the Atmel ATA5830N handheld key fob. Run the "ATA5830include2AVRstudio.exe" executable file included on the CD-ROM with the Atmel ATAK510020 kit. Once the installation has completed, start AVR Studio4, install a CR2032 battery into the key fob (not included with the kit) and connect the included 6-wire ISP cable between the Atmel STK600 ISP programming header and the ISP header on the Atmel ATA5830N key fob. Connect to the key fob through the AVR Studio4 using the Atmel STK600 and configure the device from the "Main" menu tab for programming with the Device set to "ATmegasigma20", Programming Mode set to "ISP Mode" and the ISP frequency to 125kHz (the device may not program at higher frequencies). Figure 1-10 is a screen capture of the correct device setting.

Note:

In order to read the device Signature Byte, read/program the fuse settings or program the flash/EEPROM, the Atmel ATA5830N must be operating in the Idle Mode (default state is Sleep Mode). To wake the device up from Sleep, PRESS and HOLD any key fob button for the duration of the read, write or programming operations.

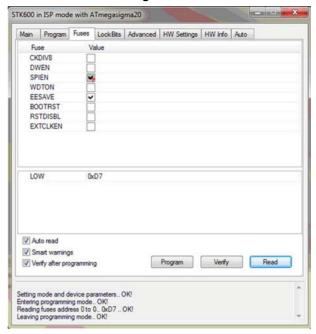
Figure 1-10. Atmel ATA5830N AVR Studio4 Main Menu Configuration



Next, program the Atmel ATA5830N fuses settings using the "Fuse" menu tab. Ensure that the SPIEN and EESAVE fuses are set with all others unchecked, see Figure 1-11 on page 10.

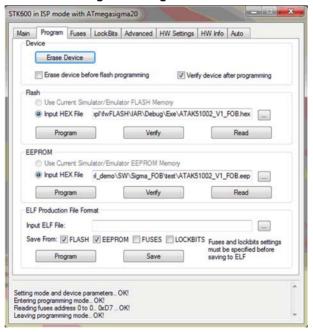


Figure 1-11. Atmel ATA5830N AVR Studio4 Fuse Configuration



Finally, program the flash with the file "ATAK51002_V1_FOB.hex" and EEPROM with "ATAK51002_V1_FOB.eep".

Figure 1-12. Atmel ATA5830N AVR Studio4 Program Configuration



1.4 Hyper-terminal Application

Download and install a Hyper-terminal application for communication between the PC and the Atmel STK600 Vehicle Host Controller using the RS232 interface. Any Hyper-terminal application like HyperTerminal, HTerm or RealTerm are suitable for use with the Atmel ATAK51002 evaluation kit.



2. Running the Demo Application

With the application boards connected, the hardware programmed and the Atmel® STK600 powered and connected to the PC via the USB and RS232 ports, it is now time to run the demo. Begin by running the Hyper-terminal application on the PC and configure it as follows:

The Hyper-terminal application must be configured as follows:

Port: will vary depending on your PC configuration

Baud: 38.4kbaudData Bits: 8Stop Bits: 1Parity: None

HW Handshake: None

Newline at: CR

Communication between the key fob and the Vehicle Host Controller utilizes a bi-directional protocol where a message is transmitted by the key fob when a button is pressed. The Host Controller then responds to the transmission from the key fob in the form of an ACK (acknowledge). The key fob application is configured as a Flash application for the Atmel ATA5830N using the internal ROM firmware and controls the four key switches and the LED located on the key fob. The Vehicle Host Controller application uses the Atmel STK600 with the on-board Atmel ATmega2560 expansion board to control the operation of the Atmel ATA5830N via the SPI commands as described in the Atmel ATA5830N datasheet.

A button press on the key fob transmits 9 bytes of data to the Host Controller. This data along with the incoming received data channel number, RSSI level and button number are output via the RS232 link to the PC. The data can then be viewed using the Hyper-terminal application.

