

## BMR511

### 2-phase integrated power stage up to 140 A peak

The BMR511 is a two-phase integrated power stage with a continuous output current of 80A, and a peak current of 140 A.

It comes in a compact footprint of just 0.9 cm<sup>2</sup> / 0.14 in<sup>2</sup> and is available with either LGA or solder bump termination.

The device is designed with the power stages located on bottom for the most effective down stream conducted cooling, and delivers excellent thermal results.

The BMR511 features protection mechanisms such as over-current protection and over-temperature protection. Two enable inputs are provided for each phase, and the module accepts tri-state PWM inputs.



### Key features

- High efficiency:
  - 1.8V - up to 94.5% at light load, 92.5% at full load.
  - 0.75V - up to 92% at light load, 88% at full load.
- Can be paralleled with other units
- Remote control
- Reporting temperature and current for each phase
- Excellent thermal performance
- Halogen-free

### Soldering methods

- Reflow soldering, LGA and solder bump options

### Key electrical information

Parameter	Values
Input voltage range	5 - 15 V
Output voltage range	0.5 - 1.8 V
Max output current	80 A TDC/ 140 A peak

### Mechanical

10 x 9 x 8 mm / 0.39 x 0.35 x 0.31 in

### Application areas

- Designed for AI applications
- Used by CPU, GPUs, IPUs, high-performance ASICs

## Product options

The table below describes the different product options.

	BMR511	1	04	4	/002	C	Definitions
<b>Product family</b>	BMR511						
<b>Mounting options</b>		1					0 = solder bump 1 = LGA
<b>Product variants</b>			04				04 = standard electrical variant
<b>Mechanical configuration</b>				4			4 = standard mechanical configuration
<b>Configuration code</b>					/002		/002 = 2 phases
<b>Packaging options</b>						C	C = Antistatic tape and reel packaging

For more information, please refer to [Part 2 Mechanical information](#).

If you do not find the variant you are looking for, please contact us at [Flex Power Modules](#).

## Order number examples

Part number	V <sub>in</sub>	outputs	configuration
BMR5111034/001C	5-15 V	0.5-1.8 V	Standard 2 phase module, tape and reel packaging

## Part 1: Electrical specifications

### Absolute maximum ratings

Stress in excess of our defined *absolute maximum ratings* may cause permanent damage to the converter. Absolute maximum ratings, also referred to as *non-destructive limits*, are normally tested with one parameter at a time exceeding the limits in the electrical specification.

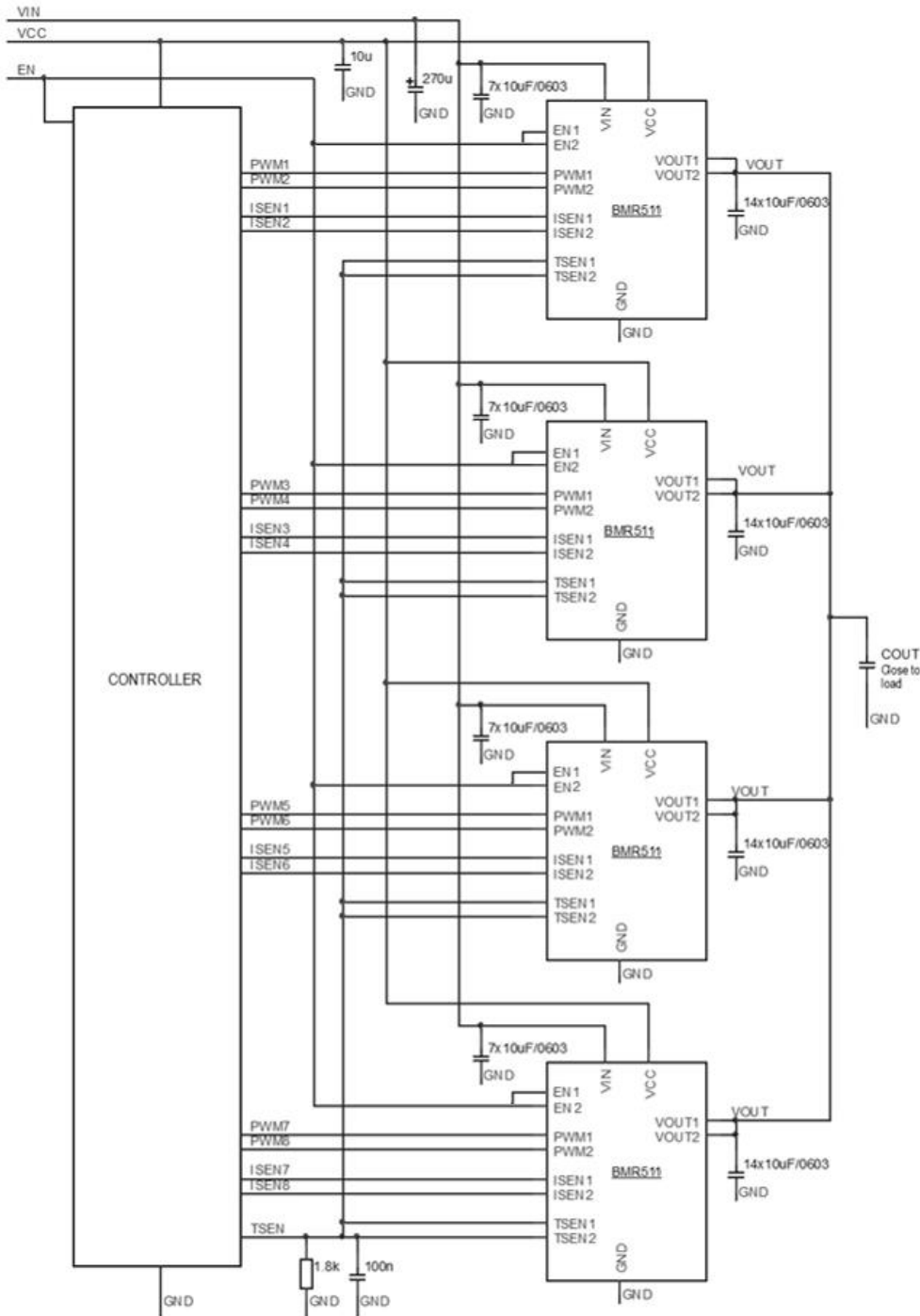
Characteristics		min	typ	max	Unit
Operating temperature (T <sub>P1</sub> )		-40		125	°C
Storage temperature		-40		125	°C
Input voltage (V <sub>in</sub> )		-0.3		20	V
Signal I/O voltage	EN, PWM,ISEN, TSEN	-0.3		VCC+0.3	V
Driver and logic supply	VCC	-0.3	3.3	4	V

### Reliability

Failure rate ( $\lambda$ ) and mean time (50%) between failures (MTBF= 1/  $\lambda$ ) are calculated based on *Telcordia SR-332 Issue 4: Method 1, Case 3, (80% of I<sub>out</sub>, T<sub>P1</sub>=40°C)*.

