

**ABSTRACT**

This document describes the known exceptions to the functional specifications (advisories).

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**1 Functional Advisories**

Advisories that affect the device operation, function, or parametrics.

✓ The check mark indicates that the issue is present in the specified revision.

Errata Number	Rev A
<a href="#">ADC_ERR_05</a>	✓
<a href="#">COMP_ERR_05</a>	✓
<a href="#">CPU_ERR_02</a>	✓
<a href="#">CPU_ERR_03</a>	✓
<a href="#">FLASH_ERR_02</a>	✓
<a href="#">FLASH_ERR_03</a>	✓
<a href="#">I2C_ERR_04</a>	✓
<a href="#">I2C_ERR_05</a>	✓
<a href="#">I2C_ERR_06</a>	✓
<a href="#">I2C_ERR_07</a>	✓
<a href="#">I2C_ERR_08</a>	✓
<a href="#">I2C_ERR_09</a>	✓
<a href="#">I2C_ERR_10</a>	✓
<a href="#">PMCU_ERR_13</a>	✓
<a href="#">RST_ERR_01</a>	✓
<a href="#">RTC_ERR_01</a>	✓
<a href="#">SPI_ERR_04</a>	✓
<a href="#">SPI_ERR_05</a>	✓
<a href="#">SPI_ERR_06</a>	✓
<a href="#">SPI_ERR_07</a>	✓
<a href="#">SYSOSC_ERR_02</a>	✓
<a href="#">TIMER_ERR_04</a>	✓
<a href="#">TIMER_ERR_06</a>	✓

Errata Number	Rev A
<a href="#">UART_ERR_01</a>	✓
<a href="#">UART_ERR_02</a>	✓
<a href="#">UART_ERR_04</a>	✓
<a href="#">UART_ERR_05</a>	✓
<a href="#">UART_ERR_06</a>	✓
<a href="#">UART_ERR_07</a>	✓
<a href="#">UART_ERR_08</a>	✓

## 2 Preprogrammed Software Advisories

Advisories that affect factory-programmed software.

✓ The check mark indicates that the issue is present in the specified revision.

## 3 Debug Only Advisories

Advisories that affect only debug operation.

✓ The check mark indicates that the issue is present in the specified revision.

## 4 Fixed by Compiler Advisories

Advisories that are resolved by compiler workaround. Refer to each advisory for the IDE and compiler versions with a workaround.

✓ The check mark indicates that the issue is present in the specified revision.

## 5 Device Nomenclature

To designate the stages in the product development cycle, TI assigns prefixes to the part numbers of all MSP MCU devices. Each MSP MCU commercial family member has one of two prefixes: MSP or XMS. These prefixes represent evolutionary stages of product development from engineering prototypes (XMS) through fully qualified production devices (MSP).

**XMS** – Experimental device that is not necessarily representative of the final device's electrical specifications

**MSP** – Fully qualified production device

Support tool naming prefixes:

**X**: Development-support product that has not yet completed Texas Instruments internal qualification testing.

**null**: Fully-qualified development-support product.

XMS devices and X development-support tools are shipped against the following disclaimer:

"Developmental product is intended for internal evaluation purposes."

MSP devices have been characterized fully, and the quality and reliability of the device have been demonstrated fully. TI's standard warranty applies.

Predictions show that prototype devices (XMS) have a greater failure rate than the standard production devices. TI recommends that these devices not be used in any production system because their expected end-use failure rate still is undefined. Only qualified production devices are to be used.

TI device nomenclature also includes a suffix with the device family name. This suffix indicates the temperature range, package type, and distribution format.

### 5.1 Device Symbolization and Revision Identification

The package diagrams below indicate the package symbolization scheme, which is the pre-prod version. After release, RTM version will be added here. And [Table 5-1](#) defines the device revision to version ID mapping.