HTerm 0.8.1beta - [hterm.cfg] File Options View Help Disconnect Port COM4 ▼ R Baud 38400 ▼ Data 8 ▼ Stop 1 ▼ Parity None ▼ ☐CTS Flow control Show newline 0 Reset Count 0 0 Reset Newline at CR 0 Autoscroll Show errors Newline after ... ms receive pause (0=off 0 1 5 10 15 20 25 30 35 40 45 50 55 60 65 70 75 80 85 Channel-1 RSSI-115 Button-1 MSG Count-1 Data-0x51,0x4E,0x87,0xA9,0x0,0x1,0x1,0xFF,0xAD_w Channel-1 RSSI-128 Button-2 MSG Count-1 Data-0x51,0x4E,0x87,0xA9,0x0,0x1,0x2,0xFF,0x2C_w Channel-1 RSSI-31 Button-3 MSG Count-1 Data-0x51,0x4E,0x87,0xA9,0x0,0x1,0x4,0xFF,0xEC_w Channel-1 RSSI-31 Button-4 MSG Count-1 Data-0x51,0x4E,0x87,0xA9,0x0,0x1,0x4,0xFF,0xEC_w Selection (-) Input control Input options Type ASC ▼ ASend mitted data 15 20 25 30 35 40 45

History -/0/10

Figure 2-1. Hyper-terminal Key Fob Data Output



Connect to COM4 (b:38400 d:8 s:1 p:None)

Additionally, the button number and incoming received data channel can be viewed on the Atmel[®] STK600 output LEDs. The button number is read right to left on LEDs 0-3 where button #1 is LED0. The incoming channel number is read from right to left as well on LEDs 4-7 where channel #1 is LED4. With each incoming data transmission from the key fob, the LEDs will be updated. The LEDs will remain illuminated for approximately 2 seconds before returning to the default "off" state.

Figure 2-2. Atmel STK600 Status LEDs



3. Atmel ATA5830N Data Telegram Overview

3.1 Transmission Protocol

This demo uses a bi-directional communication protocol with a message part and an acknowledge part (ACK). Figure 3-1 shows the data transmission using three different RF channels indicated by three different colors. In the following sections, scenarios with and without acknowledge are described, and the data protocol details are explained.

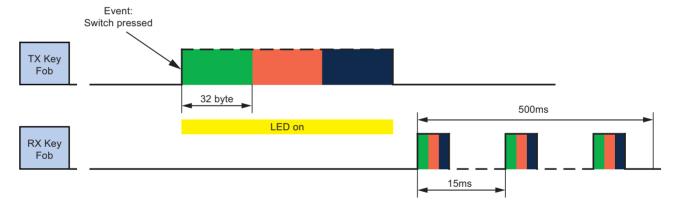
Figure 3-1. Data Transmission with Three Different Channels



3.1.1 Transmission without ACK Message

The first scenario considers that no base station is in the receiving range of the key fob. The data transmission shown in Figure 3-2 starts with the transmission of a 32 byte data messages on the three RF channels. After this transmission the key fob switches into the Polling Mode to be able to receive an ACK message. In Polling Mode the key fob is switched between the RX Mode and the IDLE Mode or OFF Mode used for power saving. When a time period of 500ms expires the Polling Mode will be stopped and the key fob is set into the OFF Mode. During the data transmission the LED of the key fob is switched on.

Figure 3-2. Data Transmission without Base Station Reply





3.1.2 Transmission with ACK Message

In this scenario the base station is in the receiving range of the key fob with a data transmission shown in Figure 3-3. The key fob is sending the data telegrams on the three channels, as described before, while the base station is in Polling Mode. The base station is receiving the first data telegram while the key fob is switched into the Polling Mode after the data transmission on all channels. The base station is analyzing the received data payload and in case that the message is correct an ACK message is send out on the RF channel which was used for the message reception. It is important that the key fob is in Polling Mode when the base station starts to send out the ACK message. This is achieved inside the base station by adapting the delay for sending the ACK message according to the channel. After receiving the ACK message the data is verified and in case that the ACK was correct, the LED of the key fob is switched on for another 500ms to indicate a successful communication. Now the key fob will be set into OFF Mode and the base station is set into Polling Mode again. If the data from the ACK message could not be verified the key fob is immediately switched into the OFF Mode.