	Mean	90% confidence level	Unit
Steady-state failure rate ( $\lambda$ )	14	21	nfailures/h
Standard deviation ( $\sigma$ )	5.5		nfailures/h
MTBF	70.13	46.97	MHr

Typical application diagram



Typical application circuit for 8 phase rail

Notes:

1. Value of output capacitance will depend on the application and load transient requirements.
2. TSEN filter values might be adjusted if connecting together TSEN of more than 16 phases.

**Electrical specifications for BMR511 — Control and Monitoring**

$T_{P1} = -40\text{ °C}$  to  $125\text{ °C}$ ,  $V_I = 12\text{ V}$ ,  $V_{CC} = V_{EN} = 3.3\text{ V}$ , unless otherwise specified under Conditions.

Typical values given at:  $T_{P1} = +25\text{ °C}$ , unless otherwise specified under Conditions.

Characteristics		Conditions	min	typ	max	Unit
UVLO <sub>VIN</sub>	VIN Under Voltage Lock-Out	Rising threshold		2.5	3.0	V
		Hysteresis		200		mV
UVLO <sub>VCC</sub>	VCC Under Voltage Lock-Out	Rising threshold		2.75	2.95	V
		Hysteresis		200		mV
V <sub>IL,EN</sub>	EN input low threshold				0.9	V
V <sub>IH,EN</sub>	EN input high threshold		1.4			V
V <sub>IL,PWM</sub>	PWM input low threshold				0.6	V
V <sub>IH,PWM</sub>	PWM input high threshold		2.6			V
V <sub>TRL,PWM</sub>	PWM tri-state region		1.1		2.1	V
V <sub>HIZ,PWM</sub>	PWM high impedance voltage			1.6		V
I <sub>PWM</sub>	PWM sink/source current	PWM = 0 V		500		μA
		PWM = 3.3 V		-500		μA
t <sub>PWM</sub>	PWM minimum pulse width			15		ns
V <sub>O,ISEN</sub>	TSEN voltage when fault		3.0	3.3		V
G <sub>TSEN</sub>	TSEN gain			8		mV/°C
O <sub>TSEN</sub>	TSEN offset	T <sub>J</sub> = +25 °C		800		mV
T <sub>TSEN</sub>	TSEN overtemperature shutdown and fault flag			160		°C
G <sub>ISEN</sub>	ISEN gain			5		μA/A
		Accuracy	-2	0	2	%
O <sub>ISEN</sub>	ISEN offset	I <sub>O</sub> = 0 A, V <sub>ISEN</sub> = 1.2 V T <sub>J</sub> = +25 °C	-4	0	4	μA
V <sub>ISEN</sub>	ISEN voltage range		0.7		2.1	V
I <sub>LIM,H</sub>	High-side current limit	Threshold, cycle-by-cycle		120		A
		Shutdown counter		10		Times
I <sub>LIM,L</sub>	Low-side current limit	Threshold, cycle-by-cycle		-50		A
		No fault report Off time		200		ns

**Electrical specifications for BMR511 – Power Conversion (1.8 V out)**

$T_{P1} = -10\text{ °C to }95\text{ °C}$ ,  $V_I = 5\text{ to }15\text{ V}$ ,  $V_{CC} = 3.3\text{ V}$ , unless otherwise specified under Conditions.

Typical values given at:  $T_{P1} = +25\text{ °C}$ ,  $V_I = 12\text{ V}$ ,  $V_O = 1.8\text{ V}$ ,  $I_O = 80\text{ A}$ ,  $f_{sw} = 800\text{ kHz}$ , 2-phase single rail operation, otherwise specified under Conditions.

Measurements made on Reference board ROA 170 347.

External  $C_{IN} = 1 \times 270\text{ }\mu\text{F}/22\text{ m}\Omega\text{ OSCON} + 28 \times 10\text{ }\mu\text{F}\text{ ceramic}$ .

External  $C_{OUT} = 10 \times 470\text{ }\mu\text{F}/3\text{ m}\Omega\text{ POSCAP} + 356 \times 10\text{ }\mu\text{F}\text{ ceramic}$ .

Characteristics		Conditions	min	typ	max	Unit
$V_I$	Input supply	Continuous operation	5		15	V
		Peak			16	V
$V_{CC}$	Driver and logic supply		3.0	3.3	3.6	V
$V_O$	Output voltage range		0.5		1.8	V
$V_{Oac}$	Output ripple & noise	20 MHz BW		3		mVp-p
$f_{sw}$	Switching frequency	$T_{P1} = +25\text{ °C}$	500	800	1000	kHz
$C_I$	Internal input capacitance	$V_I = 0\text{ V}$		8.8		$\mu\text{F}$
$C_O$	Internal output capacitance	$V_O = 0\text{ V}$		0		$\mu\text{F}$
$L_O$	Output inductance	$I_O = 0\text{ A}$		120		nH
$I_O$	Output current, peak	2-phase operation			140	A
		1-phase operation			70	A
	Output current, continuous, Note 1	2-phase operation	0	80		A
		1-phase operation	0	40		A
$I_{IN}$	VIN input current	Standby, EN = low		10		$\mu\text{A}$
$I_{VCC}$	VCC input current	1-phase operation		38		mA
		$I_O = 40\text{ A}$				
		2-phase operation		71		mA
		$I_O = 80\text{ A}$				
		Standby, PWM1 = PWM2 = low		3		mA

Note 1: The maximum continuous output current will also be limited by the thermal conditions.