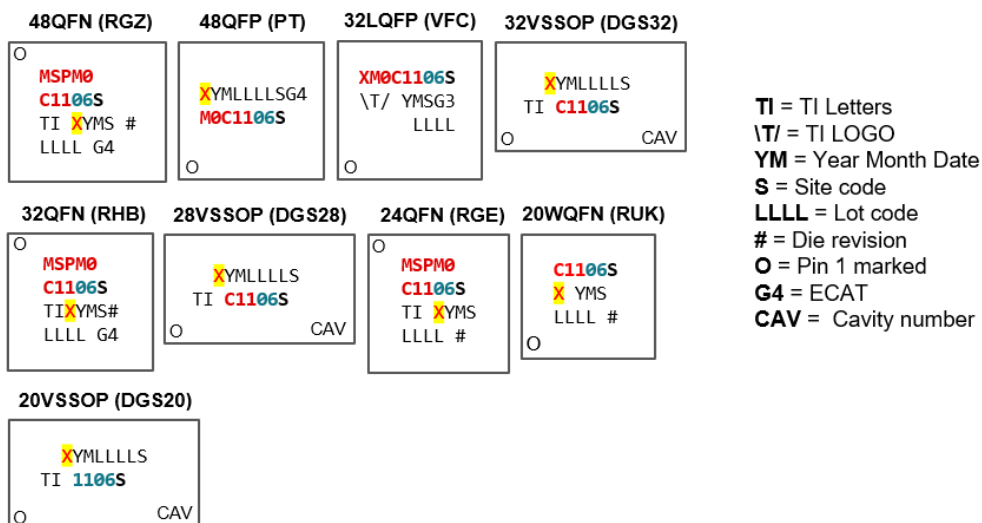


Figure 5-1. Package Symbolization

Table 5-1. Die Revisions

Revision Letter	Version (in the device factory constants memory)
B	1

The revision letter indicates the product hardware revision. Advisories in this document are marked as applicable or not applicable for a given device based on the revision letter. This letter maps to an integer stored in the memory of the device, which can be used to look up the revision using application software or a connected debug probe.

## 6 Advisory Descriptions

### ADC\_ERR\_05

#### *ADC Module*

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#### Category

Functional

#### Function

HW Event generated before enabling IP, ADC Trigger will stay in queue

#### Description

When ADC is configured in HW event trigger mode and the trigger is generated before enabling the ADC, the ADC trigger will stay in queue. Once ADC is enabled, it will trigger sampling and conversion.

#### Workaround

After configuring ADC in HW trigger mode, enable ADC first before giving external trigger.

### COMP\_ERR\_05

#### *COMP Module*

---

#### Category

Functional

#### Function

Comparator output will set the rising and falling interrupt when comparator is enabled

#### Description

Comparator will set the rising and falling when the comparator is enabled.

#### Workaround

1. Clear the CPU interrupts by using ICLR bit.  
ICLR will not work for clearing generic events. Follow below steps to clear COMP generic events (below are DriverLib functions, you can see the bits manipulation by looking in the function contents in our MSPM0 SDK)

- Before COMP is enabled, configure COMP publisher with some dummy ID.  
`DL_COMP_setPublisherChanID(COMP_0_INST, 0); // remove the actual publisher`
- `DL_COMP_enableEvent(COMP_0_INST, (DL_COMP_EVENT_OUTPUT_EDGE)); // Enable the COMP events in IMASK`
- `DL_COMP_enable(COMP_0_INST); // Enable the COMP module, this step clearing the events in RIS.`
- `DL_COMP_disableEvent(COMP_0_INST, (DL_COMP_EVENT_OUTPUT_EDGE)); // Disable the COMP events by clearing in IMASK`
- `DL_COMP_setPublisherChanID(COMP_0_INST, COMP_0_INST_PUB_CH); // configure the actual publisher`
- `DL_COMP_enableEvent(COMP_0_INST, (DL_COMP_EVENT_OUTPUT_EDGE)); // Re-enable COMP events in IMASK`

Or

Read the interrupt after the comparator is enabled, knowing that the first interrupt happened due to comparator being enabled.

### CPU\_ERR\_02

#### *CPU Module*

---

#### Category

Functional

## CPU\_ERR\_02

(continued)

### **CPU Module**

---

#### Function

Limitation of disabling prefetch feature for CPUSS

#### Description

MMR disable feature for prefetch logic won't work till there is an ongoing/ new access thrown to flash.

#### Workaround

First, disable the prefetch from MMR and run some dummy instructions (like shutdown register read or any peripheral read) which doesn't access prefetch so that prefetch can get disabled.