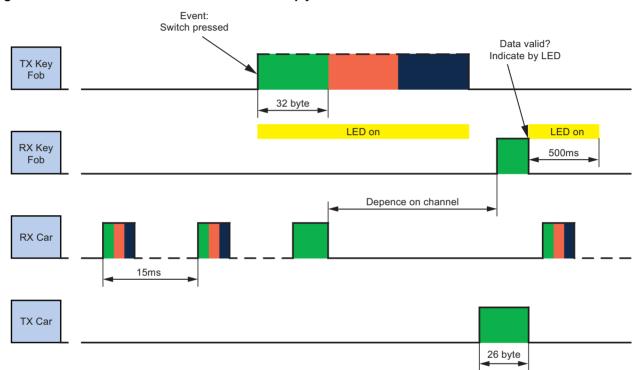


Figure 3-3. Data Transmission with Base Station Reply

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3.2 Data Telegram

This section describes the data telegram of the message part which is sent out by the key fob. The data telegram consists of 32 bytes as follows:

Preamble	Start Bit	Pattern ID	Telegram Number	Data	CRC
[183 bit]	[1 bit]	[32 bit]	[16 bit]	[8 bit]	[16 bit]

The data direction of the bytes is LSB first for every byte.

3.2.1 Data Synchronization

The data synchronization is achieved during the transmission of the preamble and is followed by a start bit.

3.2.1.1 Preamble Data

The preamble data is a stream of identical data bits that is used to synchronize the receiver with the transmitted data stream. To reduce the power consumption the receiver is switched on for short time periods to check for a data stream and is switched in Sleep or Power-down Mode when no data is available (Polling Mode). The time periods for the activation must ensure that the data reception is possible at all times which is achieved when the preamble is covering two active phases. The following preamble is used for this demo:

Preamble
bit [1820] = 00000000

3.2.1.2 Start Bit

The start bit indicates the end of the preamble and the end of the synchronization period. In addition it indicates the start of the payload data. To ensure that the start bit is detectable by the receiver it must be a bit with the inverted polarity of the preamble data. Thus the demo will use the following start bit:

Start Bit
bit [0] = 1

3.2.2 Payload Data

The payload data is following the synchronization period of the telegram. This part includes a pattern ID, a telegram number, additional data and a CRC checksum.

3.2.2.1 Pattern ID

To avoid the reception of invalid and unwanted data the ID scan function is used in the demo. The definition of the IDs is part of the EEPROM configuration data and the demo setup uses the following ID:

3.2.2.2 Telegram Number

The 16-bit telegram number will be incremented with every transmitted telegram packet and is defined as follows:

Telegram Number	
bit [150] = 1	

In this demo the number will be 1 for every key event.



3.2.2.3 Data (Key Information)

The data part is one byte long and defines the number of the pressed key as follows:

Data (Key Information)
bit [70] = 0x01 for switch 1
0x02 for switch 2
0x04 for switch 3
0x08 for switch 4

3.2.2.4 CRC

The CRC checksum is used for the verification of the correct transmission of the telegram. The receiver can check the data payload with the polynomial $x^8+x^2+x^1+1$. For the generation of the CRC a hardware block inside the ATA5830 is used. The payload data is copied to the data input register of the CRC block and returns a two byte checksum. This hardware block performs only 8 bit CRC calculations so that the high byte of the CRC checksum is always 0xFF. The CRC part of the payload is defined as follows:

1	CRC
	bit [150] = 0xFF, <crc crcdro="" from="" register=""></crc>

The used CRC polynomial is x^8+x^2+x^1+1

3.3 ACK Telegram

The acknowledge telegram confirms that a correct message was received by the base station and is sent out by the base station.