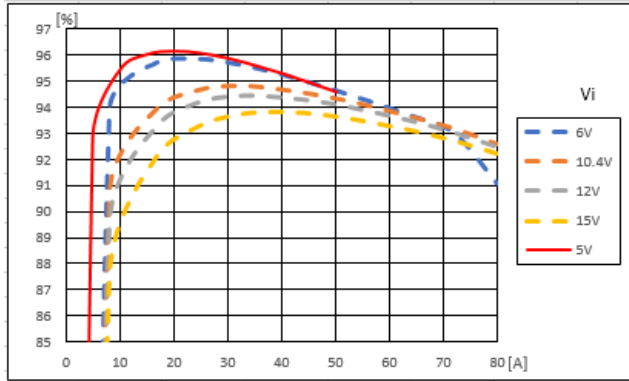
See derating graphs and section Thermal Considerations.

$V_{in} = 5\text{--}6\text{ V}$ ,  $V_O = 1.8\text{ V}$ ,  $I_O\text{ typ} = 50\text{ A}$

Electrical graphs for BMR511

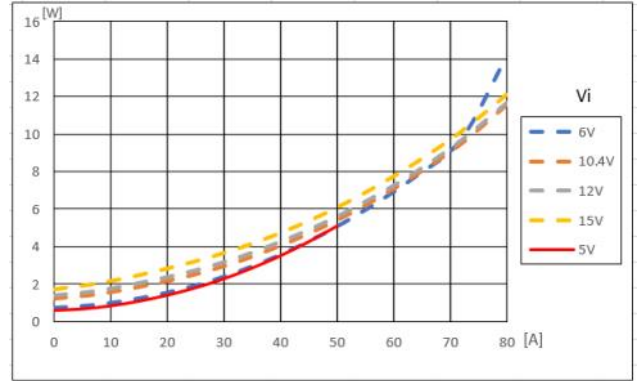
$V_{out} = 1.8 V$

Efficiency



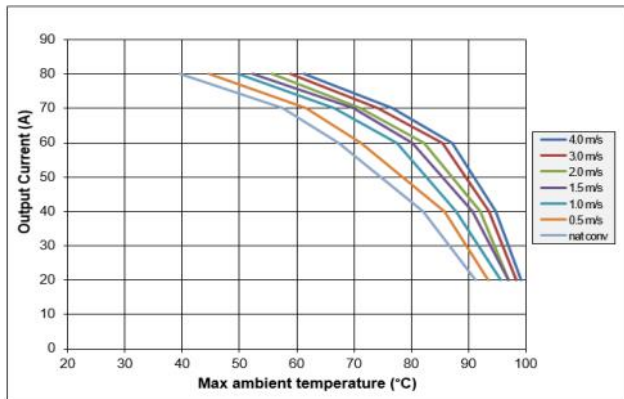
Driver losses excluded, 2 phases, fsw=800 kHz

Power dissipation



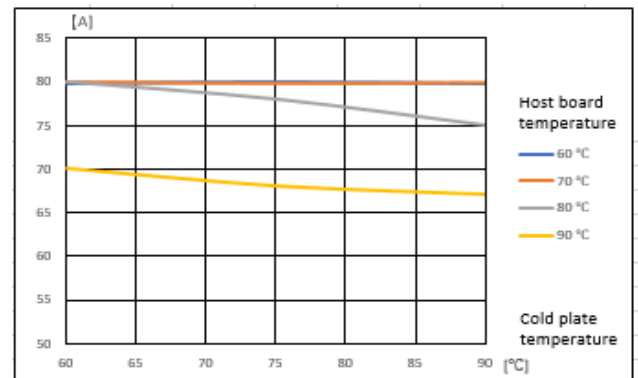
Driver losses excluded, 2 phases, fsw= 800 kHz

Output Current Derating-wind tunnel



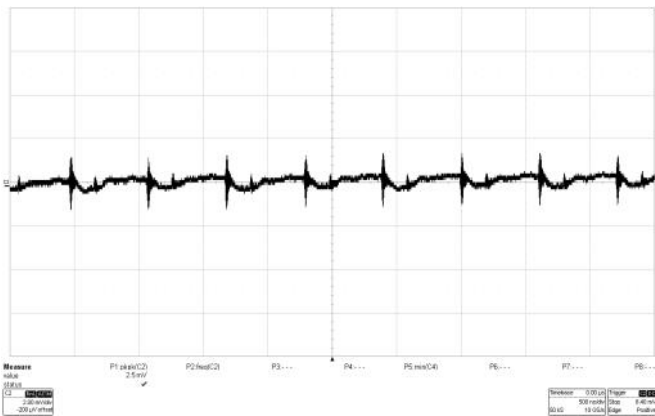
Available load current vs. ambient air temperature and air flow at  $V_i = 12V$ .

Output Current Derating-cold wall



Thermal interface gap pad 1 mm, 8 W/mK.  $V_i = 12V$ .

Output ripple



$V_i = 12 V$ ,  $I_o = 80 A$ , Scale: 2 mV/div, 0.5 μs/div, 20 MHz BW.  $C_{OUT} = 10 \times 470 \mu F / 3 m\Omega$  POSCAP + 365 x 10 μF ceramic.

## Part 1: Electrical specifications

**Electrical specifications for BMR511 – Power Conversion (0.75 V out)**

$T_{P1} = -10\text{ °C}$  to  $95\text{ °C}$ ,  $V_I = 5$  to  $15\text{ V}$ ,  $V_{CC} = 3.3\text{ V}$ , unless otherwise specified under Conditions.

Typical values given at:  $T_{P1} = +25\text{ °C}$ ,  $V_I = 12\text{ V}$ ,  $V_O = 0.75\text{ V}$ ,  $I_O = 80\text{ A}$ ,  $f_{sw} = 450\text{ kHz}$ , 2-phase single rail operation, otherwise specified under Conditions.

Measurements made on Reference board ROA 170 347.

External  $C_{IN} = 1 \times 270\text{ }\mu\text{F}/22\text{ m}\Omega$  OSCON +  $28 \times 10\text{ }\mu\text{F}$  ceramic.