## CPU\_ERR\_03

### **CPU Module**

---

#### Category

Functional

#### Function

Prefetcher can cause data integrity issues when transitioning into SLEEP mode

#### Description

When transitioning into SLEEP0 the prefetcher can erroneously fetch incorrect data (all 0's). When coming out of sleep mode, if the prefetcher and cache do not get overwritten by ISR code, then the main code execution from flash can get corrupted. For example, if the ISR is in the SRAM, then the incorrect data that was prefetched from Flash does not get overwritten. When the ISR returns the corrupted data in the prefetcher can be fetched by the CPU resulting in incorrect instructions.

#### Workaround

Disable prefetcher before entering SLEEP.

## FLASH\_ERR\_02

### **FLASH Module**

---

#### Category

Functional

#### Function

Debug disable in NONMAIN can be re-enable using default password

#### Description

If debug is disabled in NONMAIN configuration, it still can be enabled using default password.

#### Workaround

1. Set the DEBUGACCESS to Debug Enabled with Password option and provide a unique password in the PWDDEBUGLOCK field. For higher security, it is recommended to have device-unique passwords that are cryptographically random. This would allow debug access with the right 128-bit password but can still allow some debug commands and access to the CFG-AP and SEC-AP.
2. Disable the physical SW Debug Port entirely by disabling SWDP\_MODE. This fully prevents any debug access or requests to the device, but may affect Failure Analysis and return flows.

---

**FLASH\_ERR\_03**    *FLASH Module*


---

**Category**

Functional

**Function**

Flash access with 2 wait states followed by invalid bootcode access will cause next flash access to also throw a violation

**Description**

Doing a Flash access followed by a access to BOOTCODE when you have 2 wait states will cause the next flash access to also cause a violation.

**Workaround**

Do not attempt to access boot-code region post-boot phase. Otherwise, there will need to be 4 clock cycles in between the bootcode violation and next correct flash access.

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**I2C\_ERR\_04**
*I2C Module*


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**Category**

Functional

**Function**

When SCL is low and SDA is high the Target i2c is not able to release the stretch.

**Description**

1: SCL line grounded and released, device indefinitely pulls SCL low.

2: Post clock stretch, timeout, and release; if there is another clock low on the line, device indefinitely pulls SCL low.

**Workaround**

If the I2C target application does not require data reception in low power mode using Async fast clock request, disabling SWUEN by default is recommended, including during reset or power cycle. In this case, bug description 1 and 2 does not occur.

If the I2C target application requires data reception in low power mode using Async fast clock request, enable SWUEN just before entering low power and clear SWUEN after low power exit. Even in this scenario, bug description 1 and 2 can occur when the I2C target is in low power, it will indefinitely stretch the SCL line if there is a continuous clock stretching or timeout caused by another device on the bus. To recover from this situation, enable the low timeout interrupt on the I2C target device, reset and re-initialize the I2C module within the low timeout ISR.

---

**I2C\_ERR\_05**
*I2C Module*


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**Category**

Functional

**Function**

I2C SDA may get stuck to zero if we toggle ACTIVE bit during ongoing transaction

**Description**

If ACTIVE bit is toggled during an ongoing transfer, its state machine will be reset. However, the SDA and SCL output which is driven by the I2C controller will not get reset. There is a situation where SDA is 0 and I2C controller has gone into IDLE state, here the I2C controller won't be able to move forward from the IDLE state or update the SDA value. I2C Target's BUSBUSY is set (toggling of the ACTIVE bit is leading to a start being

**I2C\_ERR\_05**  
(continued)

***I2C Module***

---

detected on the line) and the BUSBUSY won't be cleared as the I2C controller will not be able to drive a STOP to clear it.

**Workaround**

Do not toggle the ACTIVE bit during an ongoing transaction.

**I2C\_ERR\_06**

***I2C Module***

---

**Category**

Functional

**Function**

SMBus High timeout feature fails at I2C clock less than 24KHz onwards.

**Description**

SMBus High timeout feature is failing at I2C clock rate less than 24KHz onwards (20KHz, 10KHz). From SMBUS Spec, the upper limit on SCL high time during active transaction is 50us. Total time taken from writing of I2C START bit to SCL low is 60us, which is >50us. It will trigger the timeout event and let I2C Controller go into IDLE without completing the transaction at the start of transfer. Below is detailed explanation.