The ACK telegram includes 26 byte with the following format:

Preamble		Start Bit	Data	CRC	
	[183 bit]	[1 bit]	[8 bit]	[16 bit]	

The data direction of the ACK message is LSB first for every byte.

3.3.1 Data Synchronization

The data synchronization is achieved during the transmission of the preamble followed by a start bit as described in Section 3.2 "Data Telegram" on page 15 for the data telegram.



3.3.2 Payload Data

The payload data is following the synchronization part of the telegram. This part includes a data byte and a CRC checksum.

3.3.2.1 Data (Key and Channel Information)

The data is used to indicate to the key fob, that the received message was correct and includes the key number of the pressed key and the RF channel number, which was used for the reception in the base station. The MSB of the data byte is used as an ACK bit. The data byte format is as follows:

Data (ACK, Key and Channel Information) data bits[3...0] = 0x1 for switch 1 0x2 for switch 2 0x4 for switch 3 0x8 for switch 4 data bits[5...4] = 0x1 for channel 1 0x2 for channel 2 0x3 for channel 3 data bit[7] = 0x1 for ACK

3.3.2.2 CRC

The CRC checksum is used for the verification of the correct transmission of the telegram as described in Section 3.1 "Transmission Protocol" on page 13 for the data telegram.



3.4 Data Transmission Timing

To ensure that a data telegram is received and acknowledged the timing shown in Figure 3-4 has to be kept. The first valid data telegram which is received will be acknowledged on the same channel with a pre-defined delay according to the transmission channel sequence (see Figure 3-2 on page 13). The key fob is sending the data telegram on three different channels in a pre-defined order. The base station is sending one ACK telegram on the channel which was received first. The key fob has to be switched immediately into Polling Mode after sending all data telegrams to receive this ACK telegram in time. At least 6 bits of the ACK preamble must be received to capture the ACK packet.

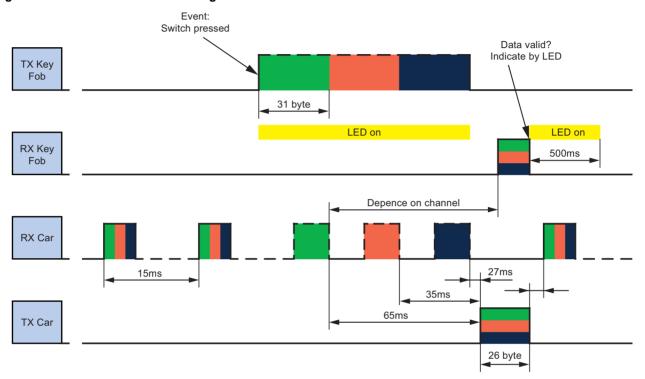


Figure 3-4. Data Transmission Timings of the Demo

Figure 1-7 on page 7 shows the delays for sending out the ACK telegram by the base station depending on the channel which was used.

4. Key Fob Application

The key fob application is a standalone Flash application inside the Atmel[®] ATA5830. The following sections describe the program flow and EEPROM settings. For more details refer to the application software source code included on the kit CD-ROM.

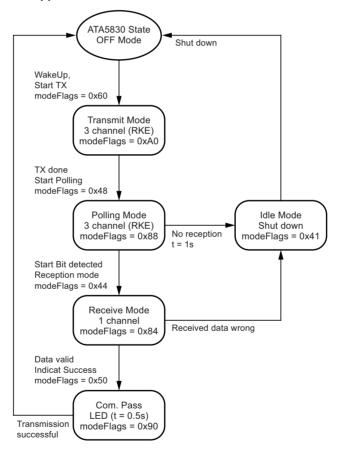
4.1 Program Flow

Figure 4-1 shows the flowchart of the standalone key fob Flash application with the state description and the mode flags to explain the control operation of the demo software.

The default state of the key fob is the OFF Mode which is a Power-down Mode. By pressing a switch the device is powered-up and changes into the TX Mode with sending out a data telegram on three channels as described in Section 3. "Atmel ATA5830N Data Telegram Overview" on page 13.