External  $C_{OUT} = 10 \times 470\text{ }\mu\text{F}/3\text{ m}\Omega$  POSCAP +  $356 \times 10\text{ }\mu\text{F}$  ceramic.

Characteristics		Conditions	min	typ	max	Unit
$V_I$	Input supply	Continuous operation	5		15	V
		Peak			16	V
$V_{CC}$	Driver and logic supply		3.0	3.3	3.6	V
$V_O$	Output voltage range		0.5	0.75	1.8	V
$V_{Oac}$	Output ripple & noise	20 MHz BW		3		mVp-p
$f_{sw}$	Switching frequency	$T_{P1} = +25\text{ °C}$	400	450	1000	kHz
$C_I$	Internal input capacitance	$V_I = 0\text{ V}$		8.8		$\mu\text{F}$
$C_O$	Internal output capacitance	$V_O = 0\text{ V}$		0		$\mu\text{F}$
$L_O$	Output inductance	$I_O = 0\text{ A}$		120		nH
$I_O$	Output current, peak	2-phase operation			140	A
		1-phase operation			70	A
	Output current, continuous, Note 2	2-phase operation	0	80		A
		1-phase operation	0	40		A
$I_{IN}$	VIN input current	Standby, EN = low		10		$\mu\text{A}$
$I_{VCC}$	VCC input current	1-phase operation		38		mA
		$I_O = 40\text{ A}$				
		2-phase operation		71		mA
		$I_O = 80\text{ A}$				
	Standby, PWM1 = PWM2 = low		3		mA	

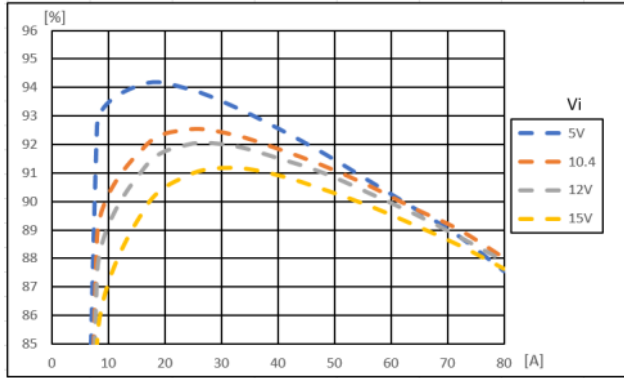
Note 2: The maximum continuous output current will also be limited by the thermal conditions.

See derating graphs and section Thermal Considerations.

### Electrical graphs for BMR511

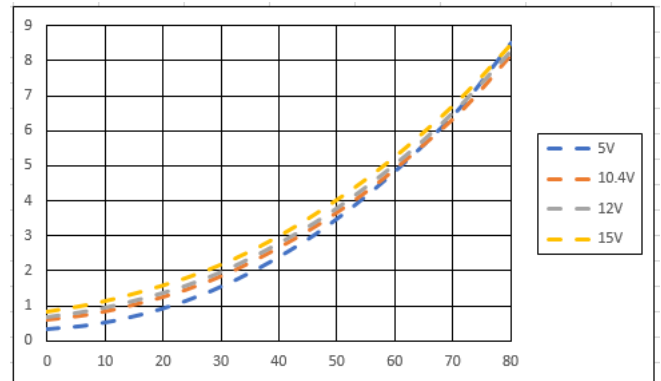
$V_{out} = 0.75 V$

#### Efficiency



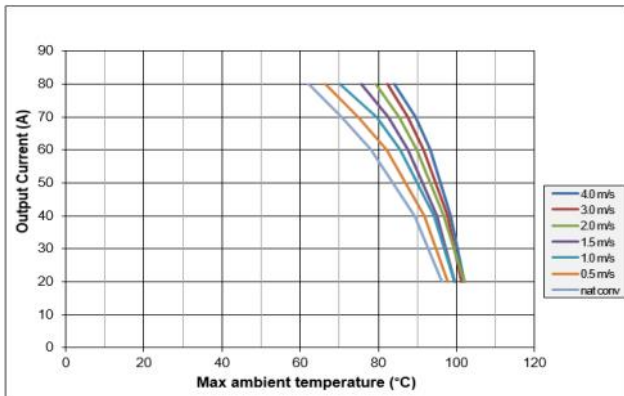
Driver losses excluded, 2 phases, fsw=450 kHz

#### Power dissipation



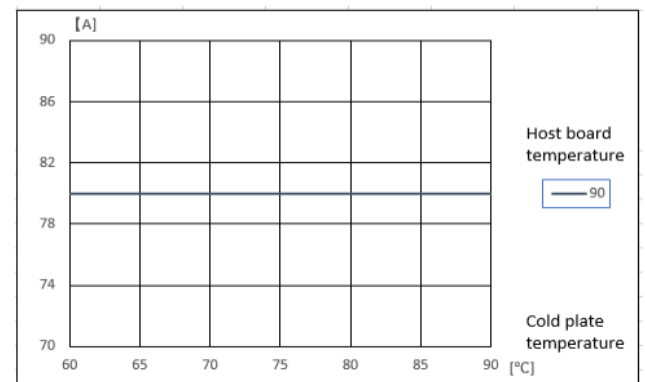
Driver losses excluded, 2 phases, fsw= 450 kHz

#### Output Current Derating-wind tunnel



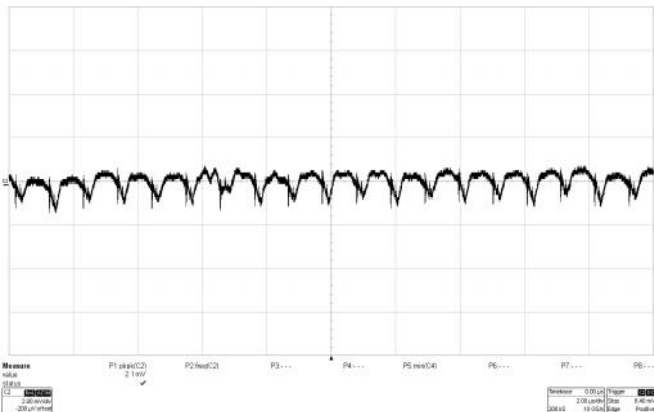
Available load current vs. ambient air temperature and air flow at  $V_i = 12V$ .