For SCL is configured as 20KHz, SCL low and high period is 30us and 20us respectively. First, I2C START bit write at the same time high timeout counter starts decrementing. Then, it takes one SCL low period (30us) from the START bit write to SDA goes low (start condition). Next, it takes another SCL low period (30us) from SDA goes low (start condition) to SCL goes low (data transfer starts) which should stop the high timeout counter at this point. As a total, it takes 60us from counter start to end. However, due to the upper limit(50us) of the high timeout counter, the timeout event will still be triggered although the I2C transaction is working fine without issue.

**Workaround**

Do not use SMBus High timeout feature when I2C clock less than 24KHz onwards.

**I2C\_ERR\_07**

***I2C Module***

---

**Category**

Functional

**Function**

Back to back controller control register writes can cause I2C to not start.

**Description**

Back to back CTR register writes can cause the next CTR.START to not properly cause the start condition.

**Workaround**

Write all the CTR bits including CTR.START in a single write or wait between the CTR writes and CTR.START write.

**I2C\_ERR\_08**

***I2C Module***

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**Category**

Functional

<b>I2C_ERR_08</b> (continued)	<b>I2C Module</b>
<b>Function</b>	FIFO Read directly after RXDONE interrupt causes erroneous data to be read.
<b>Description</b>	When the RXDONE interrupt happens the FIFO can not be updated for the latest data.
<b>Workaround</b>	Wait 2 I2C CLK cycles for the FIFO to make sure to have the latest data. I2C CLK is based on the CLKSEL register in the I2C registers.
<b>I2C_ERR_09</b>	<b>I2C Module</b>
<b>Category</b>	Functional
<b>Function</b>	Start address match status might not be updated in time for a read through the ISR if running I2C at slow speeds.
<b>Description</b>	If running at atypical I2C speeds (less than 100kHz) then the ADDRMATCH bit (address match in the TSR register) might not be set in time for the read through an interrupt.
<b>Workaround</b>	If running at atypical I2C speeds, wait at least 1 I2C CLK cycle before reading the ADDRMATCH bit.
<b>I2C_ERR_10</b>	<b>I2C Module</b>
<b>Category</b>	Functional
<b>Function</b>	I2C Busy status is enabled preventing low power entry.
<b>Description</b>	When in I2C Target mode, the I2C Busy Status stays high after a transaction if there is no STOP bit.
<b>Workaround</b>	Program the I2C controller to send the STOP bit and don't send a NACK for the last byte. Any I2C transfer can always be terminated with a STOP condition to provide proper BUSY status and Asynchronous clock request behavior (for low power mode reentry).
<b>PMCU_ERR_13</b>	<b>PMCU Module</b>
<b>Category</b>	Functional
<b>Function</b>	MCU may get stuck while waking up from STOP2 & STANDBY0 at certain scenario
<b>Description</b>	When there is a pending prefetch access before device transitions to STOP2 & STANDBY0. A pending prefetch access such as a timer has just run to completion and DMA has received the event from the GPIO, in that scenario neither DMA transfer

## PMCU\_ERR\_13

(continued)

### **PMCU Module**

---

happens nor timer ISR execution takes place as well as CPU gets stuck. This issue arises when WFI instruction is half word aligned, wait state of device is 2 and there is a pending prefetch access before device transitions to LPM.

#### **Workaround**

Before going to LPM, customer can disable the prefetch and run some dummy instructions (like shutdown register read or any peripheral read) which doesn't access prefetch so that prefetch can get disabled and doesn't cause the device to hang when waking up from LPM as no prefetch access will be pending.

## RST\_ERR\_01

### **RST Module**

---

#### **Category**

Functional

#### **Function**

NRST release doesn't get detected when LFCLK\_IN is LFCLK source and LFCLK\_IN gets disabled

#### **Description**

When LFCLK = LFCLK\_IN and we disable the LFCLK\_IN, then comes a corner scenario where NRST pulse edge detection is missed and the device doesn't come out of reset. This issue is seen if the NRST pulse width is below 608us. NRST pulse above 608us, the reset should appear normally.

#### **Workaround**

Keep the NRST pulse width higher than 608us to avoid this issue.

## RTC\_ERR\_01

### **RTC Module**

---

#### **Category**

Functional

#### **Function**

Some RTC Interrupts are not available in STANDBY1

#### **Description**

When in STANDBY1, the RTCRDY and RTC\_PRESCALER1 interrupts cannot wakeup the device.