After transmission of the three data telegrams, the Polling Mode is entered and a timer is started to run for one second. When the timer expires without receiving an ACK message from the base station the key fob will shut down and change into the OFF Mode. When a start bit was detected instead the RX Mode will be entered. The key fob will now wait until an EOT (End Of Telegram) event occurs which will be automatically generated, when the ACK data stream is finished. When no valid ACK data is received the key fob will enter the state OFF Mode. If the ACK data is valid the LED is switched on to indicate the successful communication and after 500ms the key fob will change into the OFF Mode and switch the LED off.

Figure 4-1. Flow of the Key Fob Application





4.2 **EEPROM Settings**

The configuration data for the key fob application is stored in the EEPROM of the Atmel® ATA5830 device. The following settings are based on the EEPROM default setting V2.32:

- Use Buffered Mode
- PC1...4 must be inputs with enabled pull-up resistor
- Enable the pin-change interrupt for PC1...4
- Enable Sleep Mode (if used)
- Data order is LSB first
- Polling mode cycle is 15ms
- Customer settings are
 - ID at addr.
 - 0x0180: 0x51
 - 0x0181: 0x4E
 - 0x0182: 0x87
 - 0x0183: 0xA9
 - Length of pre-amble (in byte) at addr. 0x01A0: 23



5. Vehicle Host Controller Application

The Vehicle Host Controller is a standalone host application running on the Atmel[®] ATmega2560 AVR[®] microcontroller of the Atmel STK600 kit. The host controls the Atmel ATA5830N transceiver and the application using SPI commands as described in the Atmel ATA5830N datasheet.

After reset the host microcontroller configures the Atmel ATA5830N transceiver EEPROM with configuration data stored in the microcontrollers EEPROM. This is performed only for one time indicated by a flag in the microcontrollers EEPROM. If a new configuration has to be programmed into the Atmel ATA5830N EEPROM the configuration data stored in the EEPROM of the microcontroller has to be programmed again.

The host application is displaying the information received by the ACK packet like RX channel on LED4-6 and the key information on the LED0-3 of the Atmel STK600. In addition this information is send out via the RS232 interface to a terminal application, i.e. HyperTerminal, on the PC. LED7 is active when an error in the received data occurs.

In case of a data error the Host Controller will not send an ACK telegram but the RX Mode will be re-started. If the received data is correct the ACK telegram will be send on the same channel and the RX Mode is re-started.

5.1 Program flow for the Polling Mode and the RX Mode

This section describes the interaction between the Atmel ATA5830 and a Host Controller using SPI commands for the Polling Mode and the RX Mode. The flow diagram is shown in Figure 5-1 on page 22.

Before starting the Polling Mode or RX Mode, the IRQ line has to be checked for an internal Atmel ATA5830 IRQ event. When the IRQ line is low, i.e. no IRQ event occurs, the Polling Mode or RX Mode can be started. If the IRQ line is high active, the four internal status bytes has to be checked for an IRQ event. When the RXB flag (minimum RX buffer fill level) is set, the transceiver has received some data and which is stored in the RX buffer. In addition the Host Controller has to check the other interrupt sources which are provided within the four status bytes.

When the RXB flag is set, the Host Controller has to read the RX buffer fill level to read the number of received data bytes. When all received data bytes are read the host must check if the RX Mode is stopped by checking the EOT flag (End of Telegram).

If the EOT flag is set the receiving is stopped and the Atmel ATA5830 is set into the IDLE Mode and if EOT is still cleared the transceiver is still in the Receiving Mode, and the Host Controller has to wait for the next IRQ event.

5.2 Program Flow for the TX Mode

Figure 5-2 on page 23 shows the interaction between the ATA5830 and the Host Controller for the TX Mode.

Before starting the TX Mode or the fast TX Mode, the IRQ line has to be checked for an internal Atmel ATA5830 IRQ event. When the IRQ line is low, i.e. no IRQ event occurs, the Host Controller can fill the TX buffer with data to be transmitted. Once the TX Mode or fast TX Mode is started by the Host Controller, the host has to check the IRQ line which will indicate a new internal event.