#### Output Current Derating-cold wall



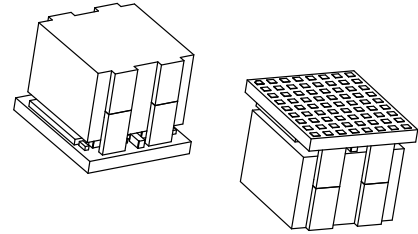
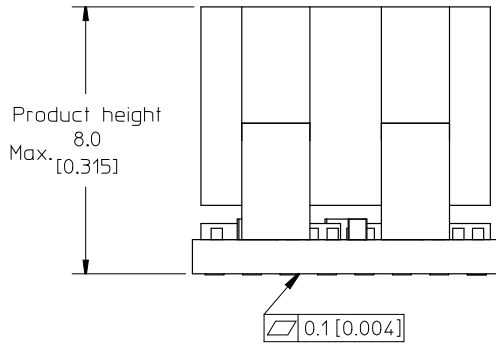
Thermal interface gap pad 1 mm, 8 W/mK.  $V_i = 12V$ .

#### Output ripple

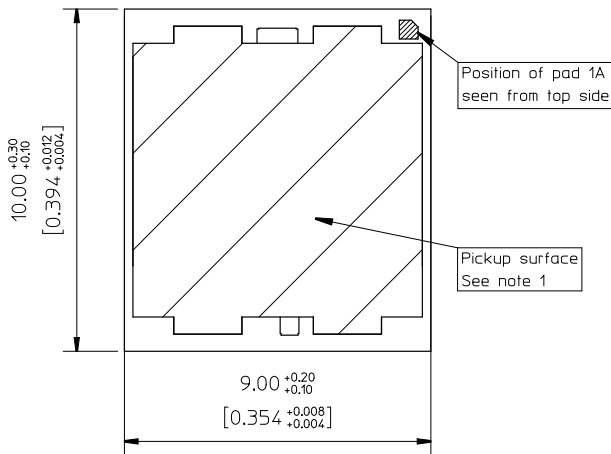


$V_i = 12 V$ ,  $I_o = 80 A$ , Scale: 2 mV/div, 2  $\mu s$ /div, 20 MHz BW.  $C_{OUT} = 10 \times 470 \mu F / 3 m\Omega$  POSCAP + 365  $\times$  10  $\mu F$  ceramic.

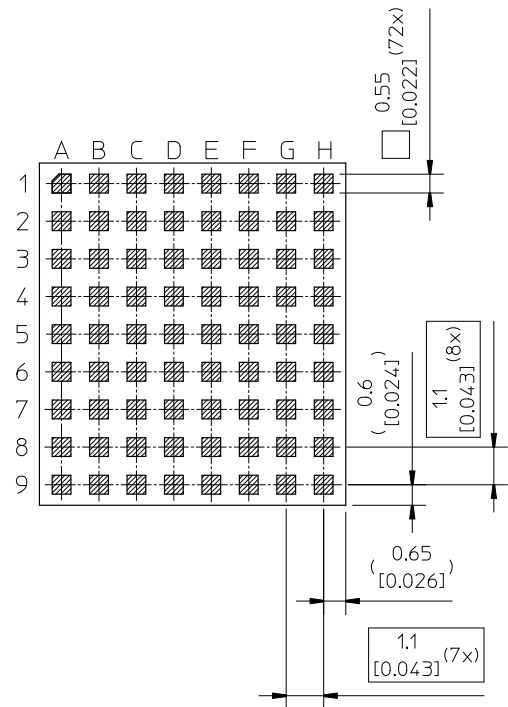
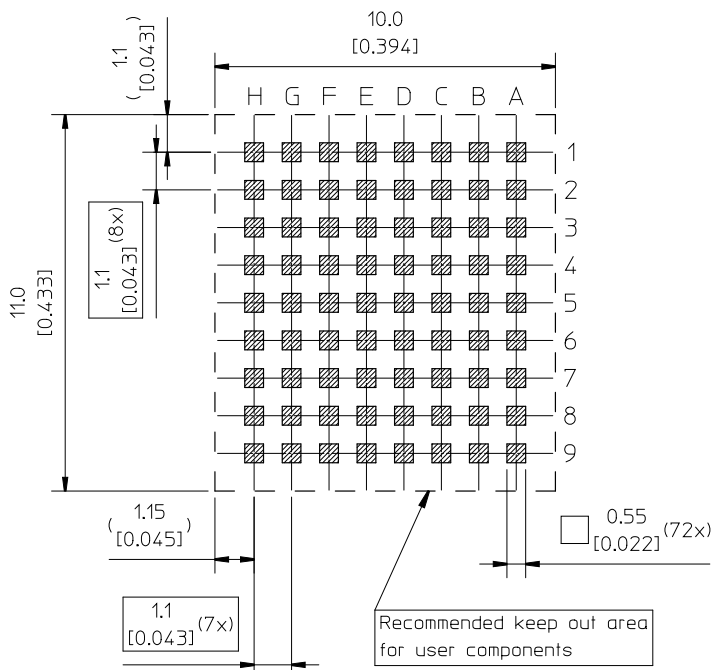
Part 2: Mechanical information  
BMR511: Surface Mount Version



TOP VIEW  
Pin position acc. to recommended footprint



RECOMMENDED FOOTPRINT - TOP VIEW



Note:

1. Max pressure on top surface: 10N

Weight: 3.05 g

All dimensions in mm [inches]

Tolerances unless specified:

x.x ±0.5 mm [0.02 inch]

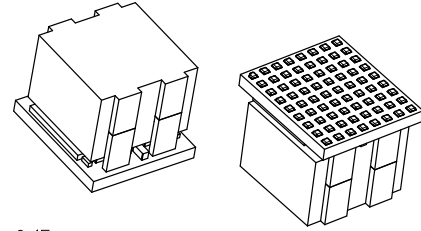
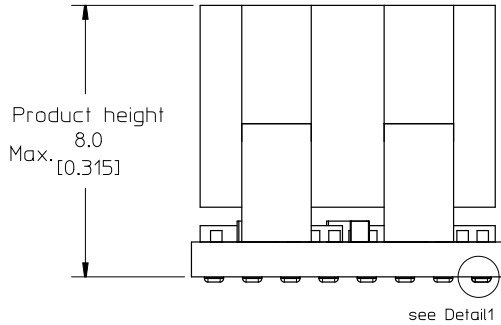
x.xx ±0.25 mm [0.01 inch]