#### **Workaround**

When waking up the device from STANDBY1 with the RTC, use other available interrupts such as RTC\_ALARM and RTC\_PRESCALER0.

## SPI\_ERR\_04

### **SPI Module**

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#### **Category**

Functional

#### **Function**

IDLE/BUSY status toggle after each frame receive when SPI peripheral is in only receive mode.

**SPI\_ERR\_04**

(continued)

**SPI Module**

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**Description**

In case of SPI peripheral in only receiving mode, the IDLE interrupt and BUSY status are toggling after each frame receive while SPI is receiving data continuously(SPI\_PHASE=1). Here there is no data loaded into peripheral TXFIFO and TXFIFO is empty.

**Workaround**

Do not use SPI peripheral only receive mode. Set SPI in peripheral simultaneous transmit and receive mode.

**SPI\_ERR\_05****SPI Module**

---

**Category**

Functional

**Function**

SPI Peripheral Receive Timeout interrupt is setting irrespective of RXFIFO data

**Description**

When using the SPI timeout interrupt the RXTIMEOUT can continue decrementing even after the final SPI CLK is received, which can cause a false RXTIMEOUT.

**Workaround**

Disable the RXTIMEOUT after the last packet is received (this can be done in the ISR) and re-enable when SPI communication starts again.

**SPI\_ERR\_06****SPI Module**

---

**Category**

Functional

**Function**

IDLE/BUSY status does not reflect the correct status of SPI IP when debug halt is asserted

**Description**

IDLE/BUSY is independent of halt, it is only gating the RXFIFO/TXFIFO writing/reading strobes. So, if controller is sending data, although it's not latched in FIFO but the BUSY is getting set. The POCI line transmits the previously transmitted data on the line during halt

**Workaround**

Don't use IDLE/BUSY status when SPI IP is halted.

**SPI\_ERR\_07****SPI Module**

---

**Category**

Functional

**Function**

SPI underflow event may not generate if read/write to TXFIFO happen at the same time for SPI peripheral

**Description**

TXFIFO for SPI peripheral uses a bus synchronization scheme. While the control signal from BUSCLK domain to SPICLK domain is getting transferred, if read and write pointer

**SPI\_ERR\_07**  
(continued)

**SPI Module**

---

points to the same head of FIFO, there is a possibility of data coherence issues. This issue only happens in corner case scenarios, and cause no underflow event being generated.

**Workaround**

Customer must ensure that TXFIFO on peripheral can never be empty when Controller is addressing the peripheral.

**SYSOSC\_ERR\_02** **SYSOSC Module**

---

**Category**

Functional

**Function**

MFCLK does not work when Async clock request is received in an LPM where SYSOSC was disabled in FCL mode

**Description**

MFCLK will not start to toggle in below scenario:

1. FCL mode is enabled and then MFCLK is enabled
2. Enter a low power mode where SYSOSC is disabled (SLEEP2/STOP2/STANDBY0/STANDBY1).
3. Async request is received from some peripherals which use MFCLK as functional clock. On receiving async request, SYSOSC gets enabled and ulpclk becomes 32MHz. But MFCLK is gated off and it does not toggle at all as the device is still set to the LPM.

**Workaround**

If SYSOSC is using the FCL mode - Do not enable the MFCLK for a peripheral when you're entering a LPM mode which would typically turn off the SYSOSC.

**TIMER\_ERR\_04**

**TIMG Module**

---

**Category**

Functional

**Function**

TIMER re-enable may be missed if done close to zero event

**Description**

When using a GP TIMER in one shot mode and CLKDIV.RATIO is not 0, TIMER re-enable may be missed if done close to zero event.

**Workaround**

TIMER can be disabled first before re-enabling.

**TIMER\_ERR\_06**

**TIMA and TIMG Module**

---

**Category**

Functional

**Function**

Writing 0 to CLKEN bit does not disable counter

**TIMER\_ERR\_06**

(continued)

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***TIMA and TIMG Module***


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**Description**

Writing 0 to the Counter Clock Control Register(CCLKCTL) Clock Enable bit(CLKEN) does not stop the timer.

**Workaround**

Stop the timer by writing 0 to the Counter Control(CTRCTL) Enable(EN) bit.