When an IRQ occurs the Host Controller must read the four status bytes to identify the source of the event. When the TXB flag (minimum TX buffer fill level) is set, the Host Controller has to fill the TX buffer immediately to keep the transmission ongoing and to prevent interruptions. The EOT flag (End Of Telegram) shows, when cleared, that a transmission is ongoing (TX Mode) and the filling of the TX buffer keeps the data transmission ongoing. When the EOT flag is set, a run-out of transmit data in the TX buffer has happened and a Manchester code violation has been detected, and the Transceiver Mode is switched into the IDLE Mode.

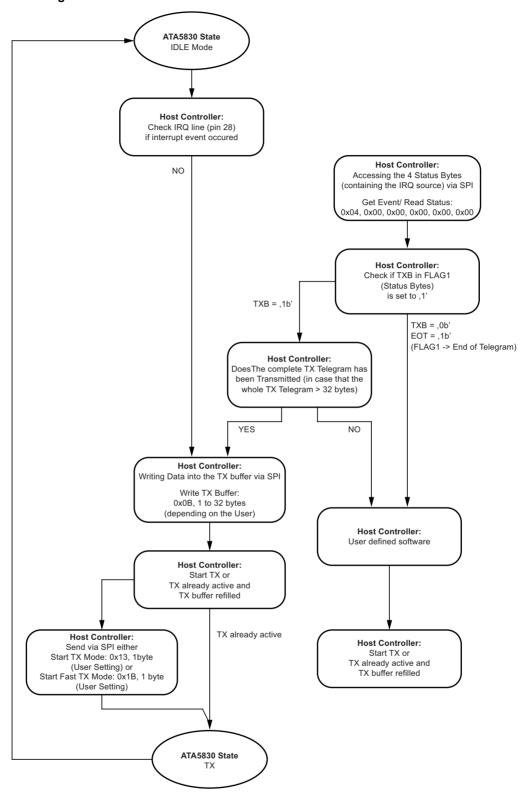


ATA5830 State IDLE Mode **Host Controller:** YES Check IRQ line (pin 28) if interrupt event occured **Host Controller:** Accessing the 4 Status Bytes (containing the IRQ source) via SPI NO Get Event/ Read Status: 0x04, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00 Host Controller: RXB = ,1b' Check if RXB in FLAG1 (Status Bytes) is set to ,1' RXB = ,0b' **Host Controller:** Accessing RX Buffer Fill Level Read Fill Level RX Buffer: 0x01, 0x00 **Host Controller:** Accessing the RX Buffer (containing the received data's) via SPI Read RX Buffer: 0x06, 0x0.1, 1 to 32 bytes (depending on the RX Buffer fill Level Host Controller: Send via SPI either **Host Controller:** Start RX Mode: 0x12, 0xXX Check if TXB (End of Telegram) FLAG 1 (Status Bytes) or Start RX Polling Mode: 0x11, 0xXX is Set to ,1b' TXB = ,0b' TXB = ,1b' -> RX active -> RX stopped **Host Controller:** User defined software **Host Controller:** Depending on the user software, ATA5830 State RX/ RX Polling Mode using other ATA5830 SPI commands

Figure 5-1. Flow Diagram of the RX Mode and the Polling Mode



Figure 5-2. Flow Diagram of the TX Mode





5.3 EEPROM settings

The configuration data for the base station application are initially stored in the EEPROM memory of the Host Controller and is programmed into the EEPROM of the Atmel ATA5830 device. The following settings are corresponding to the key fob settings for an ACK transmission:

- Use Buffered Mode
- Enable Sleep Mode (if used)
- Data order is LSB first
- Polling Mode cycle is 15ms
- Customer settings are
 - Length of pre-amble (in byte) at addr. 0x01A0: 23



6. Revision History

Please note that the following page numbers referred to in this section refer to the specific revision mentioned, not to this document.

Revision No.	History
9252B-RKE-07/15	Put document in the latest template













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