(not applied on footprint or typical values)

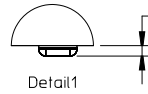


Part 2: Mechanical information

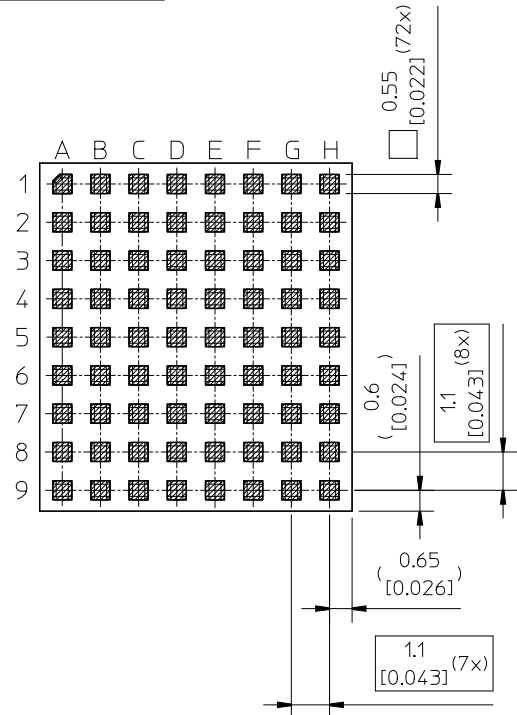
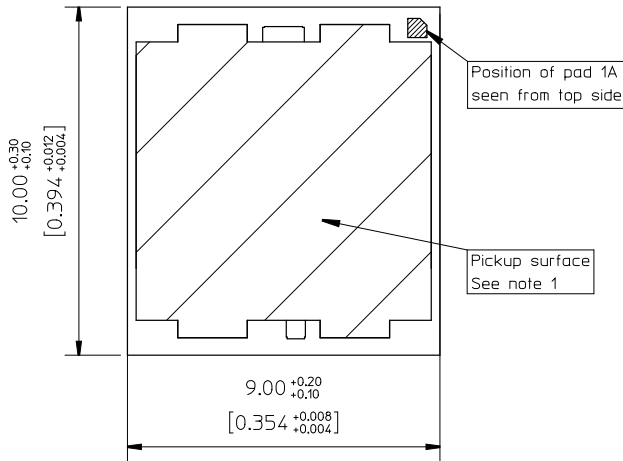
**BMR511: Surface Mount Version with solder bumps**



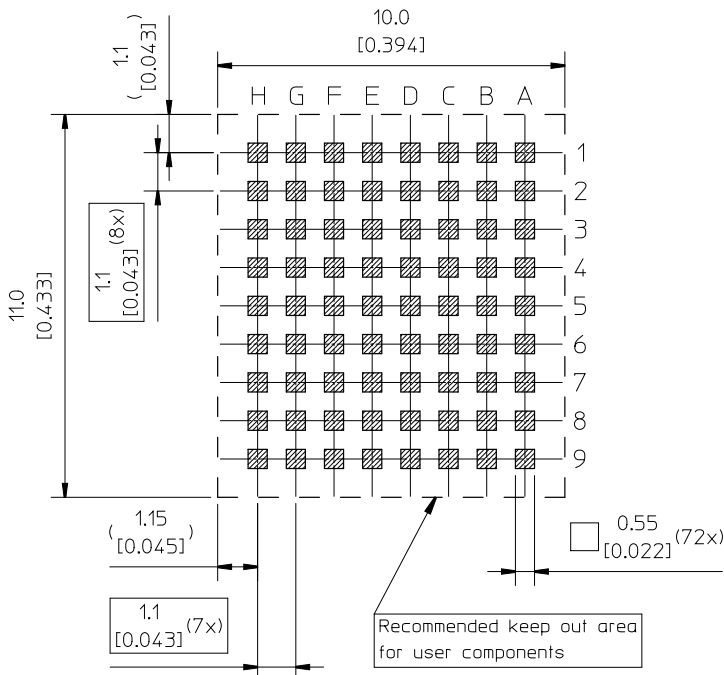
Typical 0.15  
[0.006]  
Pre-soldered bump



TOP VIEW  
Pin position acc. to recommended footprint



RECOMMENDED FOOTPRINT - TOP VIEW



Note:

1. Max pressure on top surface: 10N

Weight: 3.05 g

All dimensions in mm [inches]

Tolerances unless specified:

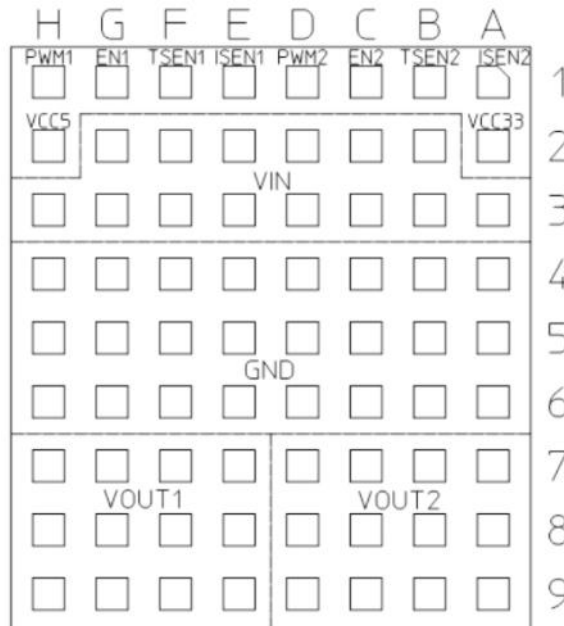
x.x  $\pm 0.5$  mm [0.02 inch]

x.xx  $\pm 0.25$  mm [0.01 inch]