**UART\_ERR\_01**


---

***UART Module***


---

**Category**

Functional

**Function**

UART start condition not detected when transitioning to STANDBY1 Mode

**Description**

After servicing an asynchronous fast clock request that was initiated by a UART transmission while the device was in STANDBY1 mode, the device will return to STANDBY1 mode. If another UART transmission begins during the transition back to STANDBY1 mode, the data is not correctly detected and received by the device.

**Workaround**

Use STANDBY0 mode or higher low power mode when expecting repeated UART start conditions.

**UART\_ERR\_02**


---

***UART Module***


---

**Category**

Functional

**Function**

UART End of Transmission interrupt not set when only TXE is enabled

**Description**

UART End Of Transmission (EOT) interrupt does not trigger when the device is set for transmit only (CTL0.TXE = 1, CTL0.RXE = 0). EOT successfully triggers when device is set for transmit and receive (CTL0.TXE = 1, CTL0.RXE = 1)

**Workaround**

Set both CTL0.TXE and CTL0.RXE bits when utilizing the UART end of transmission interrupt. Note that you do not need to assign a pin as UART receive.

**UART\_ERR\_04**


---

***UART Module***


---

**Category**

Functional

**Function**

Incorrect UART data received with the fast clock request is disabled when clock transitions from SYSOSC to LFOSC

**Description**

Scenario:  
 1. LFCLK selected as functional clock for UART  
 2. Baud rate of 9600 configured with 3x oversampling

## UART\_ERR\_04

(continued)

### *UART Module*

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3. UART fast clock request has been disabled  
If the ULPCCLK changes from SYSOSC to LFOSC in the middle of a UART RX transfer, it is observed that one bit is read incorrectly

#### Workaround

Enable UART fast clock request while using UART in LPM modes.

## UART\_ERR\_05

### *UART Module*

---

#### Category

Functional

#### Function

Limitation of debug halt feature in UART module

#### Description

All Tx FIFO elements are sent out before the communication comes to a halt against the expectation of completing the existing frame and halt.

#### Workaround

Please ensure data is not written into the TX FIFO after debug halt is asserted.

## UART\_ERR\_06

### *UART Module*

---

#### Category

Functional

#### Function

Unexpected behavior RTOUT/Busy/Async in UART 9-bit mode

#### Description

UART receive timeout (RTOUT) is not working correctly in multi node scenario, where one UART will act as controller and other UART nodes as peripherals, each peripheral is configured with different address in 9-bit UART mode.

First UART controller communicated with UART peripheral1, by sending peripheral1's address as a first byte and then data, peripheral1 has seen the address match and received the data. Once controller is done with peripheral1, peripheral1 is not setting the RTOUT after the configured timeout period, if controller immediately starts the communication with another UART peripheral (peripheral2) which is configured with different address on the bus. The peripheral1 RTOUT counter is resetting while communication ongoing with peripheral2 and peripheral1 setting its RTOUT only after UART controller is completed the communication with peripheral2.

Similar behavior observed with BUSY and Async request. Busy and Async request is setting even if address does not match while controller communicating with other peripheral on the bus.

#### Workaround

Do not use RTOUT/ BUSY /Async clock request behavior in multi node UART communication where single controller is tied to multiple peripherals.

## UART\_ERR\_07 *UART Module*

---

### Category

Functional

### Function

RTOUT counter not counting as per expectation in IDLE LINE MODE

### Description

In IDLE LINE MODE in UART, RTOUT counter gets stuck at even when the line is IDLE and FIFO has some elements. This means that RTOUT interrupts will not work in IDLE LINE MODE.

In case of an Address Mismatch, RTOUT counter is reloaded when it sees toggles on the Rx line.

In case of a multi-responder scenario this could lead to an indefinite delay in getting an RTOUT event when communication is happening between the commander and some other responder.

### Workaround

Do not enable RTOUT feature when UART module is used either in IDLELINE mode/ multi-node UART application.

## UART\_ERR\_08 *UART Module*

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### Category

Functional

### Function

STAT BUSY does not represent the correct status of UART module

### Description

STAT BUSY is staying high even if UART module is disabled and there is data available in TXFIFO.

### Workaround

Poll TXFIFO status and the CTL0.ENABLE register bit to identify BUSY status.

## 7 Trademarks

All trademarks are the property of their respective owners.

## 8 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

DATE	REVISION	NOTES
February, 2025	A 1.0	The first version before RTM
July, 2025	A 2.0	The second version to include more items before RTM

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