(not applied on footprint or typical values)



Connections



Pin layout, top view

Pin	Designation	Type	Function
A1	ISEN2	Output	Current sense output, phase 2. Use external resistor to adjust the voltage proportional to the inductor current
A2	VCC33	input	Driver and internal circuitry supply. Connect to +3.3 V.
B1	TSEN2	Output	Temperature sense and fault reporting, phase 2.
C1	EN2	Input	Active high enable input, phase 2
D1	PWM2	Input	Pulse-width modulation input, phase 2. The PWM2 signal shall be 180° phase shifted compared to the PWM1 signal
E1	ISEN1	Output	Current sense output, phase 1. Use external resistor to adjust the voltage proportional to the inductor current
F1	TSEN1	Output	Temperature sense and fault reporting, phase 1 .
G1	EN1	Input	Active high enable input, phase 1.
H1	PWM1	Input	Pulse-width modulation input, phase 1. The PWM1 signal shall be 180° phase shifted compared to the PWM2 signal .
H2	VCC5	NC	No connection.
B2-G2, A3-H3	VIN	Power	Input voltage .
A4-H4, A5-H5, A6-H6	GND	Power	Power ground and digital ground .
A7-D7, A8- D8, A9-D9	VOUT2	Power	Output voltage, phase 2
E7-H7, E8-H8, E9-H9	VOUT1	Power	Output voltage, phase 1

## Part 3: Thermal considerations

### Thermal Consideration

#### General

The product is designed with inductor on top. Cooling is mainly achieved by conduction to the host board and convection which is dependent on the airflow across the product. Increased airflow enhances the cooling of the product.

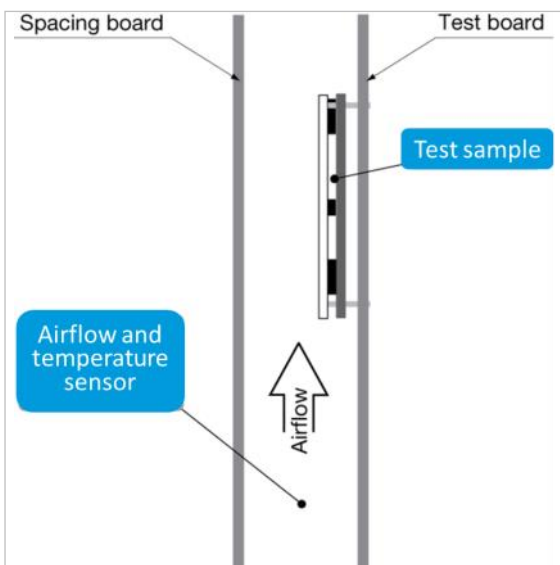
The Output Current Derating graph found in the Electrical Specification section provides the available output current versus Max. ambient temperature, and output current versus cold plate temperature and host board temperature.

#### Test Setup - Wind tunnel

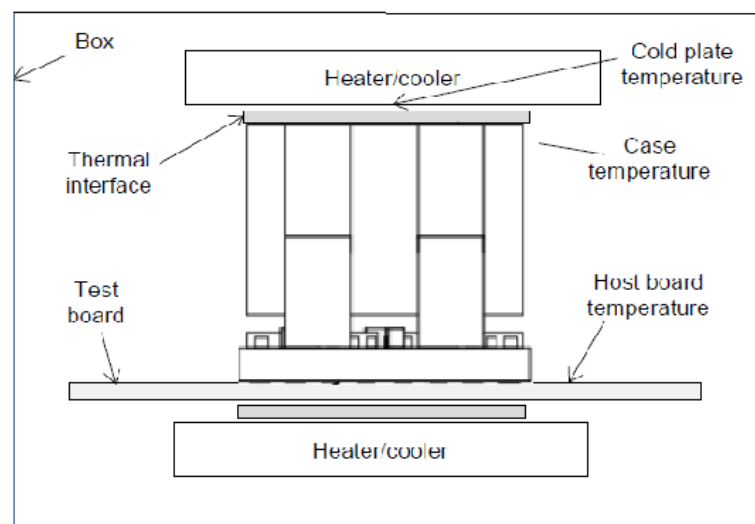
The product is tested on a 254 x 254 mm, 35  $\mu\text{m}$  (1 oz), 8 layer test board mounted vertically in a wind tunnel with a cross section of 608 x 203 mm. Distances between the tested device and the top space board are 12 mm.

#### Test Setup – Cold Plate

The product is tested in a box with two heater/coolers; one as a cold plate to control the temperature at the top of the module, another on the bottom side of the test board to control the host board temperature. The test board used is 254 x 254 mm in size with 1.6 mm thickness and 8 layers of 1 oz.



Picture: test set-up - wind tunnel



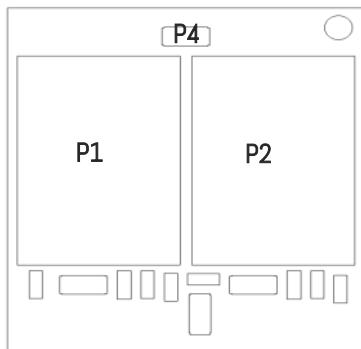
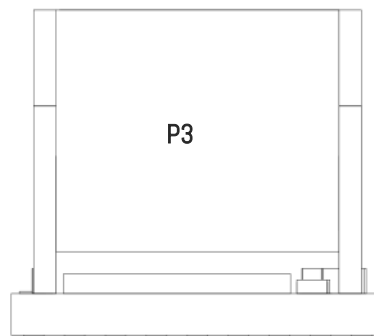
Picture: test setup — Cold plate

### Definition of Product Operating Temperature

The temperature at positions P1-P4 should not exceed the maximum temperatures in the table below. The number of measurement points may vary with different thermal design and topology. Temperature above specified maximum measured at the specified position is not allowed and may cause permanent damage.

## Part 3: Thermal considerations

Position	Description	Max temperature
P1	Power switch case phase 1 reference point	$T_{P1}=125^{\circ}\text{C}$
P2	Power switch case phase 2	$T_{P2}=125^{\circ}\text{C}$
P3	M1, Inductor core	$T_{P3}=125^{\circ}\text{C}$
P4	capacitors	$T_{P4}=105^{\circ}\text{C}$

Top view ( inductor re-  
moved)

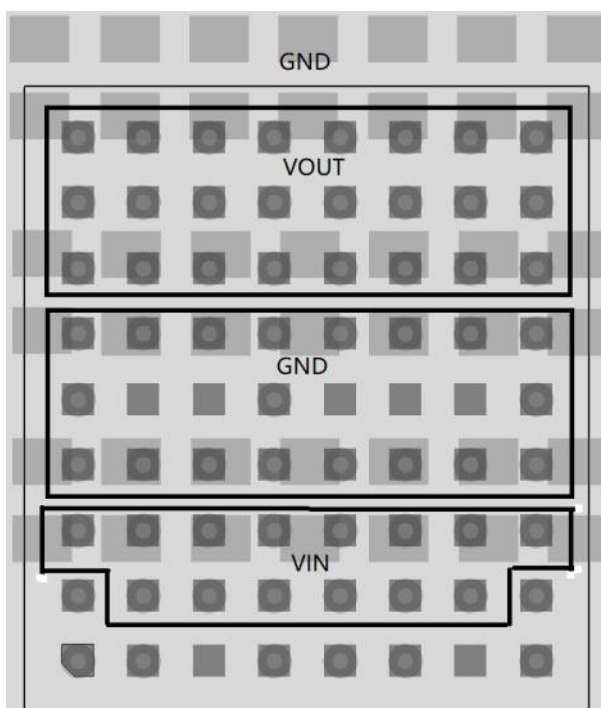
Side view

## Part 4: PCB layout considerations

### PCB Layout Consideration

1. The radiated EMI performance of the product will depend on the PCB layout and ground layer design. A ground plane shall be used, to increase the stray capacitance in the PCB and improve the high frequency EMC performance. The ground plane shall connect to the GND pins of the devices and the equipment ground or chassis.
2. For a multiphase rail including several power modules, layout should be as symmetrical as possible in order to help balance the current between devices.
3. If possible, use planes on several layers to carry VI, VO and ground. There should be a large number of vias close to the VIN, VOUT and GND pins to lower input and output impedances and improve heat spreading between the product and the host board.
4. Care should be taken in the routing of the ISEN and TSEN connections. The routing should be along a GND plane and should avoid areas of switching signals or high electric or magnetic fields, e.g. keep away from PWM signals.
5. The external input capacitors, CI\_EXT, shall be placed as close to the input pins as possible and with low impedance connections, e.g. using via stitching around capacitors' terminals. See AN323 for more details.
6. The external output capacitors, CO\_EXT, should be placed close to the output pins to handle the output current ripple, and close to the load to handle the load transients. See AN321 for more details. Low impedance connections must be used, e.g. via stitching around capacitors' terminals.

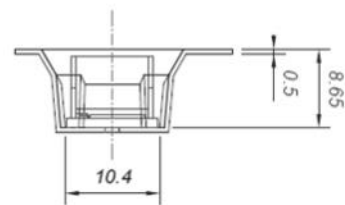
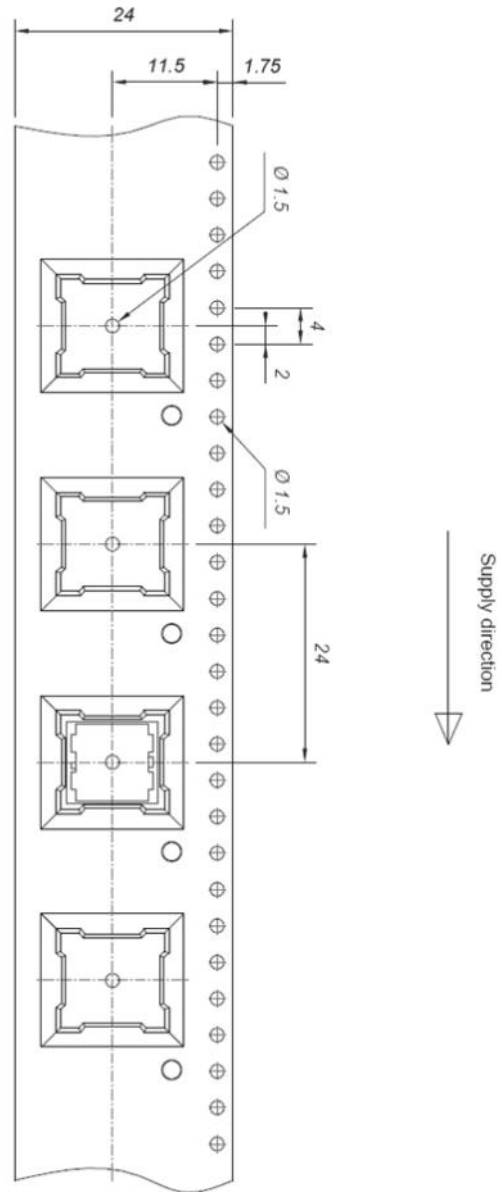
Below picture shows a layout example where the module is mounted on the top side of the PCB and 7 pcs 0603 input capacitors and 14 pcs 0603 output capacitors are placed on the bottom side of the PCB, providing a short connection to the VIN, VOUT and GND pins through vias in module pads.



Layout example: Input and output capacitance placement close to the module (top view).

Part 5: Packaging  
Packaging information

C option:	
<b>Material</b>	Antistatic polyphenylene ester (PPE)
<b>Surface resistance</b>	$10^5 < \text{ohm/square} < 10^{11}$
<b>Bakeability</b>	The tape is not bakeable
<b>Tape width, W</b>	24 mm [0.95 inch]
<b>Pocket pitch, P<sub>1</sub></b>	24 mm [0.95 inch]
<b>Pocket depth, K<sub>0</sub></b>	8.65 mm [0.34 inch]
<b>Reel diameter</b>	330 mm [13.0 inch]
<b>Reel capacity</b>	300 products /reel
<b>Reel weight</b>	1400 g/full reel



## Part 6: Revision history

### Revision table

Revision number	revision change	date	revisor
Rev. A	New document	2023/6/15	JIDDIYAN
Rev. B	Spell check	2023/6/15	KARTWAER

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